Lower bounds for the two well problem
with surface energy I:
Reduction to finite elements

by

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LOWER BOUNDS FOR THE TWO WELL PROBLEM WITH SURFACE ENERGY I: REDUCTION TO FINITE ELEMENTS

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Abstract. Let Ω be a bounded domain in IR², let H be a 2 × 2 matrix with det (H) = 1. Let ϵ > 0 and consider the functional

I(ϵ) := ∫Ω dist (Du(z), SO(2) ∪ SO(2) H) + ϵ |D²u(z)| dL²z

over the class B_F of Lipschitz functions from Ω satisfying affine boundary condition F. It can be shown by convex integration that there exists F \not∈ SO(2) ∪ SO(2) H and u ∈ B_F with I_0(u) = 0. In this paper we begin the study of the asymptotics of m_ϵ := inf_{B_F ∩ W^{2,1}} I(ϵ) for such F. This is the simplest minimisation problem involving surface energy in which we can hope to see the effects of convex integration solutions. The only known lower bounds are lim inf_ϵ→0 m_ϵ = ∞. In this paper we link the behavior of m_ϵ to the minimum of I_0 over a suitable class of piecewise affine functions. Let \{τ_i\} be a triangulation of Ω by triangles of diameter less than h and let A^h denote the class of continuous functions that are piecewise affine on a triangulation \{τ_i\}. For function u ∈ A^h let \tilde{u} ∈ A^h be the interpolant, i.e. the function we obtain by defining \tilde{u}_{τ_i} to be the affine interpolation of u on the corners of τ_i. We show that if for some small β > 0 there exists u ∈ B_F ∩ C^2 ∩ Bilip with

I(ϵ) ≤ ϵ - β

then for h ≈ ϵ√β the interpolant \tilde{u} ∈ A^h satisfies I_0(\tilde{u}) ≤ h^{1-ε√β}.

Note that it is conjectured that inf_{v ∈ A^h} I_0(v) ≈ h^2 and it is trivial that inf_{v ∈ A^h} I_0(v) ≥ c_0 h so we reduce the problem of non-trivial lower bounds on inf_{v ∈ A^h} I_0 to the problem of non-trivial lower bounds on inf_{v ∈ A^h} I_0. This latter point will be addressed in a forthcoming paper.

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1. Introduction

In the 1980’s from the work of Ball, James [1], [2] and Chipot, Kinderlehrer [5] a now well known model for solid-solid phase transformations arose. In the model, microstructures observed in phase mixtures were explained in terms of energy minimisation of deformations of the material.

Let \( u : \Omega \rightarrow \mathbb{R}^3 \) be a deformation of the material which occupies a reference configuration \( \Omega \), the total free energy of this deformation is given by

\[
I (u) = \int_{\Omega} \phi(Du(x), \theta) \, dL^3 x
\]  

(1)

where \( \phi (\cdot, \theta) \) is the free energy per unit volume in \( \Omega \) at temperature \( \theta \). We fix \( \theta \) and we normalize \( \phi \) such that

\[
\inf_{F} \phi (F, \theta) = 0.
\]

Formation of microstructure was shown to be closely related to the behavior of minimising sequences of \( I \).

Many features of minimising sequences can be understood from the set

\[
\{ F : \phi (F) = 0 \}
\]

which is now known as the energy wells of the functional \( I \).

Certain natural assumptions on the behavior of \( \phi \), in particular frame indifference, imply that \( K \) has to be of the form

\[
K = \{ SO(3) A_i : i = 1, 2, \ldots n \}
\]

(2)

where the \( A_i \) are symmetry related and depend on the action of the phase transition.

Given \( F \in M^{n \times n} \) let \( B_F \) denote the set of functions \( u : \Omega \rightarrow \mathbb{R}^n \) satisfying \( u(x) = F(x) \) for all \( x \in \partial \Omega \). The set of \( F \) for which \( \inf_{u \in B_F} I = 0 \) turns out to agree with the quasiconvex hull \( K^{qc} \) (see [22] for the relevant notions). For any \( F \in \text{int}(K^{qc}) \) it is possible to lower the energy of functional \( I \) with a relatively simple function \( u \in B_F \) that is built up from a simple (finite) layering of regions on which \( Du \) is made to be affine, these functions are known as laminates.

Mathematically speaking, the first real surprise in this theory is the existence of exact minimisers of functional \( I \). Formally; given \( F \in K^{qc} \) there exists a function \( u \in B_F \) such that

\[
Du(x) \in K \text{ for a.e. } x \in \Omega.
\]

(3)

Even though functional \( I \) is not quasiconvex (by the very existence of such exact solutions) and therefor not lower semicontinuous with respect to weak convergence, absolute minimizers exist and can be constructed.

Following the work of Dacorogna and Marcellini [8], Müller and Šverák [18], and later by Sychev [24] and Kirchheim [10] there now exist a wide variety of methods to prove the existence of such solutions.

The approach of Müller, Šverák was to apply the theory of convex integration developed by Gromov [12]; convex integration is a far reaching generalisation of the methods developed by Nash and Kuiper in their work on isometric embeddings.

Dacorogna and Marcellini used Baire category methods that were introduced by Cellina [3] and developed by DeBlasi and Pianigiani in the context of Cauchy problems for ordinary differential inclusions.

The method of Müller, Šverák is in some sense more constructive in that the functions \( u \) satisfying (3) are the limit in the \( W^{1,1} \) norm of a sequence of explicitly constructed functions. These functions are, roughly speaking, “laminate like” in nature. Surprisingly, strong convergence in \( W^{1,1} \) norm is achieved by making the
functions oscillate faster and faster. The limiting function is a wild object. In fact it has been proved that solutions to (3) must be such that $Du \notin BV(\Omega)$, see [7].

So exact minimisers of functional $I$ are only possible due to the fact that $I$ takes no account of the "cost" of oscillations. This is physically unrealistic. Since oscillations in minimisers occur when the derivative of the function jumps from one well, say $SO(3) A_i$, to another well $SO(3) A_j$, the "amount" of oscillation is related to the total "surface area" of the regions in which the derivative of the minimizer lies in specific wells, this is referred to as the surface energy. The bulk energy is the $\int_\Omega \phi(\cdot) \, dL^2 x$ part of the functional.

Functional $I$ was designed to model situations for which the surface energy is small. From the mathematical perspective the simplest adaption of the functional that takes account of surface energy is:

$$I_\epsilon(u) = \int_\Omega \phi(Du(x)) + \epsilon |D^2 u(x)| \, dL^2 x$$

(4)

This functional is minimised over functions $u \in W^{2,1}(\Omega) \cap B_F$.

1.1. The question: The effect of Surface Energy on Microstructure. The question of interest is whether the unexpected existence of exact solutions to inclusion (3) having affine boundary condition has any effect on the scaling of $\inf_{W^{2,1}(\Omega) \cap B_F} I_\epsilon$ as $\epsilon \to 0$. In some sense this could be expected, in words; as $\epsilon \to 0$ surface energy becomes arbitrarily cheap, we can concern ourselves less and less with oscillations and just concentrate on minimizing the bulk part of the functional. It may there for be reasonable to expect that minimisers for sufficiently small $\epsilon$ are something like slightly smoothed out solutions of (3).

This question is important because convex integration solutions are important. Recently, long standing questions as to the regularity of systems of elliptic and parabolic equations have received surprising counter examples via convex integration methods, [20], [21]. Specifically it has been proved there exist nowhere $C^1$ solutions to the Euler Lagrange equations of a strictly quasiconvex functional. This is in contrast to the well known result of Evans [9] that minimisers of strictly quasiconvex functions are $C^{1,\alpha}$ on a dense open, full measure subset of $\Omega$. In [21] a parabolic system that starts from smooth initial data and evolves into a function that is nowhere $C^1$ is exhibited.

Let $K = SO(2) \cup SO(2) H$, $F \in \text{int} K^{qc}$. The differential inclusion

$$Du \in K \text{ a.e.}$$

(5)

for function $u \in B_F$ is the simplest convex integration result. And the minimisation problem

$$\inf_{u \in B_F \cap W^{2,1}} I_\epsilon(u)$$

(6)

is the simplest "physical" situation where we could hope to see the effects of convex integration. The question of asymptotics of $\inf_{B \cap W^{2,1}} I_\epsilon(\cdot)$ is a simple case of the more fundamental question; how much do convex integration solutions oscillate?

The only known lower bounds on (6) are $\inf_{u \in B_F} \frac{I_\epsilon(u)}{\epsilon} \to \infty$ which follows from the result of Dolzmann, Müller [7].

As a consequence of Sverák’s characterization of the wells $K$, [23] (namely that the quasiconvex hull is in the second laminate convex hull) it is easy to see

$$\inf_{u \in B_F \cap W^{2,1}} \frac{I_\epsilon(u)}{\epsilon} < c \epsilon^{-\frac{3}{2}}.$$ 

If convex integration type solutions start having an effect on our functional for sufficiently small $\epsilon$ then we can expect to be able to "beat" the scaling $\epsilon^{-\frac{3}{2}}$. Conversely if it could be shown that $\inf_{A \cap W^{2,1}} \frac{I_\epsilon}{\epsilon} \geq c' \epsilon^{-\frac{3}{2}}$ this would say that convex integration solutions do not affect functional $I$.

Note that the only method by which non-trivial lower bounds on surface energy have previously been obtained for simplified (finite well) versions of functional $I_\epsilon$ is to use the smallness of the bulk energy of function $u$ to show that $u$ must lie close to the affine boundary condition. Since the affine boundary condition is a non-trivial laminate convex combination of matrices in the wells, the only way $u$ can remain close the affine boundary is if the derivative of $u$, going up through region $\Omega$, jumps continuously from one well to another. In this way lower bounds on surface energy can be easily harvested [17],[13].
In our case, by the very existence of convex integration solutions, functions even with zero bulk energy need not behave anything like the affine boundary. Hence it is necessary to somehow use the smallness of surface and bulk energies in combination to control the function.

The main contribution of this paper is to reduce the problem of (non-trivial) lower bounds for \( I \) to the problem of (non-trivial) lower bounds for the finite element approximation of \( I \). In the follow up to this paper [14] we will establish such bounds. Before stating our results we need to introduce the notation and background to explain the scaling of the finite element approximations of \( I \).

2. Background and Notation

We let \( H \) denote a diagonal matrix of the form

\[
H = \begin{pmatrix}
\tilde{\sigma} & 0 \\
0 & \tilde{\sigma}^{-1}
\end{pmatrix}
\]

for some \( \tilde{\sigma} \in (0, 1) \). Let \( \sigma = \min \{ \tilde{\sigma}, 10000^{-1} \} \) and we assume throughout that \( \sigma \) is radically smaller than any small constant that might appear in the proof.

Let \( P(a, \phi_1, \phi_2, r) \) denote the parallelogram centered on \( a \) of side length equal to \( r \) with sides parallel to \( \phi_1 \) and \( \phi_2 \). We will refer to this as a "skewcube".

We let \( \tilde{X}(a, v_1, v_2) \) denote the parallelogram centered on \( a \) with one side parallel to \( v_1 \) of length \( |v_1| \) and the other side parallel to \( v_2 \) of length \( |v_2| \).

We will often be required to consider ODEs of the form

\[
X(0) = x_0 \quad \text{and} \quad \frac{dX}{dt}(t_0) = D\Psi(X(t_0))
\]

where \( \Psi \) is some \( C^2 \) scalar function. Informally when we use the expression "run \( X \) forward in time until it hits .." we consider the set \( \{X(t) : t > 0\} \) and we find the smallest \( t_1 > 0 \) such that \( X(t_1) \) reaches the boundary of some set. The expression "run \( X \) backward in time until it hits .." is defined similarly.

Let

\[
\mathcal{D}(\sigma) := \left\{ M \in M^{2 \times 2} : \sup_{v \in S} |Mv| \leq \frac{1}{\sigma^2} \text{ and } \inf_{v \in S} |Mv| \geq \sigma^2 \right\}
\]

and we let

\[
\mathcal{A}_F(\Omega) = \left\{ u \in C^2(\text{int}(\Omega)) : u(x) = F(x) \text{ for } x \in \partial\Omega \text{ and } Du(x) \in \mathcal{D}(\sigma) \text{ for any } x \in \text{int}(\Omega) \right\}.
\]

We will be considering minimisers of functional \( I \) over this function class. As we will be dealing with the case \( \det (H) = 1 \) a solution to the differential inclusion (5) is given by method of Müller and Šverák ([19]). Their method yields easily the existence of a sequence \( u_k \in \mathcal{A}_F(\Omega) \) such that \( u_k \rightharpoonup u \) in \( W^{1,1}(\Omega) \) for some Lipschitz function \( u \) that solves (5).

In this paper we will have to deal with many constants, all of them in one way or the other dependent on the eigenvalues of \( H \). We adopt the following convention: constants that carry through the whole proof from lemma to lemma will be denoted \( c_1, c_2, \ldots \). Inside each lemma the "local" constant will be denoted \( \tilde{c}_1, \tilde{c}_2, \ldots \). In each lemma "we start the clock back" and begin by numbering our local constants from \( c_1 \). We also make the convention that \( c_1 \leq \tilde{c}_2 \leq \tilde{c}_3 \cdot \ldots \).

2.1. Finite Element Approximations. As is standard in finite element approximations, we will say a triangulation (denoted \( \Delta_\varepsilon \)) of \( \Omega \) of size \( \varepsilon \) is a collection of pairwise disjoint triangles \( \{\tau_i\} \) all of diameter \( \varepsilon \) such that

\[
\Omega \subset \bigcup_{\tau_i \in \Delta_\varepsilon} \tau_i.
\]

Given a function \( u \), we can approximate \( u \) uniformly by a function \( \tilde{u} \) that is piecewise affine on the triangles of \( \Delta_\varepsilon \) by letting \( \tilde{u}_{|\tau_i} \) be the affine map we obtain from interpolating \( u \) on the corners of \( \tau_i \). We will call \( \tilde{u} \) the F.E. approximation of \( u \). When we replace the function class of a minimisation problem with respect to functional \( J \), with a the class of F.E. approximations to the functions in the function class, this is known as the finite element approximation to \( J \).
Finite element approximations of functionals such as $I$ have received much interest, for example see [15],[17],[4]. In this paper our interest in these approximations comes mainly from the fact that they provide a convenient intermediary step for the study of surface energy problems: Given a triangulation for which the edges of the triangles are not parallel to the rank-1 connections of the wells $K$, every time the F.E. approximation to a function jumps from one well to another, there must be at least one triangle which is nowhere near the wells. More informally; if for example we have an F.E. approximation to a laminate, every triangle that cuts through an interface between the regions where the derivative of the laminate takes different wells will be such that the affine map we get from interpolating the laminate on the corners of the triangle will have its linear part some distance from the wells.

In this way, F.E. approximations reflect a competition between “surface energy” as given by the error contributed from jumps in the derivative, and bulk energy which in the case of “laminate like” F.E. approximations is basically the width of the interpolation layer.

F.E. approximations of a three well functional $\bar{I}$ of the form $I$, over a function class having affine boundary condition in the second laminate convex hull of the wells have been studied by Chipot [4] and the author [13]. If $\Delta_h$ denotes a triangulation of size $h$ and $A^h_F$ denotes the set of functions that are piecewise affine on $\Delta_h$ satisfying the affine boundary condition $F$. Chipot showed $\inf_{u \in A^h_F} I(u) \leq Ch^2$, and the lower bound of $\inf_{u \in A^h_F} \bar{I}(u) \geq ch^{3\over 2}$ was provided by the author. From Šverák’s characterization [23] we even know the exact arrangement of rank-1 connections between the wells $SO(2) \cup SO(2) H$ and a matrix in the interior of the quasiconvex hull. The finite well functional studied in [13] precisely mimics these rank-1 connections. We feel confident in conjecturing:

**Conjecture 1.** Let $K := SO(2) \cup SO(2) H$, $H = \left( \begin{smallmatrix} \sigma & 0 \\ 0 & \sigma^{-1} \end{smallmatrix} \right)$. Let $\Delta_h$ be a triangulation of $\Omega$ of size $h$ with the edges of the triangles not in the set of rank-1 direction of $K$.

Let $A^h_F$ denote the set of function with affine boundary condition $F$ that are piecewise affine on the triangulation $\Delta_h$. Let $d(\cdot, B)$ denote the Euclidean distance away from set $B$. Let $I(u) := \int_{\Omega} d(Du(x), K) dL^2 x$ then we have

$$\inf_{u \in A^h_F} I(u) \geq ch^{3\over 2}$$

The contribution of this paper that is most recognizably relevant to the asymptotics of $\inf_{u \in A^F} \frac{L(u)}{\epsilon}$ is to reduce the proof of lower bounds of the form $\inf_{u \in A^F} \frac{L(u)}{\epsilon} \geq \epsilon^{-\beta}$ (for sufficiently small $\beta$) to lower bounds of the form $\inf_{u \in A^h_F} I(u) \geq h^{1-\epsilon\sqrt{\epsilon}}$ for $h \approx \epsilon^{1\over \sqrt{\epsilon}}$.

3. **Statement of Results**

**Theorem 1.** Given region $\Omega$ and triangulation $\Delta_\epsilon$ with triangulation size $\epsilon$. Let $m_1 \geq 2048$. Let $v \in A^F(\Omega)$. If we have for some small $\epsilon$

$$\int_{\Omega} d(Dv(x), SO(2) \cup SO(2) H) dL^2 x \leq \epsilon^{m_1}$$

and

$$\int_{\Omega} |D^2v(x)| dL^2 x \leq \epsilon^{4m_1\over m_1 + 8}$$

then the F.E. approximation $\tilde{v}_\epsilon$ of $v$ on $\Delta_\epsilon$ satisfies

$$I(\tilde{v}_\epsilon) \leq \epsilon^{1 - 4m_1 \over m_1 + 8}.$$ 

This Theorem is basically a consequence of the following Theorem.

**Theorem 2.** Given region $\Omega$ and triangulation $\Delta_\epsilon$ with triangulation size $\epsilon$. Let $m_0 \geq 2048$. Let $v \in A^F(\Omega)$ and let skewcube $S := P(a, \phi_1, \phi_2, \epsilon)$ be such that $N_{\epsilon \sigma}(S) \subset \Omega$. If for some small $\kappa > 0$ we have

$$\int_{S} d(Dv(x), SO(2) \cup SO(2) H) dL^2 x \leq \kappa^{m_0 \over m_0 + 8} \epsilon^{2}$$

then either
\[ \int_S \left| D^2 v (x) \right| dL^2 x \geq \epsilon_0 c \]

or given triangle \( \tau_i \in \Delta_c \) containing \( a \), if \( L_i \) denotes the linear part of the affine map obtain from interpolating \( v \) on the corners of \( \tau_i \) then

\[ d (L_i, SO (2) \cup SO (2) H) < \kappa \frac{m_1}{8192} \]

Theorem 1 has as an easy corollary

**Corollary 1.** Given region \( \Omega \) and triangulation \( \Delta_h \) with triangulation size \( h \). Let \( m_1 \geq 2048 \). If \( v \in A_F (\Omega) \) is such that

\[ \frac{I_\epsilon (v)}{\epsilon} \leq \epsilon \frac{2048}{m_1^2} \]

then for \( h := \epsilon \frac{\sqrt{m_1 - 2048}}{m_1^2} \), the F.E. approximation \( \tilde{v}_h \) of \( v \) on \( \Delta_h \) satisfies

\[ I (\tilde{v}_h) \leq h^{1 - \frac{4092}{m_1}} \]

The bulk of this paper will be devoted to proving Theorem 2.

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4. Plan of Proof

The proof is long, but essentially made up of only four basic ideas. We explain them in chronological order (which is not the order they appear in the proof) because this still seems the best way to explain how the proof builds up.

4.1. The pull back idea. To begin with note that there are two linearly independent vectors \( \phi_1 \) and \( \phi_2 \) such that \( |H\phi_i| = 1 \) for \( i = 1, 2 \). See for example Fig. 14. Every unit vector between \( \phi_1 \) and \( \phi_2 \) (denoted by \( \Xi_2 \)) will be mapped by \( H \) to a vector of size strictly less than 1. Similarly every vector between \(-\phi_1 \) and \(-\phi_2 \) (denoted by \( \Xi_1 \)) will by shrunk by \( H \). For this reason \( \Xi_1 \cup \Xi_2 \) will be called the shrink directions.

Now the most basic example of a function satisfying the affine boundary condition that minimizes bulk energy is a laminate. In the reference configuration this can be seen as a function defined on a collection of strips running parallel to either \( \phi_1 \) or \( \phi_2 \) for which the derivative of the laminate alternates from one strip to the next from being in \( SO (2) \) to being in \( SO (2) H \). For simplicity, let us suppose for the time being the strips are parallel to \( \phi_1 \) and let us denote the laminate by \( u \). Now if all our strips are of width \( w \), by Fubini and the fact that \( \det (H) = 1 \) and \( |H\phi_1| = 1 \) we know that the images of our strips under the action of \( u \) will be to send them to strips of width \( w \), as shown Fig. 1.

![Figure 1](image_url)

Now if we want a path that travels through the strips in the image in the quickest way possible (i.e. a path that goes from one strip to the next with the minimum length possible) then clearly such a path would traverse at right angles to the strips in the image, as shown in Fig. 1. Let \( P \) denote this path. Now we consider the pull back of \( P \) in the image. Let \( t(z) \) denote the tangent to the path \( u^{-1}(P) \) at point \( z \), so we have the following formula:

\[
H^1 (P) = \int_{u^{-1}(P)} |Du(x) t(x)| dH^1 x.
\]

Let \( Q \) denote a subsegment of the path that is given by the path intersected with one strip in the image (denoted \( S \), see Fig. 1) for which \( Du|_{u^{-1}(S)} \in SO (2) \). Now \( H^1 (Q) = w \) and as \( u^{-1}(Q) \) connects the edges of \( u^{-1}(S) \), so \( H^1 (u^{-1}(Q)) \geq w \). Since \( Du|_{u^{-1}(S)} \in SO (2) \) we have

\[
w = H^1 (Q) = \int_{u^{-1}(Q)} |Du(x) t(x)| dH^1 x = H^1 (u^{-1}(Q)).
\]

Thus \( u^{-1}(Q) \) must be a straight line going through \( S \) perpendicular to \( \phi_1 \). Now let \( R \) denote the subsegment of the path given by the path intersected with a strip in the image (denoted by \( T \)) for which the \( Du|_{u^{-1}(T)} \in SO (2) H \). It should be obvious that \( u^{-1}(R) \) is not going to be a line perpendicular to \( \phi_1 \), since if our laminate pulled back two linearly independent straight lines to straight lines it would be affine. On the other hand, by the same argument as for \( Q \), if \( u^{-1}(R) \) isn’t perpendicular to \( \phi_1 \) and so \( H^1 (u^{-1}(R)) > w \), then (by the fact that \( u \) is a laminate and so \( u^{-1}(R) \) is a straight line) all the points \( x \in u^{-1}(R) \) must be such that \( t(x) \in \Xi_1 \), i.e. \( t(x) \) must be in the shrink directions. We examine the situation more closely, see Fig. 2.

Now \( u^{-1}(Q) \) needs to connect the edges of \( u^{-1}(T) \) (which are of course distance \( w \) apart) whilst keeping the integral \( \int_{u^{-1}(Q)} |Du(x) t(x)| dH^1 x \) small. As can be seen from Fig. 14, the vector that shrinks most under the action of \( H \) is right in the middle of \(-\phi_1, -\phi_2 \). We denote this vector by \( \psi_0 \)
Let $W$ be the straight line connecting the edges of $u^{-1}(T)$, which minimizes $\int_W |Ht(x)| \, dH^1 x$. In deciding the angle of $W$ there is a compromise between having $W$ close to parallel with $\psi_0$ and trying to keep the length of $W$ not too much bigger than $w$. Its an exercise to calculate the optimal direction, we will denote it $\phi_1$.

Now $u^{-1}(Q)$ connects the edges of $u^{-1}(T)$ and $w = H^1(Q) = \int_{w^{-1}(Q)} |Ht(x)| \, dH^1 x$. So since $w$ minimizes we must have that $\int_W |Ht(x)| \, dH^1 x \leq w$. If the inequality was strictly less, then as $u(W)$ connects the edges of $T$, so we would have

$$w > \int_W |Ht(x)| \, dH^1 x = H^1(u(W)) \geq w,$$

contradiction. So $u^{-1}(Q)$ is the minimiser and hence $u^{-1}(Q)$ must be parallel to $\phi_1$.

So we know exactly what the pull back of $p$ looks like; in strips in the reference with derivative in $SO(2)$ it is forms a line perpendicular to $\phi_1$. And in strips in the reference with derivative in $SO(2)H$ it is forms a line parallel to $\phi_1$. As shown on Fig. 1.

Now we wish to apply what we have learned to a general function $v : \Omega \to \mathbb{R}^2$ with small bulk energy (i.e. $\int_\Omega d(Dv(x) : SO(2) \cup SO(2)H) \, dL^2 x < \epsilon L^2(\Omega)$). We take lines through the reference going in direction $\phi_1$ going through $\Omega$ and consider their image under $v$, as shown in Fig. 3.
Suppose for two lines $l_1, l_2$ we have that $v(l_1), v(l_2)$ are distance less than $w$ apart at some point, as shown. Let $l$ be the line of length less than $w$ joining $v(l_1)$ to $v(l_2)$. We consider the pull back $v^{-1}(l)$. Let $n_1$ denote the anticlockwise normal to $\phi_1$. Now as we have an $L^1$ bound we know that most of the points $x \in v^{-1}(l)$ are close to the wells, if $x \in v^{-1}(l)$ such that $Du(x) \in N_{\sqrt{\nu}}(SO(2))$ it doesn’t matter which direction the tangent $t(x)$ is in. On the other hand for those $x \in v^{-1}(l)$ such that $Dv(x) \in N_{\sqrt{\nu}}(SO(2)H)$ the worst thing that can happen is that $t(x) = \phi_1$. But even in this case (as we know from the example we studied) $l$ will “fill up” according to how far in direction $n_1$ path $v^{-1}(l)$ travels. So we have

$$H^1(l) = \int_{v^{-1}(l)} |Dv(x) t(x)| dH^1 x \geq (1 - \sqrt{\nu}) L^1 P_{\phi_1}^{-1}(v^{-1}(l)) = (1 - \sqrt{\nu}) w.$$ 

So this implies the images of lines $l_1$ and $l_2$ must be (by at least $(1 - \sqrt{\nu}) w$ “pushed over” from one another. This is our first restriction on the geometry of the function we want to study, just coming from smallness of bulk energy.

4.2. ODE method. We consider the same picture as before but from a different perspective. So $l_1, l_2, \ldots$ are lines in direction $\phi_1$ going through $\Omega$ and we consider the images $v(l_1), v(l_2), \ldots$. Now supposing we were on a point $x \in v(l_1)$ and we wanted to get to $v(l_2)$ via a path of the shortest length.

The most natural way to do it would be to consider the vector field given by the derivative of the function $\Psi_1 : v(\Omega) \to \mathbb{R}^2$ defined by $\Psi_1(x) := v^{-1}(x) \cdot n_1$. If we “follow” the vector field from point $x$ it will indeed take us along the optimal path to $v(l_2)$. But “following” a vector field is exactly finding an integral curve for a vector field, which means solving the following ODE

$$X(0) = x \quad \frac{dX}{dt}(t_1) = D\Psi_1(X(t_1)).$$

Now if point $y \in \{X(t) : t > 0\}$ is such that $Dv(v^{-1}(y)) \in N_{\sqrt{\nu}}(SO(2) \cup SO(2)H)$ we calculate that $D\Psi_1(y) = Dv^{-T}(v^{-1}(y)) \cdot n_1$. Letting $R(v^{-1}(y)) S(v^{-1}(y)) := Dv(v^{-1}(y))$ be the polar decomposition of $Dv(v^{-1}(y))$ (i.e. $R(v^{-1}(y)) \in SO(2)$ and $S(v^{-1}(y)) \in M_{\text{sym}}$) we have $Dv^{-T}(y) n_1 = R(v^{-1}(y)) S^{-1}(v^{-1}(y)) n_1$ and as $S(v^{-1}(y)) \in N_{\sqrt{\nu}}(\{Id, H\})$ so either $S(v^{-1}(y)) \in N_{\sqrt{\nu}}(Id)$ and so $|S(v^{-1}(y)) n_1| \approx 1$ or $S(v^{-1}(y)) \in N_{\sqrt{\nu}}(H)$ and so $|S(v^{-1}(y)) n_1| \approx |H^{-1} n_1| = 1$ (see Fig. 14). So assuming the path of the vector field is such that $Dv$ stays close to the wells, if $\Lambda$ is a connected subset of the set $\{X(t) : t > 0\}$ with end points $e \in v(l_2), s \in v(l_1)$ and with the property $\int_\Lambda d\left(Dv(v^{-1}(x)) : SO(2) \cup SO(2)H\right) dH^1 x < \epsilon H^1(\Lambda)$ then

$$|\Psi_1(e) - \Psi_1(s)| = |(v^{-1}(e) - v^{-1}(s)) \cdot n_1| \approx H^1(\Lambda).$$

The precise statement of this is given by Lemma 3. So on Fig. 4, if $v^{-1}(s) \in l_1$ and $v^{-1}(e) \in l_2$ then $H^1(\Lambda) \approx w$, however if $\Lambda$ is a wavy line, then $|e - s| \approx H^1(\Lambda)$ and so we have $e \in v(l_2)$ is distance less than $w$ away from $s \in v(l_1)$. This contradicts the “pull back” idea. And so $\Lambda$ must form a nearly straight line.
4.3. The Coarea Alternative. From the “pull back idea” and the “ODE method” it seems we are able to gain quite a lot of control of our function $v$ just by using bulk energy. The catch is that whilst it is not hard (by Fubini and the Area Formula) to find lines in the image for which $Dv \left( v^{-1}(\cdot) \right)$ stays close to the wells, it is much harder to find integral curves to the vector field $D\Psi_1$ with this property. We require a kind of curvilinear version of Fubini and this of course is nothing other than the Coarea formula.

To invoke the Coarea formula we need to define a function $\Theta_1 : v(\Omega) \to \mathbb{R}$ such that the level sets $\Theta_1^{-1}(t)$ form integral curves of $D\Psi_1$. By smoothness of $u$ and hence of $D\Psi_1$ and so by uniqueness of ODE solutions, it is easy to see that such a function exists. Let $a$ be the center of $\Omega$, in its crudest possible manifestation we define $\Theta_1$ in the following way: For any $x \in v(\Omega)$ we run the ODE that forms the integral curve of $D\Psi_1$ containing $x$ until we reach $v((a + \langle \phi_1 \rangle) \cap \Omega)$ (for easy reasons the integral curve must intersect this 1-set at only one point) we define $p(x)$ to be the point of $v((a + \langle \phi_1 \rangle) \cap \Omega)$ that we reach, then we define $\Theta_1(x) := v^{-1}(p(x)) \cdot \phi_1$.

Let $J(x) := d(Dv(v^{-1}(x)), SO(2) \cup SO(2)H)$, the coarea formula tells us

$$\int_\Omega J(x)|D\Theta_1(x)|dL^2x = \int_{\mathbb{R}} \int_{\Theta_1^{-1}(t)} J(x)dH^1xdL^1t.$$ 

So assuming the expression on the left hand side is small we are guaranteed the existence of many integral curves with small bulk energy. However by the existence of an abundance of functions with arbitrarily small bulk energy that are nothing like close to being affine, smallness of $\int_\Omega J(x)|D\Theta_1(x)|dL^2x$ is obvious a non-trivial issue. It is here that we finally have to use the information we have about the surface energy of $v$.

If $\int_{v(\Omega)} J(x)|D\Theta_1(x)|dL^2x$ is large, then we must (by an application of the coarea formula with respect to the lines $v((z + \langle \phi_1 \rangle) \cap \Omega)$ using $|D\Psi_1|$ as the Jacobian) be able to find a point $z \in \Omega$ such that $\int_{v((z + \langle \phi_1 \rangle) \cap \Omega)} J(x)dH^1x$ is very small but

$$\int_{v((z + \langle \phi_1 \rangle) \cap \Omega)} J(x)|D\Theta_1(x)|dL^2x \text{ is big.} \quad (7)$$

So there must exist a set $B \subset v((z + \langle \phi_1 \rangle) \cap \Omega)$ of quite small $H^1$ measure such that $\int_B |D\Theta_1(x)|dH^1x$ is big. Now considering the pull back of the integral curves into the reference configuration gives us Figure 5.

![Figure 5](image-url)

We arrive at this diagram in the following way: Firstly it’s an exercise to see that lines of the form $v((\phi_1) + z)$ form integral curves to $D\Theta_1$. So we can find a collection of intervals $[a_k, b_k] \subset (\langle \phi_1 \rangle + z)$ such that

$$\int_{\bigcup_k v([a_k, b_k])} |D\Theta_1(x)|dH^1x = \sum_{k \in \mathbb{N}} \Theta_1(b_k) - \Theta_1(a_k) \text{ is big.}$$

On the other hand by definition of $\Theta_1$ this means the integral curves running from the endpoints of each interval $[a_k, b_k]$ must be splayed out as is shown. We let $c_k$ denote the point in $a + \langle \phi_1 \rangle$ reached from $a_k$ by
the pullback of the integral curve that goes through \( v(a_k) \) and let \( d_k \) be the point in \( a + \langle \phi_1 \rangle \) reached from \( b_k \) by the pullback of the integral curve that goes through \( v(b_k) \), as shown on Fig. 5.

Recall by polar decomposition of the derivative: \( Dv(x) =: R(x) S(x) \) we have \( R(x) \in SO(2) \), \( S(x) \in M^{\text{sym}} \). Its a calculation to see that if \( t(x) \) denotes the tangent to pull back of the integral curve at \( x \), then

\[
t(x) := S^{-1}(x) S^{-1}(x) n_1.
\] (8)

Now we know from the fundamental theorem of calculus that the integral of the difference of the tangents to the pull backs of the integral curves starting at \( a_k, b_k \) must be bigger than \( \frac{|c_k - d_k|}{2} \). From (8) the difference in tangents from one curve to the next is a lower bound for the difference in \( Dv \) between these two curves, so we have an inequality of the following form.

\[
\int_{\Omega} |D^2v(x)| \, dL^2 x \geq \sum_k \frac{|c_k - d_k|}{2} \approx \frac{1}{2} \int_B |D\Theta_1(x)| \, dH^1 x \approx c_0 \int_{v(\{z + \langle \phi_1 \rangle \})} J(x) |D\Theta_1(x)| \, dH^1 x.
\]

So we have the “Coarea alternative” either

\[
\int_{\Omega} |D^2v(x)| \, dL^2 x \text{ is not small}
\]

or

\[
\int_{v(\Omega)} J(x) |D\Theta_1(x)| \, dL^2 x \text{ is small}
\]

and we can find many integral curves with small bulk energy. The most basic form of the coarea alternative is given by Lemma 10.

4.4. Finite element reduction. If we have region \( \Pi \) such that \( \int_{v(\Pi)} J(x) |D\Theta_1(x)| \, dL^2 x \) is small for \( i = 1, 2 \), by the pull back idea and the ODE method we know that we can find many integral curves of the form \( \Theta_1^{-1}(t) \) and \( \Theta_2^{-1}(t) \) (where \( \Theta_i \) denotes the level set function for \( \Psi_i \)) which form approximate straight lines. We know from our analysis of the laminate example in section 4.1, exactly what the pull back of straight lines look like. Since \( Dv \) stays close to the wells along our integral curves \( \Theta_i^{-1}(t) \), by the same arguments we end up being able to show that the pull back of \( \Theta_1^{-1}(t) \) and \( \Theta_2^{-1}(t) \) have very much the same form. Informally; our control of the integral curves \( \{\Theta_i^{-1}(t) : t \in R\} \) says that our function \( v \) has to be something like a laminate with strips parallel to \( \phi_1 \). And our control of integral curves \( \{\Theta_2^{-1}(t) : t \in R\} \) says that \( v \) has to be something like a laminate with strips parallel to \( \phi_2 \). The only way \( v \) can be both these things is if \( Du_{\mid H} \approx R_1 H \) for some \( R_1 \in SO(2) \) or \( Du_{\mid H} \approx R_2 \) for some \( R_2 \in SO(2) \).

So the natural idea is to cut \( \Omega \) into triangular subregions (i.e. take a triangulation of \( \Omega \)) of roughly fixed size. Denote these regions as \( \{\tau_i\} \). For each \( \tau_i \), by the “coarea alternative” and what we have shown, either

\[
\int_{\tau_i} |D^2v(x)| \, dL^2 x \text{ is not small}
\]

or

\[
Du_{\mid \tau_i} \approx R \mathbb{S}
\]

for some \( R \in SO(2) \) and some \( \mathbb{S} \in \{Id, H\} \). So if we let \( \tilde{v} \) be the function we obtain by interpolating \( v \) on the corners of each \( \tau_i \) (i.e. for each \( \tau_i \) the affine function we obtain from interpolating \( v \) on the corners of \( \tau_i \) is given by \( \tilde{v}_{\mid \tau_i} \)), then we can expect \( I(\tilde{v}) \) to be quite small, assuming the bulk and surfaces energies of \( v \) are small enough.

This is how we reduce the problem to the problem of lower bounds for the finite element approximation of \( I \).

In truth, the “coarea alternative” we apply to each \( \tau_i \) is considerably more subtle than the argument described here, but the basic ideas are the same. When needed we will preface the proof of the more intricate lemmas with a preproof to indicate how the argument goes.
5. Preliminary Lemmas

5.1. The vector field $D\Psi_i$.

5.1.1. Traveling in Cones.

Here we set up one of the basic lemmas about integral curves to the vector field $D\Psi_i$. Quite simply this lemma says that when we pull back with $v^{-1}$ one such integral curve, the resulting curve will be a Lipschitz graph over the line $\phi_i^+$. More informally, the pull back of the integral curve will always travel in cones. The proof is just a calculation.

Lemma 1. Let $v \in A_F(\Omega)$. Let $\phi_1, \phi_2 \in S^1$ be the rank-1 directions of $H$, let $n_i \in S^1$ be the counterclockwise normal to $\phi_i$ for $i = 1, 2$. Let

$$X^+(x, v, \alpha) := \{z \in \mathbb{R}^2 : |(z-x) \cdot v^+| \leq \alpha (z-x) \cdot v, \ (z-x) \cdot v > 0 \},$$

be the standard one sided cone. For $i \in \{1, 2\}$ given function $v \in A_F(\Omega)$ we can define a function $\Psi_i : v(\Omega) \to \mathbb{R}$ in the following way:

$$\Psi_i(x) = v^{-1}(x) \cdot n_i.$$

By smoothness of $v$ the vector field

$$D\Psi_i : v(\Omega) \to \mathbb{R}^2$$

is smooth. For any $x_0 \in \mathbb{R}^2$ if we solve the ODE

$$\frac{dX}{dt}(t) = D\Psi_i(X(t)),
X(0) = x_0,$$

then the path $X$ has the property

$$v^{-1}(X(t)) \in X^+ \left(v^{-1}(x_0), n_i, \frac{1}{\sigma^6}\right) \forall t \in \mathbb{R}_+ \cap \{t : X(t) \in v(\Omega)\}$$

and

$$v^{-1}(X(t)) \in X^+ \left(v^{-1}(x_0), -n_i, \frac{1}{\sigma^6}\right) \forall t \in \mathbb{R}_- \cap \{t : X(t) \in v(\Omega)\}$$

Proof. Let $i \in \{1, 2\}$ and let

$$\Psi_i(x) = v^{-1}(x) \cdot n_i.$$

Given $x_0 \in \mathbb{R}^2$ and let $X : \mathbb{R}_+ \to \mathbb{R}^2$ be a solution of the ODE; $X(0) = x_0$,

$$\frac{dX}{dt}(t_0) = D\Psi_i(X(t_0)).$$

Let $z_0 = X(t_0)$ for some $t_0 > 0$, so

$$\frac{dX}{dt}(t_0) = D\Psi_i(z_0)$$

and note

$$D\Psi_i(z_0) = D \left(v^{-1}(z_0) \cdot n_i\right) = Dv^{-T} \left(v^{-1}(z_0)\right) n_i.$$  \hspace{1cm} (9)

Since $\det(Dv(x)) > \sigma^2$ for every $x \in \mathbb{R}^2$, we have the following decomposition;

$$Dv(x) = R(x) S(x)$$  \hspace{1cm} (10)

for some $R(x) \in SO(2)$ and some positive definite symmetric matrix $S(x)$. So

$$Dv^{-T} \left(v^{-1}(z_0)\right) = R \left(v^{-1}(z_0)\right) S^{-1} \left(v^{-1}(z_0)\right).$$  \hspace{1cm} (11)

Hence

$$\frac{dX}{dt}(t_0) = R \left(v^{-1}(X(t_0))\right) S^{-1} \left(v^{-1}(X(t_0))\right) n_i.$$  \hspace{1cm} (12)

Let $Y : \mathbb{R}_+ \to \mathbb{R}^2$ be the path defined by

$$Y(t) := v^{-1}(X(t)),$$
and so we have

\[ v_{t_0} = \frac{dY}{dt}(t_0) = Dv^{-1}(X(t_0)) \frac{dX}{dt}(t_0), \quad (13) \]

and as \( Dv^{-1}(X(t_0)) = (Dv(v^{-1}(X(t_0))))^{-1} \) putting (10), (12) and (13) together

\[ [Dv(Y(t_0))] v_{t_0} \stackrel{(10)}{=} [R(Y(t_0)) S(Y(t_0))] v_{t_0} \stackrel{(13)}{=} \frac{dX}{dt}(t_0) \stackrel{(12)}{=} [R(Y(t_0)) S^{-1}(Y(t_0))] n_i. \]

This gives;

\[ v_{t_0} = \left[ S^{-1}(Y(t_0)) S^{-1}(Y(t_0)) \right] n_i. \quad (14) \]

Now its easy to see that \( S^{-1}(\cdot) S^{-1}(\cdot) \) is symmetric. If we let \( \lambda_2 > 0 \) and \( \lambda_2 > 0 \) denote the eigenvalues of \( S^{-1} \) then the eigenvalues \( S^{-1}(\cdot) S^{-1}(\cdot) \) will be \( \lambda^2_2 > 0 \) and \( \lambda^2_2 > 0 \) and in particular there exits a unitary matrix \( U \) such that \( U^T S^{-1}(\cdot) S^{-1}(\cdot) U = D \) where \( D \) is a diagonal matrix with entries \( \lambda^2_2 \) and \( \lambda^2_2 \). So for any \( m = \left( \begin{smallmatrix} m_1 \\ m_2 \end{smallmatrix} \right) \in S^1 \), letting \( \tilde{m} = U^T m \) we have

\[ m \cdot S^{-1}(\cdot) S^{-1}(\cdot) m = \tilde{m} \cdot D \tilde{m} = \lambda^2_1 m_1^2 + \lambda^2_2 m_2^2 > \sigma^2 \]

and so we have

\[ \frac{dY}{dt}(t_0) \cdot n_i \geq \sigma^2. \quad (15) \]

Now from (13) and (14) we have

\[ \left| \frac{dY}{dt}(t_0) \right|^2 = \left| (S^{-1}(Y(t_0)) S^{-1}(Y(t_0))) \cdot n_i \right|^2 \leq \frac{1}{\sigma^4}. \quad (16) \]

Note from (15), (16) we have

\[ Y(t) \in X^+ \left( v^{-1}(x_0), n_i, \frac{1}{\sigma^2} \right) \quad (17) \]

for all \( t > 0 \).

In exactly the same way, if we solve the ode \( X(0) = x_0 \) and

\[ \frac{dX}{dt}(t_0) = -D\Psi_i(X(t_0)) \]

we can show that if \( Y(t_0) = v^{-1}(X(t_0)) \) then

\[ Y(t) \in X^+ \left( v^{-1}(x_0), -n_i, \frac{1}{\sigma^2} \right), \quad (18) \]

and this completes the proof.

5.1.2. The level set function.

As noted in the introduction (section 4.3), we will need to integrate up our integral curves with with the coarea formula. To do this we require a function whose level sets form the integral curves. Here such a function is defined and its basic properties are proved.

Lemma 2. Let \( v \in A^F(\Omega) \) and let \( S = P(a, \phi_1, \phi_2, \epsilon) \) be such that \( N^\omega(\theta)(\cdot) \subset \Omega \). Let \( i \in \{1, 2\} \) and let \( \Psi_i(x) := v^{-1}(x) \cdot n_i \).

Take \( q \in S \). We define \( \Upsilon_q := (q + \phi_1) \cap \Omega \). We can define function

\[ \Theta_i^q : v(S) \to \mathbb{R} \]

such that for any \( x_0 \in v(S) \), the path defined by the ODE

\[ \begin{align*}
X(0) &= x_0 \\
\frac{dX}{dt}(t) &= D\Psi_i(X(t))
\end{align*} \quad (19) \]
is such that there exists a unique \( t_0 \in \mathbb{R} \) for which
\[
X(t_0) = v(T_q^i),
\]
\[
\{ X(t) : t \in \mathbb{R} \} = \Theta_q^i \Gamma(X(t_0)).
\]
and
\[
\sup_{x \in v(S)} |\Theta_q^i(x)| < \frac{2e}{\sigma^2}.
\] (20)

Proof. To start, we note that for any \( x_0 \in v(S) \) by smoothness of \( v \) on \( \Omega^0 \) we can uniquely solve the ode
\[
X(0) = x_0
\]
\[
\frac{dX}{dt}(t) = D\Psi(X(t)).
\] (21)

Let \( s(x_0) \) be the first point of \( \partial v(\Omega) \) to be hit by the path \( X \) going backwards in time from \( x_0 \). And let \( e(x_0) \) be the first point of \( \partial v(\Omega) \) to be hit by the path \( X \) going forwards in time from \( x_0 \). Let \( \pi_1 \in \mathbb{R} \) be the unique number such that \( X(\pi_1) = s(x_0) \) and let \( \pi_2 \in \mathbb{R} \) be the unique number such that \( X(\pi_2) = e(x_0) \). By definition; for any \( t \in [\pi_1, \pi_2] \) we have \( v(t) \in v(\Omega) \). Let \( \mathcal{I}(t_0) := \{ X(t) : t \in [\pi_1, \pi_2] \} \). Let \( T(x_0) := [\pi_1, \pi_2] \).

Now \( \mathcal{I}(x_0) \) is the continuous image of a connected interval, so is connected.

By Lemma 1 we know
\[
\{ v^{-1}(X(t)) : t \in \mathbb{R} \cap T(x_0) \} \subset X^+\left(v^{-1}(x_0), n, \frac{1}{\sigma^6}\right)
\]
\[
\{ v^{-1}(X(t)) : t \in \mathbb{R} \cap T(x_0) \} \subset X^+\left(v^{-1}(x_0), -n, \frac{1}{\sigma^6}\right). \]

So from (22) we have that for any \( x \in P_{(n^+)}(v^{-1}(\mathcal{I}(x_0))) \) we have \( P_{(n^+)}^{-1}(x) \cap v^{-1}(\mathcal{I}(x_0)) \) consists of one point.

So since \( P_{(n^+)}(v^{-1}(\mathcal{I}(x_0))) \) is a connected set, if \( v^{-1}(\mathcal{I}(x_0)) \cap T_q^i = \emptyset \) it can only be because path \( X \) has run out of region \( v(\Omega) \) before crossing \( v(T_q^i) \). However since any point \( x_0 \in S \) is at least distance \( \frac{7}{\sigma^6} \) away from \( \partial \Omega \) by (22) this can not happen. So the exists a unique point \( t_0 \in \mathbb{R} \) such that \( X(t_0) \in v(T_q^i) \).

Now we define \( \Theta_q^i : v(S) \to \mathbb{R} \) as follows; For any \( x_0 \in v(S) \) let \( X \) be the solution of
\[
X(0) = v(x_0)
\]
\[
\frac{dX}{dt}(t) = D\Psi(X(t)).
\]

Let \( t(x_0) \in \mathbb{R} \) be the unique real number such that \( v^{-1}(X(t(x_0))) \cap T_q^i \neq \emptyset \). We define
\[
\Theta_q^i(x_0) := v^{-1}(X(t(x_0))) \cdot \phi_1,
\]
by uniqueness of \( t(x_0), \Theta_q^i(x_0) \) is well defined and its clear that \( \Theta_q^i\Gamma(X(t_0)) = \{ X(t) : t \in \mathbb{R} \} \).
5.1.3. Integrating along integral curves.

As mentioned in the introduction, section 4.2, one of the main observations in this proof is that for integral curves for which the derivative $Dv\left(v^{-1}\left(\cdot\right)\right)$ stays close to the wells, we have that $|D\Psi_i\left(\cdot\right)| \approx 1$. So for a subsegment $U$ of such an integral curve of $D\Psi_i$ with end points $s$ and $e$, the $H^1\left(U\right)$ is approximately $|\Psi_i\left(e\right) - \Psi_i\left(s\right)|$.

This is the contents of the statement of Lemma 3, the proof is just a calculation.

**Lemma 3.** Let $v \in \mathcal{A}_F\left(\Omega\right)$. Let $S := P\left(\alpha, \phi_1, \phi_2, \epsilon\right) \subset \Omega$ and let $i \in \{1, 2\}$. Suppose we have for some $t_0 \in \mathbb{R}$ we have a connected subset $U \subset \Theta_n^{-1}\left(t_0\right) \cap v\left(S\right)$ such that

$$\int_U J\left(x\right) dH^1x \leq \alpha H^1\left(U\right).$$

(23)

If we let $s, e$ be the endpoints of $U$ then we have

$$\left(1 - \frac{c_1\alpha}{\sigma^4}\right) |\Psi_i\left(e\right) - \Psi_i\left(s\right)| \leq H^1\left(U\right) \leq \left(1 + \frac{c_1\alpha}{\sigma^4}\right) |\Psi_i\left(e\right) - \Psi_i\left(s\right)|.$$

**Proof.** For each $x \in U$ since $K$ is compact we can find $P\left(x\right) \in K$ such that

$$d\left(Dv\left(v^{-1}\left(x\right)\right) \cdot K\right) = |Dv\left(v^{-1}\left(x\right)\right) - P\left(x\right)|.$$

Let $E\left(x\right) = Dv\left(v^{-1}\left(x\right)\right) - P\left(x\right)$.

Let $B = \{x \in U : d\left(Dv\left(v^{-1}\left(x\right)\right) \cdot SO\left(2\right)\right) < d\left(Dv\left(v^{-1}\left(x\right)\right) \cdot SO\left(2\right) H\right)\}$ this is a closed set and since we have (23) we know

$$H^1\left(B\right) < c_1\alpha H^1\left(U\right).$$

(24)

Let

$$R = \{x \in U : d\left(Dv\left(v^{-1}\left(x\right)\right) \cdot SO\left(2\right)\right) < d\left(Dv\left(v^{-1}\left(x\right)\right) \cdot SO\left(2\right) H\right)\}.$$

And let

$$S = \{x \in U : d\left(Dv\left(v^{-1}\left(x\right)\right) \cdot SO\left(2\right) H\right) < d\left(Dv\left(v^{-1}\left(x\right)\right) \cdot SO\left(2\right)\right)\}.$$ 

Now $S$ and $R$ are open in $\Theta_n^{-1}\left(q\right)$ and so

$$R = \cup_n K_n \quad \text{and} \quad S = \cup_n I_n$$

where $I_n$ and $K_n$ are open connected sets in $U$.

Let $s_n$ be the starting point of segment $I_n$ (the point coming from the right) and let $e_n$ be the endpoint. For each $x \in I_n$ let $t_x \in S^1$ denote the tangent to the curve $I_n$ at point $x$. We will show

$$\int_{I_n} D\Psi_i\left(x\right) t_x - \frac{3 E\left(x\right)}{\sigma^4} dH^1x < H^1\left(I_n\right) < \int_{I_n} D\Psi_i\left(x\right) t_x + \frac{3 E\left(x\right)}{\sigma^4} dH^1x.$$ 

(25)

To begin with note

$$\int_{I_n} D\Psi_i\left(x\right) t_x dH^1x = \Psi_i\left(e_n\right) - \Psi_i\left(s_n\right).$$

Recall,

$$R\left(\cdot\right) S\left(\cdot\right) = Dv\left(\cdot\right)$$

(26)

is the polar decomposition of of $Dv\left(\cdot\right)$.

We have already calculated that $D\Psi_i\left(x\right) = R\left(v^{-1}\left(x\right)\right) S^{-1}\left(v^{-1}\left(x\right)\right) n_i$. We let $X : \mathbb{R} \to \mathbb{R}^2$ be a solution of

$$X\left(0\right) = s_n$$

$$\frac{dX}{dt}\left(t\right) = D\Psi_i\left(X\left(t\right)\right).$$

(27)

Let $Y\left(s\right) = v^{-1}\left(X\left(s\right)\right)$. We also have calculated that

$$\frac{dY}{dt}\left(s\right) = S^{-1}\left(Y\left(s\right)\right) S^{-1}\left(Y\left(s\right)\right) n_i,$$

(28)

for $s > 0$. Let $x_0 \in I_n$ and let $s_0 > 0$ be such that $X\left(s_0\right) = x_0$. So as $v\left(Y\left(s_0\right)\right) = X\left(s_0\right)$ we have

$$\frac{dX}{dt}\left(s_0\right) = Dv\left(Y\left(s_0\right)\right) \frac{dY}{dt}\left(s_0\right),$$

(29)
and as $Dv(Y(s_0)) = R(Y(s_0)) S(Y(s_0))$ so by (26), (28) and (29) we have

$$D\Psi_i(x_0) = \frac{dX}{dt}(s_0)$$

$$= (28),(29)$$

$$= R(Y(s_0)) S(Y(s_0)) S^{-1}(Y(s_0)) S^{-1}(Y(s_0)) n_i$$

$$= R(Y(s_0)) S^{-1}(Y(s_0)) n_i. \quad (30)$$

So to estimate the length of $D\Psi_i(x_0)$ we need only know $S^{-1}(Y(s_0)) n_i$ however as we know $Dv(Y(s_0)) = P(Y(s_0)) + E(Y(s_0))$ for some $P(Y(s_0)) \in SO(2)$ $H$ we have

$$S(Y(s_0))^2 = Dv(Y(s_0))^T Dv(Y(s_0))$$

$$= (P(Y(s_0)) + E(Y(s_0)))^T (P(Y(s_0)) + E(Y(s_0)))$$

$$= P(Y(s_0))^T + E(Y(s_0))^T P(Y(s_0)) + E(Y(s_0))^T P(Y(s_0))^T$$

$$+ E(Y(s_0)) E(Y(s_0))^T, \quad (31)$$

and recall $P(Y(s_0)) = RH$ for some $R \in SO(2)$ and so $P(Y(s_0))^T P(Y(s_0)) = H^T R^T RH = H^T H$. So $S(Y(s_0))^2 \in N_{\frac{\lambda_i(g(s))}{\sigma^2}}(H^2)$ and so

$$S^{-1}(Y(s_0)) \in N_{\frac{\lambda_i(g(s))}{\sigma^2}}(H^{-1}). \quad (32)$$

And we claim for $i = 1, 2$;

$$|H^{-1} n_i| = 1. \quad (33)$$

First we have to calculate $\phi_1, \phi_2$ and subsequently $n_1, n_2$. So we require

$$\begin{vmatrix} \left( \frac{\tilde{\sigma}}{0} \right) \left( \begin{array}{c} a \\ b \end{array} \right) \right] = (\tilde{\sigma} a)^2 + \left( \frac{b}{\tilde{\sigma}} \right)^2 = 1,$$

for vector

$$\begin{vmatrix} \left( \begin{array}{c} a \\ b \end{array} \right) \right] = 1.$$

To simplify expression we let $\lambda = \frac{1}{\tilde{\sigma}}$.

So $a^2 = 1 - b^2$ and inserting this into the first equation we have

$$\tilde{\sigma}^2 (1 - b^2) + \lambda^2 b^2 = \tilde{\sigma}^2 + (\lambda^2 - \tilde{\sigma}^2) b^2 = 1.$$

Hence

$$b^2 = \frac{1 - \tilde{\sigma}^2}{\lambda^2 - \tilde{\sigma}^2};$$

$$a^2 = 1 - b^2 = \frac{(\lambda^2 - \tilde{\sigma}^2) - (1 - \tilde{\sigma}^2)}{\lambda^2 - \tilde{\sigma}^2} = \frac{\lambda^2 - 1}{\lambda^2 - \tilde{\sigma}^2}.$$

Thus

$$\phi_1 = \left( \begin{array}{c} \sqrt{\frac{\lambda^2 - 1}{\lambda^2 - \tilde{\sigma}^2}} \\ \frac{\tilde{\sigma}}{\lambda^2 - \tilde{\sigma}^2} \end{array} \right) \quad \phi_2 = \left( \begin{array}{c} \sqrt{\frac{\lambda^2 - 1}{\lambda^2 - \tilde{\sigma}^2}} \\ -\frac{\Omega}{\lambda^2 - \tilde{\sigma}^2} \end{array} \right). \quad (34)$$

And hence

$$n_1 = \left( \begin{array}{c} -\frac{\tilde{\sigma}}{\lambda^2 - \tilde{\sigma}^2} \end{array} \right) \quad n_2 = \left( \begin{array}{c} \frac{\tilde{\sigma}}{\lambda^2 - \tilde{\sigma}^2} \end{array} \right). \quad (35)$$
Thus

\[
|H^{-1}n_i| = \left| \begin{pmatrix} \lambda & 0 \\ 0 & \tilde{\sigma} \end{pmatrix} \begin{pmatrix} \pm \sqrt{\frac{1 - \tilde{\sigma}^2}{\lambda^2 - \tilde{\sigma}^2}} \\ \tilde{\sigma} \sqrt{\frac{\lambda^2 - 1}{\lambda^2 - \tilde{\sigma}^2}} \end{pmatrix} \right| \\
= \left| \begin{pmatrix} \pm \lambda \sqrt{\frac{1 - \tilde{\sigma}^2}{\lambda^2 - \tilde{\sigma}^2}} \\ \tilde{\sigma} \sqrt{\frac{\lambda^2 - 1}{\lambda^2 - \tilde{\sigma}^2}} \end{pmatrix} \right| \\
= \lambda^2 \frac{(1 - \tilde{\sigma}^2)}{(\lambda^2 - \tilde{\sigma}^2)} + \tilde{\sigma}^2 \frac{(\lambda^2 - 1)}{(\lambda^2 - \tilde{\sigma}^2)} \\
= \frac{\lambda^2 - \tilde{\sigma}^2}{\lambda^2 - \tilde{\sigma}^2} \\
= 1.
\] (36)

So we have proved (33).

Thus from (32), (30) and (33) we have that

\[
|D\Psi_i (x_0)| \leq \left( 1 - \frac{3|E(x)|}{\sigma^4}, 1 + \frac{3|E(x)|}{\sigma^4} \right). \tag{37}
\]

Let

\[
\beta (x_0) := |D\Psi_i (x_0)| = \left| \frac{dX}{dt} (s_0) \right|. \tag{38}
\]

Now as \(X\) is a solution of (27) we have

\[
t_{x_0} = \frac{dX}{dt} (s_0) = \frac{D\Psi_i (x_0)}{\beta (x_0)}. \tag{39}
\]

and so from (39)

\[
D\Psi_i (x_0) \cdot t_{x_0} = \beta (x_0) t_{x_0} \cdot t_{x_0} = \beta (x_0).
\]

And so from (37) and (38)

\[
\int_{I_n} D\Psi_i (x) t_x dH^1 x \in \left( H^1 (I_n) - \int_{I_n} \frac{3|E(x)|}{\sigma^4} dH^1 x, H^1 (I_n) + \int_{I_n} \frac{3|E(x)|}{\sigma^4} dH^1 x \right)
\]

which implies (25).

Now we argue a similar inequality for the \(\{K_n\}\). So let \(e_n, s_n\) be endpoints of segment \(K_n\). From (31) we see that \(S (v^{-1} (x)) \in N \frac{|E(x)|}{\sigma^4} (I)\) for any \(x \in K_n\) so again we have

\[
\int_{K_n} D\Psi_i (x) t_x - \frac{3|E(x)|}{\sigma^4} dH^1 x \leq H^1 (K_n) \leq \int_{K_n} D\Psi_i (x) t_x + \frac{3|E(x)|}{\sigma^4} dH^1 x. \tag{40}
\]

Now from (25) we have

\[
\sum_n \int_{I_n} D\Psi_i (x) t_x - \frac{3|E(x)|}{\sigma^4} dH^1 x \leq \sum_n H^1 (I_n) \leq \sum_n \int_{I_n} D\Psi_i (x) t_x + \frac{3|E(x)|}{\sigma^4} dH^1 x
\]

and from (40) we have

\[
\sum_n \int_{K_n} D\Psi_i (x) t_x - \frac{3|E(x)|}{\sigma^4} dH^1 x \leq \sum_n H^1 (K_n) \leq \sum_n \int_{K_n} D\Psi_i (x) t_x + \frac{3|E(x)|}{\sigma^4} dH^1 x.
\] (42)
Since for any subsegment $I \subset U$ where $I$ has endpoint $a$ and $b$ we have

$$
\int_I D\psi_i(x) t_a dH^1 x = \psi_i(b) - \psi_i(a) = P(\phi^+_{\psi_i}) (v^{-1}(I)).
$$

Let $\varpi = \int_{\partial U - \omega_\psi \cap v(S)} \frac{3|E(x)|}{\sigma^2} dH^1 x$, note that by assumption we know $\varpi < \frac{2\alpha}{\sigma^2} H^1(U)$. Putting together (41) and (42) we have that

$$
\sum_n L^1 \left( P(\phi^+_{\psi_i}) (v^{-1}(K_n) \cup v^{-1}(I_n)) \right) - \varpi \leq \sum_n H^1(K_n) + H^1(I_n)
$$

$$
\leq \sum_n L^1 \left( P(\phi^+_{\psi_i}) (v^{-1}(K_n) \cup v^{-1}(I_n)) \right) + \varpi. \quad (43)
$$

Since we know from (24)

$$
H^1 \left( U \setminus \left( \bigcup_n (K_n \cup I_n) \right) \right) \leq c_1 \alpha H^1(U)
$$

so

$$
H^1 \left( v^{-1} \left( U \setminus \left( \bigcup_n (K_n \cup I_n) \right) \right) \right) \leq \frac{c_1 \alpha H^1(U)}{\sigma^2} \quad (44)
$$

and thus we have from (43) and (44)

$$
H^1(U) \leq \left( \sum_n H^1(K_n) + H^1(I_n) \right) + c_1 \alpha H^1(U)
$$

$$
\leq \sum_n L^1 \left( P(\phi^+_{\psi_i}) (v^{-1}(K_n) \cup v^{-1}(I_n)) \right) + \varpi + c_1 \alpha H^1(U)
$$

$$
\leq L^1 \left( P(\phi^+_{\psi_i}) (v^{-1}(U)) \right) + \left( \frac{3}{\sigma^4} + \frac{2c_1}{\sigma^2} \right) \alpha H^1(U). \quad (45)
$$

and similarly

$$
L^1 \left( P(\phi^+_{\psi_i}) (v^{-1}(U)) \right) - \left( \frac{3}{\sigma^4} + \frac{2c_1}{\sigma^2} \right) \alpha H^1(U) \leq \sum_n H^1(K_n) + H^1(I_n)
$$

$$
\leq H^1(U)
$$

and this establishes our claim.

\[\square\]

5.2. The pullback idea.

This next lemma is a formalization of what has been described in section 4.1 of introduction as the pull back idea. Essentially what it means is that for a function $v$ of small bulk energy, lines of the form $v((\phi_1) + z_1)$, $v((\phi_1) + z_2)$ are pushed over from one another. A better explanation can be obtained from section 4.1 of the introduction.

**Lemma 4.** Given function $v \in A_{\psi}(\Omega)$. Let $S = P(a, \phi_1, \phi_2, \epsilon)$ be such that $S \subset \Omega$. Let $i \in \{1, 2\}$. For any $b, e \in v(S)$, let $\eta := [b, e]$ if we have

$$
\int_{\eta} J(z) dH^1 z < \alpha |b - e|
$$

then

$$
|e - b| > (1 - 2\sigma^{-2} \sqrt{\alpha}) |\Psi_i(e) - \Psi_i(b)|.
$$
Proof. Now letting \( t_x \in S^1 \) denote the tangent to the curve \( v^{-1}(\eta) \) at point \( x \).

\[
\int_{\eta} J(z) \, dH^1 z = \int_{v^{-1}(\eta)} |Dv(x) t_x| \, J(v(x)) \, dH^1 x \geq \sigma^2 \int_{v^{-1}(\eta)} J(v(x)) \, dH^1 x,
\]

so we have

\[
\sigma^{-2} \alpha |b - e| \geq \int_{v^{-1}(\eta)} J(v(x)) \, dH^1 x.
\]

Now \( v^{-1}(\eta) \) connects \( v^{-1}(b) \) to \( v^{-1}(e) \). Let

\[
T = \{ x \in v^{-1}(\eta) : J(v(x)) < \sqrt{\alpha} \},
\]

so we know that

\[
H^1 \left( v^{-1}(\eta) \setminus T \right) \leq \sigma^{-2} \sqrt{\alpha |b - e|}.
\] (46)

Now \( T \) is the countable union of connected segments \( I_n \subset v^{-1}(\eta) \). Now let \( a_n, b_n \) be the end points of the segment \( I_n \). For \( i \in \{1, 2\} \) we will show

\[
|v(a_n) - v(b_n)| \geq L^1 \left( P_{\phi_i^0} (I_n) \right) - \sqrt{\alpha} H^1 (I_n).
\] (47)

Now recall we calculated \( n_1 \) at (35) (where \( \lambda := \tilde{\sigma}^{-1} \))

\[
n_1 = \left( -\sqrt{\frac{1 - \tilde{\sigma}^2}{\tilde{\sigma}^2}}, \sqrt{\frac{1 - \tilde{\sigma}^2}{\tilde{\sigma}^2}} \right) = \left( -\frac{\tilde{\sigma}}{\sqrt{1 + \tilde{\sigma}^2}}, \frac{\tilde{\sigma}}{\sqrt{1 + \tilde{\sigma}^2}} \right), \quad n_2 = \left( \frac{\tilde{\sigma}}{\sqrt{1 + \tilde{\sigma}^2}}, \frac{\tilde{\sigma}}{\sqrt{1 + \tilde{\sigma}^2}} \right)
\]

now as a first step to proving equation (47) we will prove the following: We firstly we define the \textit{shrink directions}. Let \( \Xi_2 \) be the subset of vectors of \( S^1 \) between \( \phi_1 \) and \( \phi_2 \) and let \( \Xi_1 \) be the subset of vectors of \( S^1 \) between \( -\phi_1 \) and \( -\phi_2 \). It’s easy to see that for any \( v \in S^1 \), \( |Hv| \leq 1 \Leftrightarrow v \in \Xi_1 \cup \Xi_2 \) hence the name \textit{shrink directions}.

\textbf{Claim} Let \( i \in \{1, 2\} \). We will show that there exists vector \( \hat{\phi}_i \in \Xi_i \) such that for any \( \psi \in \Xi_i \)

\[
|H\psi| \geq \psi \cdot n_i + \frac{\epsilon_2 (\text{ang} (\psi, \hat{\phi}_i))^2}{4}.
\] (48)

First we consider the inequality

\[
|H\psi| \geq \psi \cdot n_2 + \frac{\epsilon_2 (\text{ang} (\psi, \hat{\phi}_2))^2}{4}.
\] (49)

Let

\[
\psi = \left( \frac{\cos a}{\sin a} \right),
\]

so equation (49) is equivalent to

\[
\sqrt{\tilde{\sigma}^2 \cos^2 a + \frac{\sin^2 a}{\tilde{\sigma}^2}} \geq \frac{\tilde{\sigma} \cos a}{\sqrt{\sigma^2 + 1}} + \frac{\sin a}{\sqrt{\sigma^2 + 1}} + \frac{\epsilon_2 (\text{ang} (\psi, \hat{\phi}_2))^2}{4},
\]

and we will prove (51) in due course. Firstly we will show why inequality (48) for \( i = 1 \) follows from inequality (49). Give \( \psi \in S^1 \) of the form (50) we define

\[
\tilde{\psi} = \left( -\frac{\cos a}{\sin a} \right).
\]

When we calculate \( \hat{\phi}_1 \) and \( \hat{\phi}_2 \) it will turn out that \( \tilde{\phi}_1 = \hat{\phi}_2 \), see (247) in the Appendix.
Hence (see fig 6) if we have (49) then

\[ |\hat{H}\phi| = |\hat{H}\phi| \geq \phi \cdot n_2 + \frac{c_2}{4} (\text{ang}(\hat{\phi}, \hat{\phi}_2))^2 \]

so all that remains is to establish (49) which as we noted is equivalent to (51).

The proof of inequality (51) is quite involved, partly due to the fact its sharp. Let

\[ p = \sqrt{4\sigma^6 + (1 - \sigma^6)^2} = (1 + \sigma^6) \]

so

\[ f(a) := \sigma^2 \cos^2 a + \frac{\sin^2 a}{\sigma^2} = \sigma^2 - 2\sigma \cos a \sin a \]

now using standard trigonometric identities we have

\[ \sigma^2 (\sigma^2 + 1) f(a) = \sigma^6 (1 + \cos 2a) + \frac{1 - \cos 2a}{2} - \sigma^3 \sin 2a \]

\[ 2\sigma^2 (\sigma^2 + 1) f(a) = (\sigma^6 - 1) \cos 2a - 2\sigma^3 \sin 2a + \sigma^6 + 1. \]

Now

\[ 2\sigma^2 (\sigma^2 + 1) f'(a) = -2 (\sigma^6 - 1) \sin 2a - 4\sigma^3 \cos 2a \]

So

\[ f'(\tilde{a}) = 0 \iff -2 \sin 2\tilde{a} (\sigma^6 - 1) - 4\sigma^3 \cos 2\tilde{a} = 0 \]

\[ \iff -2 \sin 2\tilde{a} (\sigma^6 - 1) = 4\sigma^3 \cos 2\tilde{a} \]

\[ \iff \tan 2\tilde{a} = \frac{2\sigma^3}{(1 - \sigma^6)}. \]

Now as \( \tilde{a} \) is chosen from an interval of length less than \( \pi \), there is only one \( \tilde{a} \) for which (53) is true. Let

\[ \hat{\phi}_2 := \left( \frac{\cos \tilde{a}}{\sin \tilde{a}} \right). \]

(54)

Let

\[ p = \sqrt{4\sigma^6 + (1 - \sigma^6)^2} = (1 + \sigma^6), \]

so

\[ \sin 2\tilde{a} = \frac{2\sigma^3}{p} \text{ and } \cos 2\tilde{a} = \left( \frac{1 - \sigma^6}{p} \right). \]

Now

\[ 2\sigma (\sigma^2 + 1) f(\tilde{a}) = (\sigma^6 - 1) \cos 2\tilde{a} - 2\sigma^3 \sin 2\tilde{a} + \sigma^6 + 1 \]

\[ = -\frac{p(\sigma^6 - 1)^2}{p} - \frac{4\sigma^6}{p} + \sigma^6 + 1 \]

\[ = -\frac{(4\sigma^6 + (\sigma^6 - 1)^2)}{p} + \sigma^6 + 1 \]

\[ = -\sigma^6 + 1 + \sigma^6 + 1 \]

\[ = 0. \]

Now note

\[ 2\sigma^2 (\sigma^2 + 1) f''(a) = -4 (\sigma^6 - 1) \cos 2a + 8\sigma^2 \sin 2a. \]

Before continuing we need to estimate the length of \( \Xi_x \). Observe fig 6.
Now we will use this together with (55) to get a lower bound on \( f \) point \( p \). Thus we have the estimate we want;

\[
p_0 := \phi_1 + \lambda_0 \begin{pmatrix} \sqrt{\frac{1 - \sigma^2}{\sigma^2 - 1}} \\ \sqrt{\frac{1 - \sigma^2}{\sigma^2 - 1}} \end{pmatrix}
\]

where \( \lambda_0 > 0 \) is some number such that

\[
e_2 \cdot \phi_1 + \lambda_0 \begin{pmatrix} \sqrt{\frac{1 - \sigma^2}{\sigma^2 - 1}} \\ \sqrt{\frac{1 - \sigma^2}{\sigma^2 - 1}} \end{pmatrix} = 0. \tag{56}
\]

Now by (34), (56) is equivalent to

\[
\sqrt{\frac{1 - \sigma^2}{\sigma^2 - 1}} = \lambda_0 \sqrt{\frac{\sigma - 2 - 1}{\sigma^2 - 1}} \Leftrightarrow \lambda_0 = \sqrt{\frac{1 - \sigma^2}{\sigma^2 - 1}} = \sigma.
\]

So

\[
|\phi_1 - p_0| = \lambda_0 \begin{pmatrix} \sqrt{\frac{1 - \sigma^2}{\sigma^2 - 1}} \\ -\sqrt{\frac{1 - \sigma^2}{\sigma^2 - 1}} \end{pmatrix} = \sigma.
\]

Thus we have the estimate we want;

\[
H^1(\Xi_2) = H^1(\Xi_1) \leq 2\sigma.
\]

Now we will use this together with (55) to get a lower bound on \( f'' \) for those \( a \geq \) such that \( \left( \frac{\cos a}{\sin a} \right) \in \Xi_2 \):

Since \( a \in [0, \sigma] \subset [0, 1) \) so from (55)

\[
2\sigma^2 (\sigma^2 + 1) f''(a) \geq \min \left\{ 4 \left( 1 - \sigma^6 \right), 8\sigma^2 \right\} \left( \cos 2a + \sin 2a \right)
\]

\[
\geq \min \left\{ 4 \left( 1 - \sigma^6 \right), 8\sigma^2 \right\} \left( \cos 2a + \sin 2a \right)
\]

\[
> \frac{\min \left\{ 4 \left( 1 - \sigma^6 \right), 8\sigma^2 \right\}}{4}.
\]

And so

\[
f''(a) \geq \frac{\min \left\{ 4 \left( 1 - \sigma^6 \right), 8\sigma^2 \right\}}{8\sigma^2 (\sigma^2 + 1)}. \tag{57}
\]
Now note that for \( a < 0 \) such that \( \left( \frac{\cos a}{\sin a} \right) \in \Xi_2 \), since \(|a| < \tilde{a} < 1\) we know that \( \cos a > 0 \) and \( \sin a < 0 \) so we have that

\[
\sqrt{\left( \tilde{a}^2 \cos^2 a + \frac{\sin^2 a}{\tilde{a}^2} \right) - \tilde{a} \cos a - \frac{\sin a}{\tilde{a}^{2} + 1}} > \tilde{a} \cos a - \frac{\tilde{a} \cos a}{\sqrt{\tilde{a}^2 + 1}} - \frac{\sin a}{\sqrt{\tilde{a}^2 + 1}}
\]

\[
= \tilde{a} \left( \sqrt{1 - \frac{1}{\tilde{a}^2 + 1}} \right) \cos a + \frac{|\sin a|}{\sqrt{\tilde{a}^2 + 1}}
\]

\[
> \min \left\{ \tilde{a} \left( 1 - \frac{1}{\tilde{a}^2 + 1} \right), \frac{1}{\sqrt{\tilde{a}^2 + 1}}, \frac{|\cos a| + |\sin a|}{\sqrt{\tilde{a}^2 + 1}} \right\}
\]

From (57) and (58) we let

\[
\sigma_2 := \min \left\{ \frac{1}{32 \tilde{a}^2 (\tilde{a}^2 + 1)} \frac{1}{16 \tilde{a}^2 (\tilde{a}^2 + 1)} \right\}
\]

and we define \( t(x) := 8 \sigma_2 (x - \tilde{a}) \). We have

- \( f' (\tilde{a}) = t (\tilde{a}) = 0 \).
- By (57), for all \( a \in [0, \tilde{a}] \) we have \( f'' (a) - t' (a) \geq 0 \) and hence for any \( a \in [\max \{ \tilde{a}, \tilde{a} \}, 0] \) we have \( f' (a) - t (a) \geq 0 \) and for any \( a \in [0, \max \{ \tilde{a}, 0 \}] \) we have \( f' (a) - t (a) \leq 0 \).

So for any \( a \in [0, \tilde{a}] \) we have

\[
\int_\tilde{a}^a f' (x) - t (x) \, dL^1 x = f (a) - 8 \sigma_2 (a - \tilde{a})^2 \geq 0
\]

which is equivalent to

\[
\tilde{a}^2 \cos^2 a + \frac{\sin^2 a}{\tilde{a}^2} \geq \tilde{a}^2 \cos^2 a + \sin^2 a + \frac{2 \tilde{a} \cos a \sin a}{\tilde{a}^2 + 1} + 8 \sigma_2 (a - \tilde{a})^2
\]

(59).

Now in order to understand (59) note that

\[
\left( \tilde{a} \cos a + \frac{\sin a}{\sqrt{\tilde{a}^2 + 1}} \right)^2 + 8 \sigma_2 (a - \tilde{a})^2 \leq \frac{1}{(\tilde{a}^2 + 1)} + \tilde{a}^2 < 2
\]

if we let \( g (x) := \sqrt{x} \), we note that \( g' \) is greater than \( \frac{1}{\sqrt{\tilde{a}^2 + 1}} \) on the interval \([0, 2]\) and so by considering the integral of \( g' \) between \( \frac{\tilde{a} \cos a + \sin a}{\sqrt{\tilde{a}^2 + 1}} \) and \( \frac{\tilde{a} \cos a + \sin a}{\sqrt{\tilde{a}^2 + 1}} \) + 8 \sigma_2 (a - \tilde{a})^2.

We get

\[
\sqrt{\left( \frac{\tilde{a} \cos a + \sin a}{\sqrt{\tilde{a}^2 + 1}} \right)^2 + 8 \sigma_2 (a - \tilde{a})^2} - \left( \frac{\tilde{a} \cos a + \sin a}{\sqrt{\tilde{a}^2 + 1}} \right) \geq \frac{8 \sigma_2}{\sqrt{2}} (a - \tilde{a})^2.
\]

So putting this together with (59)

\[
\sqrt{\tilde{a}^2 \cos^2 a + \frac{\sin^2 a}{\tilde{a}^2}} \geq \frac{\tilde{a} \cos a + \sin a}{\sqrt{\tilde{a}^2 + 1}} + \frac{8 \sigma_2}{\sqrt{2}} (a - \tilde{a})^2
\]

and this establishes the claim for \( a \in [0, \tilde{a}] \).

Now we need to deal with the case \( a \in [-\tilde{a}, 0] \). Since \( \tilde{a} \in (0, 1) \) from (58) we have

\[
\sqrt{\tilde{a}^2 \cos^2 a + \frac{\sin^2 a}{\tilde{a}^2}} - \frac{\tilde{a} \cos a}{\sqrt{\tilde{a}^2 + 1}} - \frac{\sin a}{\sqrt{\tilde{a}^2 + 1}} \geq \frac{8 \sigma_2}{\sqrt{2}} (a - \tilde{a})^2,
\]

as \( (\ang (\psi, \hat{\sigma}_2))^2 \leq 10 (a - \tilde{a})^2 \) this completes the proof of (51).
So for each \( x \in I_n \) we know that for some \( G(x) \in SO(2) \cup SO(2)H \) and some \( E(x) \in M^{2 \times 2} \) with \( \|E(x)\| < \sqrt{\alpha} \) we have
\[
Dv(x) = G(x) + E(x).
\]
Now from (48)
\[
\|Dv(x)\| \psi > |(G(x) + E(x))\| \psi
\geq |G(x)\| \psi - |E(x)\| \psi
\geq \psi \cdot n_i - \sqrt{\alpha}.
\]
So
\[
H^1(v(I_n)) = \int_{I_n} |Dv(x) \cdot t_x| dH^1 x
\geq \int_{I_n} t_x \cdot n_i - \sqrt{\alpha} dH^1 x
= (a_n - b_n) \cdot n_i - \sqrt{\alpha} H^1(I_n).
\]
Now \((a_n - b_n) \cdot n_i = L^1(P_{\phi^+}I_n)\) and as \( v(I_n) \) is a straight line, so \( H^1(v(I_n)) = |v(a_n) - v(b_n)| \) and thus we have established inequality (47). Now by the fact that the line segments connecting \( v(a_n) \) and \( v(b_n) \) are subsets of \( \eta \) and by using (47) we have,
\[
|e - b| = H^1(\eta)
\geq \sum_{k=1}^{\infty} |v(a_n) - v(b_n)|
\geq \left( \sum_{k=1}^{\infty} L^1(P_{\phi^+}I_n) \right) - \sqrt{\alpha} \left( \sum_{k=1}^{\infty} H^1(I_n) \right).
\]
Now from (46)
\[
L^1(P_{\phi^+} v^{-1}(\eta) \setminus (\cup_n I_n)) < \bar{\sigma}^2 \sqrt{\alpha} |b - e|,
\]
and thus
\[
L^1(P_{\phi^+} (\cup_n I_n)) > L^1(P_{\phi^+} v^{-1}(\eta)) - \bar{\sigma}^2 \sqrt{\alpha} |b - e|.
\]
So inserting this into equation (60) we have
\[
|e - b| = L^1(P_{\phi^+} (v^{-1}(\eta))) - \bar{\sigma}^2 \sqrt{\alpha} |b - e| - \sqrt{\alpha} H^1(v^{-1}(\eta))
\geq |\Psi_1(e) - \Psi_1(s)| - 2\bar{\sigma}^2 \sqrt{\alpha} |b - e|.
\]
\[
□
\]
5.2.1. Forcing integral curves into straight lines.
This coming lemma is elementary. If we have the conditions to invoke both Lemma 3 and Lemma 4 then (as indicated in section 4.2 of the introduction) we get sufficiently strict bounds from above on the length of the curves and bounds from below on the distance between the end points that we are able to force the integral curves to run in straight lines.

Lemma 5. Let \( v \in A_F(\Omega) \).

Given skew rectangular region \( R = \mathcal{F}(a, w\phi_2, r\phi_1) \) where \( \frac{w}{r} < \sigma^2 \). We assume \( N_{\mathcal{F}(R)} \subset \Omega \).

Define \( \Theta^0 : R \to \mathbb{R} \) as in Lemma 2.

Suppose for some \( t \in (a + (\phi_1)) \cap R \) we have
\[
\int_{\Theta^0_{\phi_1}^{-1}(t)} J(x) dH^1 x \leq \alpha w
\]
(61)
then let $s$ be the first point of $\Theta_i^{a-1}(t)$ (going backwards in time) to hit $\partial R$ and $e$ be the first point (going forwards) to hit $\partial R$. Let $U$ denote the connected component of $\Theta_i^{a-1}(t)$ between $s$ and $e$, then firstly by Lemma 3

$$
\left(1 - \frac{c_1\alpha}{\sigma^4}\right) |\Psi_i(e) - \Psi_i(s)| \leq H^1(U) \leq \left(1 + \frac{c_1\alpha}{\sigma^4}\right) |\Psi_i(e) - \Psi_i(s)|.
$$

If in addition we have

$$
\int_{N\sqrt{w}(R)} T(x) \, dL^2x \leq \alpha^3 w^2
$$

then

$$
\Theta_i^{a-1}(t) \cap R \in N_{c\sqrt{w}}(l_t)
$$

for $l_t := t + l$, $l \in G(1, 2)$.

Proof. So $U$ is the connected component of $\Theta_i^{a-1}(t_0) \cap v(S)$ between $s$ and $e$. We will show $U$ has to lie very close to $[s, e]$.

Let $w_0 := \sup \{ |P(e-s)\perp(e-z)| : z \in U \}$ and let $\varpi \in U$ be the point such that

$$
|P(e-s)\perp(e-\varpi)| = w_0.
$$

From figure 7, it should be clear that $H^1(U) \geq \sqrt{(|e-s|^2 + w_0^2)}$.

![Figure 7](image)

Now from (61), by Lemma 3 we have

$$
H^1(U) \leq |\Psi_i(e) - \Psi_i(s)| \left(1 + \frac{c_1\alpha}{\sigma^4}\right).
$$

By Fubini we know that for some $p \in \left(s + ((e-s)^{-1})\right) \cap B_{\alpha w}(s)$ we have

$$
\int_{(p+(s-e))\cap v(S)} J(x) \, dH^1x \leq \sigma^{-2} \alpha^2 w.
$$

So let $q \in (p + (s-e)) \cap B_{\alpha w}(e)$. By Lemma 4 we have

$$
|p-q| \geq |\Psi_i(p) - \Psi_i(q)| \left(1 - 2\sigma^{-6}\alpha\right).
$$

and by bilipshitness and the fact that $|e-s| > c_1 w$ this gives

$$
|s-e| \geq |\Psi_i(s) - \Psi_i(e)| \left(1 - 4\sigma^{-6}\alpha\right).
$$
So by (63) and (64) we have
\[ w_0^2 + \left( |\Psi_i(s) - \Psi_i(e)| \left( 1 - 4\sigma^{-6} \alpha \right) \right)^2 \]
\[ \leq |e - s|^2 + w_0^2 \]
\[ \leq (H^1(U))^2 \]
\[ \leq \left( |\Psi_i(s) - \Psi_i(e)| \left( 1 + \frac{\epsilon_1 \alpha}{\sigma^4} \right) \right)^2 \]
\[ \leq |\Psi_i(s) - \Psi_i(e)|^2 + 2 \frac{\epsilon_1 \alpha}{\sigma^4} |\Psi_i(s) - \Psi_i(e)|^2 + \left( \frac{\epsilon_1 \alpha}{\sigma^4} |\Psi_i(s) - \Psi_i(e)| \right)^2. \]
So
\[ \frac{8\epsilon_1 \alpha}{\sigma^{12}} |\Psi_i(e) - \Psi_i(s)|^2 \geq w_0^2. \]
Thus
\[ w_0 \leq c_3 \sqrt{\alpha w}. \tag{65} \]
So let \( \Gamma_0 := t_0 + \langle s - e \rangle \), (65) implies
\[ U \subset N_{c_3 \sqrt{\alpha w}}(\Gamma_0) \tag{66} \]
and this concludes the proof of the Lemma.
6. Fundamental Lemmas

6.1. Precise control on the pullbacks of integral curves that form straight lines.

This coming Lemma is fundamental. We know from Lemma 5 that when we have the conditions to invoke Lemma 3 and Lemma 4 the integral curves are forced into something like straight lines. In this lemma we obtain very precise information about the pull back of such integral curves, we show that they are in effect, very much like the pullback of straight lines in the image of laminates. The proof is heuristically quite similar to the way we analyzed the the pullback of the straightline in the laminate in section 4.1 of the introduction.

Lemma 6. Let \( v \in A_F (\Omega) \). Let \( i \in \{1, 2\} \).

Given skew rectangular region \( R := \mathcal{S} (a, w\phi_2, r\phi_1) \) where \( \mathcal{S} < \sigma^2 \). We assume \( N_{\mathcal{S}} (R) \subset \Omega \). Let \( a \) be the central point of \( R \) and define \( \Theta^a_i : R \to \mathbb{R} \) as in Lemma 2. Let \( \alpha > 0 \) be a sufficiently small number.

Suppose for some \( t \in (a + (\phi_i)) \cap B_{\frac{\sigma}{2}} (a) \) we have

\[
\int_{\Theta^a_i^{-1} (t) \cap R} J (x) \, dH^1 x \leq \alpha w. \tag{67}
\]

And we have the bulk energy estimate

\[
\int_{P (s, \phi_1, \phi_2, \frac{\sigma}{2})} d (Dv (x), SO (2) \cup SO (2) H) \, dL^2 x \leq \alpha^3 w^2 \tag{68}
\]

then let \( s \) be the first point of \( \Theta^a_i^{-1} (t) \) (going backwards in time) to hit \( \partial R \) and \( e \) be the first point (going forwards) to hit \( \partial R \). Let \( U \) denote the connected component of \( \Theta^a_i^{-1} (t) \) between \( s \) and \( e \), then the following statement holds true.

Firstly recall by Lemma 5 and Lemma 3 we have

- \( \left( 1 - \frac{\xi_1}{\sigma^2} \right) |\Psi_i (s) - \Psi_i (e)| \leq H^1 (U) \leq \left( 1 + \frac{\xi_1}{\sigma^2} \right) |\Psi_i (s) - \Psi_i (e)| \). \tag{69}

- For some \( l_t := l + v (t) \), \( l \in G (1, 2) \) we have

\[
U \subset N_{\frac{\sigma}{\xi_1 \sqrt{\alpha}} (l_t)}. \tag{70}
\]

We define the clockwise normal \( w_t \), to \( l_t \) as follows. If we let \( \psi \in l_t \cap B_{\frac{\sigma}{\xi_1 \sqrt{\alpha}}} (e) \) and \( \xi \in l_t \cap B_{\frac{\sigma}{\xi_1 \sqrt{\alpha}}} (s) \) then we define \( w_t \) to be the clockwise normal to vector \( \frac{\partial w - \xi}{|\partial w - \xi|} \).

We will prove that.

Given \( A_t := N_{\frac{\sigma}{\xi_1 \sqrt{\alpha}}} (l_t) \cap R \). There exists a set \( B_t \subset A_t \) with the following properties; \( L^2 (A_t \setminus B_t) \leq \xi_1 a \xi_1 \sqrt{\alpha} w^2 \) and for any \( x \in B_t \) we have

\[
|Dv (v^{-1} (x)) \phi_1 - w_t | < \xi_1 \sqrt{\alpha} \tag{71}
\]

Proof. So to begin with, as noted in the statement, the first part is just from Lemma 5 and Lemma 3. Now by Fubini, the area formula and assumption (68) we can find the existence of a set

\[
C \subset (l^1 + v (t)) \cap B_{\frac{\sigma}{\xi_1 \sqrt{\alpha}}} (t) \text{ with } L^1 (C) > (1 - \sigma^{-2} \sqrt{\alpha}) 2\sqrt{\alpha} \tag{72}
\]

and the property that for any \( s \in C \) we have

\[
\int_{(l+\text{ })(\sigma^{-1} (R))} J (x) \, dH^1 x < \alpha w. \tag{73}
\]

Now as \( \Theta^a_i^{-1} (s) \cap v (R) \) is connected (by Lemma 1) if we let \( \eta \) denote the connected component of \( (l + s) \cap v (R) \) containing \( s \), we will show that the endpoints of \( \eta \) must be within \( \xi_1 \sigma^{-4} \sqrt{\alpha} w \) of the endpoints of \( \Theta^a_i^{-1} (s) \cap R \). Formally; let \( \tilde{s} \) denote the endpoint of \( \eta \) closest to \( s \), and let \( \tilde{e} \) denote the endpoint closest to \( e \). We will show

\[
\tilde{e} \in N_{\xi_1 \sigma^{-4} \sqrt{\alpha} w} (e) \text{ and } \tilde{s} \in N_{\xi_1 \sigma^{-4} \sqrt{\alpha} w} (s). \tag{74}
\]

To see this firstly note by bilipschitzness from (70) and by the fact that \( \tilde{e}, \tilde{s} \in v (\partial R) \) we have

\[
v^{-1} (s) \in N_{\frac{\sigma}{\xi_1 \sqrt{\alpha}}} (v^{-1} (\Theta^a_i^{-1} (s))) \cap \partial R \text{ and } v^{-1} (\tilde{e}) \in N_{\frac{\sigma}{\xi_1 \sqrt{\alpha}}} (v^{-1} (\Theta^a_i^{-1} (s))) \cap \partial R. \tag{75}
\]
By Lemma 1 we know $v^{-1}(\Theta^{a-1}_i(s))$ only passes through each side of $R$ once, so as is shown on fig 8, the end points of $v^{-1}(\Theta^{a-1}_i(s)) \cap R$ are given by $v^{-1}(e), v^{-1}(s)$. Formally $v^{-1}(\Theta^{a-1}_i(s)) \cap \partial R = \{ v^{-1}(e), v^{-1}(s) \}$ and so by (75) and the fact that $s, \tilde{s}$ are the (say) rightmost endpoints of $\Theta^{a-1}_i(s), \eta$ respectively, $e, \tilde{e}$ are the (say) leftmost endpoints; by bilipschitzness we have (74).

Note that from (74) and (69) we have that
\[
|\tilde{e} - \tilde{s}| \leq H^1(U) + 4c_3\sigma^{-4} \sqrt{\alpha w}
\]
and in the same way
\[
|\tilde{e} - \tilde{s}| \geq (1 - 8c_3\sigma^{-4} \sqrt{\alpha}) |\Psi_i(\tilde{e}) - \Psi_i(\tilde{s})|.
\]

It is also not hard to see that
\[
L^1((l + v(s)) \cap v(R) \setminus \eta) \leq c_1 \sqrt{\alpha w}.
\]

This essentially follows from fig 9. The reader who is already convinced is invited to skip the next paragraph.

By Lemma 1 we know that $v^{-1}(\Theta^{a-1}_i(s))$ must go through $v(R)$ at a definite angle. And so the line $l + v(s)$ must cut through the boundary of $v(R)$ quite cleanly. Formally, if we let $L$ denote the right hand side boundary of $R$ then diam $(v(L) \cap (l + v(t))) \leq c_1 \sqrt{\alpha w}$ since otherwise by (70) we would be able to find points $y_1, y_2 \in \Theta^{a-1}_i(s)$ with $|y_1 - y_2| > \frac{1}{2c_1} \sqrt{\alpha w}$ and $d(y_1, v(L)) < \sqrt{\alpha w}, d(y_2, v(L)) < \sqrt{\alpha w}$ and by bilipschitzness, assuming constant $c_1$ is chosen big enough this contradicts Lemma 1.

Let
\[
K := \{ x \in \eta : d(Dv(v^{-1}(x)), SO(2)) < d(Dv(v^{-1}(x)), SO(2)H) \}
\]
let
\[ L := \{ x \in \eta : d(Dv(v^{-1}(x)), SO(2) H) < d(Dv(v^{-1}(x)), SO(2)) \} \]
and let
\[ E := \{ x \in \eta : d(Dv(v^{-1}(x)), SO(2) H) = d(Dv(v^{-1}(x)), SO(2)) \}. \]

Now for some constant \( c_2 := c(\sigma) \) we have
\[ c_2 L^1(E) \leq \int_\eta d(Dv(x), SO(2) \cup SO(2) H) dL^1 x \leq \sqrt{\alpha} w. \] (79)

Which implies \( L^1(E) \leq c_2^{-1} \sqrt{\alpha} w. \)

Now \( \mathbb{K} \) is the countable union of connected subintervals \( \{K_n\} \), i.e. \( \mathbb{K} = \bigcup_{n \in \mathbb{N}} K_n \) and similarly \( L = \bigcup_{n \in \mathbb{N}} L_n \).

Let
\[ A_0 = \left\{ n \in \mathbb{N} : \int_{K_n} d(Dv(v^{-1}(x)), SO(2)) dL^1 x \leq \sqrt{\alpha} H^1(K_n) \right\} \]
and let
\[ B_0 = \left\{ n \in \mathbb{N} : \int_{L_n} d(Dv(v^{-1}(x)), SO(2) H) dL^1 x \leq \sqrt{\alpha} H^1(L_n) \right\}. \]

As \( v \) is \( C^2 \) on the compact set \( \Omega \) we know \( A_0 \) and \( B_0 \) are finite. We also know
\[ \sum_{n \in A_0} \sqrt{\alpha} L^1(K_n) + \sum_{n \in B_0} \sqrt{\alpha} L^1(L_n) \leq \sum_{n \in A_0} \int_{K_n} d(Dv(v^{-1}(x)), SO(2)) dL^1 x \]
\[ + \sum_{n \in B_0} \int_{L_n} d(Dv(v^{-1}(x)), SO(2) H) dL^1 x \leq \int_{(I_1 \cup \bigcup_{n \in \mathbb{N}} J(x))} dH^1 x \leq \alpha w. \]

So
\[ \sum_{n \in A_0} L^1(K_n) + \sum_{n \in B_0} L^1(L_n) \leq \sqrt{\alpha} w. \] (80)

We point out that from Lemma 3 we have
\[ (1 - \sigma^{-4} c_1 \sqrt{\alpha}) L^1(P_{\phi^+}(I_k)) \leq L^1(v(I_k)) \leq (1 + \sigma^{-4} c_1 \sqrt{\alpha}) L^1(P_{\phi^+}(I_k)). \] (81)

Let \( n_1 = \text{Card}(A_0) \) and \( m_1 = \text{Card}(B_0) \). Let \( \{I_k : k = 1, \ldots, n_1 + m_1\} \) be a reordering of the set \( \{K_j : j \in A_0\} \cup \{L_k : k \in B_0\} \) so that \( I_1 \) is the rightmost interval, \( I_2 \) the second rightmost interval, etc.

Note from the fact that \( \eta = \mathbb{K} \cup L \cup E \), (80), (79) and bilipschitzness we have
\[ H^1(v^{-1}(\eta) \setminus \bigcup_{k=1}^{n_1+m_1} I_k) \leq 2c_2^{-1} \sigma^{-2} \sqrt{\alpha} w. \] (82)

Let \( m_2 := m_1 + n_1 \). Now we consider point \( v^{-1}(\tilde{s}) \) to be the start of the path \( v^{-1}(\eta) \) and point \( v^{-1}(\tilde{e}) \) to be the end. So going from right to left in this way; we denote the first point of segment \( I_k \) by \( \alpha_k \) and the last point \( \beta_k \). Let \( d_k = \beta_k - \alpha_k \) for \( k = 1, 2, \ldots, m_2 \). See figure 10.

Let \( e_0 = \alpha_1 - v^{-1}(\tilde{s}) \) and \( e_{m_2} = v^{-1}(\tilde{e}) - \beta_{m_2} \). Also let \( e_k = \alpha_{k+1} - \beta_k \) for \( k \in \{1, 2, \ldots, m_2 - 1\} \). So we have
\[ v^{-1}(\tilde{e}) - v^{-1}(\tilde{s}) = \sum_{k=1}^{m_2} d_k + \sum_{j=0}^{m_2} e_j. \] (83)
Let $E_k$ be the subsegment of $v^{-1}(\eta)$ between $\beta_k$ and $\alpha_{k+1}$ for $k = 1, 2 \ldots m_2 - 1$. Let $E_0$ be the subsegment between $v^{-1}(\tilde{s})$ and $\alpha_1$ and let $E_{m_2}$ be the subsegment between $\beta_{m_2}$ and $v^{-1}(\tilde{e})$. So we know

$$\bigcup_{j=1}^{m_2} I_j \cup \bigcup_{j=0}^{m_2} E_j = v^{-1}(\eta)$$

(84)

and thus from (82) and (84) we have

$$\sum_{j=0}^{m_2} |e_j| \leq \sum_{j=0}^{m_2} H^1(E_j) \leq 2c_2^{-1} \sigma^{-2} \sqrt{\alpha w}.$$  

(85)

Now let $\mathcal{K}_1 = \{ k \in \{1, \ldots m_2 \} : d(Dv(x), SO(2) H) < d(Dv(x), SO(2)) \forall x \in I_k \}$ and let $\mathcal{K}_2 = \{1, \ldots m_2 \} \setminus \mathcal{K}_1$. For subsegment $I_k$ for $k \in \mathcal{K}_1$ we have that

$$\int_{I_k} |Dv(z) \cdot t_z| dH^1 z \geq \int_{I_k} (1 - 2d(Dv(x), SO(2) H)) |Ht_z| dH^1 z \geq |Hd_k| - 2\sigma^{-2} \sqrt{\alpha} H^1(I_k) \geq (1 - 2\sigma^{-4} \sqrt{\alpha}) |Hd_k|.$$ 

(86)

And for subsegment $I_k$ with $k \in \mathcal{K}_2$ we have

$$\int_{I_k} |Dv(z) \cdot t_z| dH^1 z \geq (1 - 2\sigma^{-4} \sqrt{\alpha}) |d_k|.$$  

(87)

So let $\tilde{d} = \sum_{k \in \mathcal{K}_2} d_k$ and $\tilde{u} = \sum_{k \in \mathcal{K}_1} d_k$, so since $\{1, 2, \ldots m_2 \} = \mathcal{K}_1 \cup \mathcal{K}_2$ and from (85) and (83) we have

$$\left| (v^{-1}(\tilde{e}) - v^{-1}(\tilde{s})) - (\tilde{d} + \tilde{u}) \right| \leq 2c_2^{-1} \sigma^{-2} \sqrt{\alpha w}.$$ 

(88)
So from (86) and (87) we also have

\[ \left| \tilde{e} - \tilde{s} \right| = \int_{v^{-1}(e)} |Dv(z) t_z| dH^1 z \]
\[ \geq \sum_{k=1}^{m_2} \int_{I_k} |Dv(z) t_z| dH^1 z \]
\[ \geq \sum_{k \in K_2} (1 - 2\sigma^{-4} \sqrt{\alpha}) |d_k| + \sum_{k \in K_1} (1 - 2\sigma^{-4} \sqrt{\alpha}) |Hd_k| \]
\[ \geq (1 - 2\sigma^{-4} \sqrt{\alpha}) \left( |\tilde{d}| + |H\tilde{u}| \right). \]  \hspace{1cm} (89)

Letting \( \tilde{e} = \sum_{j=0}^{m_2} e_j \) from (83) we have \( \tilde{v}^{-1}(\tilde{e}) = \tilde{v}^{-1}(\tilde{s}) = \tilde{d} + \tilde{u} + \tilde{e} \) and so by (88) we know \( |\tilde{e}| \leq 2e_2^{-1} \sigma^{-2} \sqrt{\alpha} \).

**Step 1**

The first thing we will show is that vector \( \tilde{u} \) points in direction \( \ddot{\Omega}_1 \) and vector \( \tilde{d} \) points in direction \( \ddot{n}_1 \). Strictly speaking this is not necessary for the proof however as it will be of great physiological comfort to know that where \( \tilde{u} \) and \( \tilde{d} \) point and as it will serve as an introduction to the ideas we will use repeatedly we give the details.

Formally, we will show

\[ \text{ang} \left( \frac{\tilde{u}}{|\tilde{u}|}, \ddot{\Omega}_1 \right) < c_4 \alpha \frac{1}{8} \]  \hspace{1cm} (90)

and

\[ \text{ang} \left( \frac{\tilde{d}}{|\tilde{d}|}, \ddot{n}_1 \right) < c_4 \alpha \frac{1}{8}. \]  \hspace{1cm} (91)

Now from (49) Lemma 4 we have that

\[ |H\psi| \geq \psi \cdot \ddot{n}_1 + \frac{c_2}{4} (\text{ang} (\psi, \ddot{\Omega}_1))^2 \]

for all \( \psi \in \Xi_i \).

![Figure 11](image)
however by (89) this implies $|\tilde{e} - \tilde{s}| > \left|v^{-1}(\tilde{e}) - v^{-1}(\tilde{s})\right|$ and this contradicts (76).

So

$$|H\tilde{u}| = |\tilde{u}| \left|H\frac{\tilde{u}}{|\tilde{u}|}\right| > |\tilde{u}| \left(\frac{\tilde{u} \cdot n_i}{|\tilde{u}|} + \frac{c_2}{4} \left(\text{ang} \left(\frac{\tilde{u}}{|\tilde{u}|}, \hat{\phi}_i\right)\right)^2\right).$$

As can be easily seen from figure 11 we have

$$|\tilde{d}| > \left(v^{-1}(\tilde{e}) - v^{-1}(\tilde{s}) + \tilde{u}\right) \cdot n_i - 2c_2^{-1}\sigma^{-2}\sqrt{\alpha w}.$$  (92)

So

$$|H\tilde{u}| + |\tilde{d}| \geq \tilde{u} \cdot n_i + \frac{c_2 |\tilde{u}|}{4} \left(\text{ang} \left(\frac{\tilde{u}}{|\tilde{u}|}, \hat{\phi}_i\right)\right)^2 + \left(v^{-1}(\tilde{e}) - v^{-1}(\tilde{s})\right) \cdot n_i - \tilde{u} \cdot n_i - 2c_2^{-1}\sigma^{-2}\sqrt{\alpha w}$$

$$= \left(v^{-1}(\tilde{e}) - v^{-1}(\tilde{s})\right) \cdot n_i + \frac{c_2 |\tilde{u}|}{4} \left(\text{ang} \left(\frac{\tilde{u}}{|\tilde{u}|}, \hat{\phi}_i\right)\right)^2 - 2c_2^{-1}\sigma^{-2}\sqrt{\alpha w}. \quad \text{(93)}$$

Hence by (76), (89), (93) we have

$$8\sigma^{-4}e_3\sqrt{\alpha w} + \left(v^{-1}(\tilde{e}) - v^{-1}(\tilde{s})\right) \cdot n_i \geq H^1(\eta)$$

$$\geq (1 - 2\sigma^{-4}\sqrt{\alpha}) \left(|\tilde{d}| + |H\tilde{u}|\right)$$

$$\geq \left|(v^{-1}(\tilde{e}) - v^{-1}(\tilde{s})) \cdot n_i\right| + \frac{c_2 |\tilde{u}|}{4} \left(\text{ang} \left(\frac{\tilde{u}}{|\tilde{u}|}, \hat{\phi}_i\right)\right)^2 - 4c_2^{-1}\sigma^{-2}\sqrt{\alpha w}.$$  (93)

Thus

$$\frac{|\tilde{u}|}{4} \left(\text{ang} \left(\frac{\tilde{u}}{|\tilde{u}|}, \hat{\phi}_i\right)\right)^2 \leq c_3\sqrt{\alpha w}.$$  

So either $|\tilde{u}| < \alpha^4 w$ or we have

$$c_3\sqrt{\alpha w} \geq \frac{\alpha^4 w}{4} \left(\text{ang} \left(\frac{\tilde{u}}{|\tilde{u}|}, \hat{\phi}_i\right)\right)^2 \iff 4c_3\alpha^4 \geq \left(\text{ang} \left(\frac{\tilde{u}}{|\tilde{u}|}, \hat{\phi}_i\right)\right)^2 \iff 2\sqrt{c_3\alpha} \geq \text{ang} \left(\frac{\tilde{u}}{|\tilde{u}|}, \hat{\phi}_i\right)$$

and so we have established (90).

Now we establish (91). To start, we know

$$|H\tilde{u}| \geq |\tilde{u} \cdot n_i| \quad \text{(94)}$$

from (48), Lemma 4. Now by (88)

$$\tilde{d} \cdot n_i + \tilde{u} \cdot n_i \geq (v^{-1}(\tilde{e}) - v^{-1}(\tilde{s})) \cdot n_i - 2c_2^{-1}\sigma^{-2}\sqrt{\alpha w}$$

(95)

and $|\tilde{d}| = \sqrt{|\tilde{d} \cdot n_i|^2 + |\tilde{d} \cdot \hat{\phi}_i|^2}$ as we have seen before, since $|\tilde{d}| < 1$ we have

$$\sqrt{|\tilde{d} \cdot n_i|^2 + |\tilde{d} \cdot \hat{\phi}_i|^2} = \int_{\Sigma} |\tilde{d} \cdot n_i|^2 + |\tilde{d} \cdot \hat{\phi}_i|^2\frac{x - \tilde{x}}{2} dL x$$

$$\geq \frac{|\tilde{d} \cdot \hat{\phi}_i|^2}{2}.$$  (96)

so putting (94), (95), (96) we get

$$|\tilde{d}| + |H\tilde{u}| \geq |\tilde{d} \cdot n_i| + |\tilde{u} \cdot n_i| + \frac{|\tilde{d} \cdot \hat{\phi}_i|^2}{2} \quad \text{(94),(96)}$$

$$\geq (v^{-1}(\tilde{e}) - v^{-1}(\tilde{s})) \cdot n_i + \frac{|\tilde{d} \cdot \hat{\phi}_i|^2}{2} - 2c_2^{-1}\sigma^{-2}\sqrt{\alpha w}. \quad \text{(97)}$$
So putting (97) together with (76) (recall $\tilde{s}, \tilde{c}$ are the endpoints of $\eta$), (89) and (88) we get

\[
(1 + 8\epsilon_3\sigma^{-4}\sqrt{a}) \left\| (v^{-1}(\tilde{c}) - v^{-1}(\tilde{s})) \cdot n_i \right\| \geq H^1(\eta)
\]
\[
\geq (1 - 2\sigma^{-4}\sqrt{a}) \left( |\tilde{d}| + |H\tilde{u}| \right)
\]
\[
\geq (1 - 2\sigma^{-4}\sqrt{a}) \left( (v^{-1}(\tilde{c}) - v^{-1}(\tilde{s})) \cdot n_i - 2c_2^{-1}\sigma^{-2}\sqrt{a}w \right) + \frac{|\bar{d} \cdot \phi_i|^2}{4}.
\]

So

\[2c_2^{-1}\sigma^{-2}\sqrt{a}w + 10\epsilon_3\sigma^{-4}\sqrt{a} \left\| (v^{-1}(\tilde{c}) - v^{-1}(\tilde{s})) \cdot n_i \right\| \geq \frac{|\bar{d} \cdot \phi_i|^2}{4},\]

thus

\[
\tilde{c}_4\sqrt{a}w \geq \frac{|\bar{d} \cdot \phi_i|^2}{4} = \frac{|\bar{d}|^2}{4} \frac{d}{|d|} \cdot \phi_i
\]

So

\[
\sqrt{\tilde{c}_4\sigma^{-2}\alpha} \geq \frac{|\bar{d}|}{2} \frac{d}{|d|} \cdot \phi_i
\]

assuming $|\bar{d}| \geq \alpha \sqrt{w}$ we have

\[
\sqrt{\tilde{c}_4\sigma^{-2}\alpha} \geq \frac{|\bar{d}|}{2} \frac{d}{|d|} \cdot \phi_i
\]

which establishes (91).

Step 2

Now we use similar arguments to establish that most of the subsegments $\{I_k : k \in \mathcal{K}_2\}$ lie roughly parallel to $n_i$ and most of the subsegments $\{I_k : k \in \mathcal{K}_1\}$ lie roughly parallel to $\tilde{\phi}_i$.

Let $P_2 := \{ k \in \mathcal{K}_2 : \text{ang} \left( \frac{d_k}{|d_k|}, n_i \right) > \alpha \frac{\pi}{4} \}$ and $P_1 := \{ k \in \mathcal{K}_1 : \text{ang} \left( \frac{d_k}{|d_k|}, \tilde{\phi}_i \right) > \alpha \frac{\pi}{4} \}$. Firstly we will show that for any $k \in P_1 \cup P_2$ we have

\[
L^1(v(I_k)) \geq \left( 1 + \frac{\epsilon_2 \alpha \pi}{16} \right) L^1(P_{\phi_i}^+(I_k)).
\]

Look at case $k \in P_2$, see fig 12. Firstly, we know from Lemma 1 that $\text{ang} \left( \frac{d_k}{|d_k|}, n_i \right) \leq \pi$. So

\[
|d_k|^2 \geq \left( L^1(P_{\phi_i}^+(I_k)) \right)^2 + \left( \sin \text{ang} \left( \frac{d_k}{|d_k|}, n_i \right) L^1(P_{\phi_i}^+(I_k)) \right)^2
\]
\[
\geq \left( L^1(P_{\phi_i}^+(I_k)) \right)^2 \left( 1 + \left( \sin \alpha \frac{\pi}{4} \right)^2 \right).
\]

**Figure 12**
Now as we have seen before, by considering the integral \( \int_{1}^{\infty} \left( \frac{\sin \alpha}{2} \right)^{2} \frac{x^{-\frac{\alpha}{2}}}{dL} \),

\[
L^1 \left( P_{\phi^+} (I_k) \right) \sqrt{1 + \left( \sin \alpha \frac{\alpha}{16} \right)^2} \geq L^1 \left( P_{\phi^+} (I_k) \right) \left( 1 + \frac{\sin \alpha}{4} \right) \tag{100}
\]

And since \( |\sin x - x| \leq (\sum_{n=3}^{\infty} \frac{1}{n!}) x^3 \), assuming \( \alpha > 0 \) is small enough (in the applications of this lemma, \( \alpha \) will be some power of \( \kappa \) or \( \epsilon \) and so will indeed be small enough) we have \( \left( \sin \alpha \frac{\alpha}{16} \right)^2 \geq \frac{\alpha^2}{16} \).

So putting this together with (99) and (100) we have

\[
|d_k| \geq L^1 \left( P_{\phi^+} (I_k) \right) \left( 1 + \frac{\alpha^2}{8} \right). \tag{101}
\]

Now as

\[
\int_{v(I_k)} d Dv (v^{-1} (x)) , SO (2) \) dL \geq \sqrt{\sigma} L^1 (v(I_k)),
\]

we have that

\[
\int_{I_k} d Dv (z) , SO (2) \) dH \leq \sigma^{-2} \sqrt{\sigma} L^1 (v(I_k))
\]

\[
\leq \sigma^{-4} \sqrt{\sigma} H (I_k). \tag{102}
\]

For each \( z \in I_k \) let \( R (z) \in SO (2) \) be such that \( |Dv (x) - R (z)| = d (Dv (z) , SO (2)) \). So by (101) and (102) we have

\[
L^1 (v (I_k)) = \int_{I_k} |Dv (z) t (z)| dH \geq \int_{I_k} |R (z) t (z)| dH \geq H (I_k) \left( 1 - \sigma^{-4} \sqrt{\sigma} \right)
\]

\[
\geq |d_k| \left( 1 - \sigma^{-4} \sqrt{\sigma} \right)
\]

\[
\geq L^1 \left( P_{\phi^+} (I_k) \right) \left( 1 + \frac{\alpha^2}{8} \right) \left( 1 - \sigma^{-4} \sqrt{\sigma} \right)
\]

\[
\geq L^1 \left( P_{\phi^+} (I_k) \right) \left( 1 + \frac{\alpha^2}{16} \right)
\]

for \( \alpha \) small enough. This establishes the claim in the case \( k \in P_1 \).

Let \( k \in P_2 \). Observe the fig 13.

\[\text{Figure 13}\]
As before letting $T ( z ) \in SO ( 2 ) H$ be such that $|Dv ( z ) - T ( z )| = d ( Dv ( z ) , SO ( 2 ) H )$ we have from (102)

\[
L^1 ( v ( I_k ) ) = \int_{I_k} |Dv ( z ) t ( z)| dH^1 z \\
\geq \int_{I_k} |T ( z ) t ( z)| dH^1 z - \int_{I_k} d ( Dv ( z ) , SO ( 2 ) H ) dH^1 z \\
\geq \int_{I_k} |T ( z ) t ( z)| dH^1 z - \sigma^{-4} \sqrt{\alpha} H^1 ( I_k ).
\]

(103)

And we know

\[
\int_{I_k} |T ( z ) t ( z)| dH^1 z = \int_{I_k} |H t ( z)| dH^1 z \\
\geq |d_k| \left| H \frac{d_k}{|d_k|} \right|.
\]

(104)

Now by (48) Lemma 4 we know

\[
\left| H \frac{d_k}{|d_k|} \right| \geq \frac{d_k}{|d_k|} \cdot n_1 + \frac{c_2}{4} \left( \operatorname{ang} \left( \frac{d_k}{|d_k|} , \hat{v}_i \right) \right)^2 \geq \frac{d_k}{|d_k|} \cdot n_1 + \frac{c_2 \alpha^\frac{1}{8}}{4}.
\]

(105)

Putting together (103),(104) and (105) gives

\[
L^1 ( v ( I_k ) ) \geq d_k \cdot n_1 + \frac{c_2 |d_k|}{4} \alpha^\frac{1}{8} - \sigma^{-4} \sqrt{\alpha} H^1 ( I_k )
\]

Now $d_k \cdot n_1 = L^1 \left( P_{\phi^+} ( I_k ) \right)$ and so $|d_k| \geq L^1 \left( P_{\phi^+} ( I_k ) \right)$ and by Lemma 1 we have $H^1 ( I_k ) \leq \sigma^{-4} L^1 \left( P_{\phi^+} ( I_k ) \right)$. So

\[
L^1 ( v ( I_k ) ) \geq L^1 \left( P_{\phi^+} ( I_k ) \right) \left( 1 + \frac{c_2 \alpha^\frac{1}{8}}{4} \right) - \sigma^{-4} \sqrt{\alpha} H^1 ( I_k ) \geq L^1 \left( P_{\phi^+} ( I_k ) \right) \left( 1 + \frac{c_2 \alpha^\frac{1}{8}}{8} \right)
\]

for small enough $\alpha$, hence we have established (98).

Step 3 In this step we bound the cardinality of $P_1$ and $P_2$.

Recall by (76) and (77)

\[
|\tilde{\sigma} - \bar{c}| \in \left( L^1 \left( P_{\phi^+} \left( v^{-1} \left( [\tilde{\sigma}, \bar{c}] \right) \right) \right) (1 - 8c_3 \sigma^{-4} \sqrt{\alpha}) , L^1 \left( P_{\phi^+} \left( v^{-1} \left( [\tilde{\sigma}, \bar{c}] \right) \right) \right) (1 + 8c_3 \sigma^{-4} \sqrt{\alpha}) \right)
\]

(106)

and from (82)

\[
L^1 \left( \left[ \tilde{\sigma}, \bar{c} \right] \cup \bigcup_{k \in K_2 \cup K_2} v ( I_k ) \right) \leq 2c_2^2 \sigma^{-4} \sqrt{\alpha} |\tilde{\sigma} - \bar{c}|.
\]

(107)
Now using (106), (81) and (98) we have
\[
(1 + 8 \varepsilon_3 \sigma^{-4} \sqrt{\alpha}) L^1 \left( P_{\phi_+^1} \left( v^{-1} ([\tilde{s}, \tilde{c}]) \right) \right) \geq |\tilde{s} - \tilde{c}|
\]
\[
\geq \sum_{k \in K_1 \cup K_2} L^1 (v(I_k))
\]
\[
\geq \sum_{k \in P_1 \cup P_2} L^1 (v(I_k)) + \sum_{k \in (K_1 \cup K_2) \setminus (P_1 \cup P_2)} L^1 (v(I_k))
\]
\[
\geq \left( 1 + \frac{c_2 \alpha^4}{16} \right) \sum_{k \in P_1 \cup P_2} L^1 \left( P_{\phi_+^1} (I_k) \right)
+ (1 - \sigma^{-4} \varepsilon_1 \sqrt{\alpha}) \sum_{k \in (K_1 \cup K_2) \setminus (P_1 \cup P_2)} L^1 \left( P_{\phi_+^1} (I_k) \right)
\]
\[
\geq \sum_{k \in K_1 \cup K_2} L^1 \left( P_{\phi_+^1} (I_k) \right) + \sum_{k \in P_1 \cup P_2} \frac{c_2 \alpha^4}{8} L^1 \left( P_{\phi_+^1} (I_k) \right) - \sigma^{-4} \varepsilon_1 \sqrt{\alpha} |\tilde{s} - \tilde{c}|.
\]

(108)

Now from (82) we have
\[
L^1 \left( P_{\phi_+^1} \left( v^{-1} ([\tilde{s}, \tilde{c}]) \setminus \bigcup_{k \in K_1 \cup K_2} I_k \right) \right) \leq 4 \varepsilon_2^{-1} \sigma^{-2} \sqrt{\alpha} |\tilde{s} - \tilde{c}|.
\]

(109)

Putting this together with (108) we get
\[
(1 + 8 \varepsilon_3 \sigma^{-4} \sqrt{\alpha}) L^1 \left( P_{\phi_+^1} \left( v^{-1} ([\tilde{s}, \tilde{c}]) \right) \right) \geq L^1 \left( P_{\phi_+^1} \left( v^{-1} ([\tilde{s}, \tilde{c}]) \right) \right) - 4 \varepsilon_2^{-1} \sigma^{-2} \sqrt{\alpha} |\tilde{s} - \tilde{c}|
+ \sum_{k \in P_1 \cup P_2} \frac{c_2 \alpha^4}{8} L^1 \left( P_{\phi_+^1} (I_k) \right) - \sigma^{-4} \varepsilon_1 \sqrt{\alpha} |\tilde{s} - \tilde{c}|.
\]

Which implies
\[
\sum_{k \in P_1 \cup P_2} \alpha^4 L^1 \left( P_{\phi_+^1} (I_k) \right) \leq c_5 \sqrt{\alpha} |\tilde{s} - \tilde{c}|.
\]

So by bilipschitzness and Lemma 1 we have
\[
\sigma^{-2} c_5 \alpha^4 L^1 \left( P_{\phi_+^1} \left( v^{-1} ([\tilde{s}, \tilde{c}]) \right) \right) \geq c_5 \alpha^4 |\tilde{s} - \tilde{c}|
\]
\[
\geq \sum_{k \in P_1 \cup P_2} L^1 \left( P_{\phi_+^1} (I_k) \right)
\]
\[
\geq \sigma^2 \sum_{k \in P_1 \cup P_2} H^1 (I_k).
\]

(110)

By Lemma 1 this gives us a bound on the cardinality of $P_1 \cup P_2$ of the following form
\[
\sigma^{-6} c_5 \alpha^4 H^1 \left( v^{-1} ([\tilde{s}, \tilde{c}]) \right) \geq \sum_{k \in P_1 \cup P_2} H^1 (I_k).
\]

(111)

As a consequence by (82) we have
\[
H^1 \left( v^{-1} ([\tilde{s}, \tilde{c}]) \setminus \bigcup_{k \in K_1 \cup K_2 \setminus (P_1 \cup P_2)} I_k \right) \leq H^1 \left( v^{-1} ([\tilde{s}, \tilde{c}]) \setminus \bigcup_{k \in K_1 \cup K_2} I_k \right) + H^1 \left( \bigcup_{k \in P_1 \cup P_2} I_k \right)
\]
\[
\leq 2 \varepsilon_3 \sigma^{-6} c_5 \alpha^4 H^1 \left( v^{-1} ([\tilde{s}, \tilde{c}]) \right).
\]

(112)

Step 4
Now let

\[ O_2 := \left\{ k \in K_2 \setminus P_2 : \exists J_k \subset I_k \text{ with } H^1(J_k) \geq \left( 1 - \frac{\alpha}{2^8} \right) H^1(I_k) \right\} \]  (113)

and let

\[ O_1 := \left\{ k \in K_1 \setminus P_1 : \exists J_k \subset I_k \text{ with } H^1(J_k) \geq \left( 1 - \frac{\alpha}{2^8} \right) H^1(I_k) \right\} \]  (114)

We will show that for \( k \in O_1 \cup O_2 \)

\[ L^1(v(I_k)) \geq \left( 1 + \frac{c_2 \alpha^{\frac{m}{4}}}{8} \right) L^1(P_{\phi^+}(I_k)) \]  (115)

First we consider the case \( k \in O_1 \) because its more intricate.

As before letting \( t(z) \) be the tangent to \( I_k \) at \( z \) and letting \( U(z) \in SO(2) \) be such that \( d(Dv(z), SO(2)H) = |Dv(z) - U(z)| \) we have by definition of the set \( \{I_k : k = 1, \ldots m_0\} \) that

\[ \int_{I_k} d(Dv(z), SO(2)H) dH^1z \leq \sqrt{\alpha H^1(I_k)}. \]

Now using again (48) from Lemma 4 and for the final inequality using Lemma 1 we have

\[ L^1(v(I_k)) \geq \int_{I_k} |Dv(z) t(z)| dH^1z \]

\[ \geq \int_{I_k} |Ht(z)| dH^1z - \sqrt{\alpha H^1(I_k)} \]

\[ \geq \int_{J_k} |Ht(z)| dH^1z + \int_{I_k \setminus J_k} |Ht(z)| dH^1z - \sqrt{\alpha H^1(I_k)} \]

\[ \geq L^1(P_{\phi^+}(J_k)) \left( 1 + \frac{c_2 \alpha^\frac{m}{4}}{4} \right) - \sqrt{\alpha H^1(I_k)} \]

\[ \geq L^1(P_{\phi^+}(I_k)) \left( 1 + \frac{c_2 \alpha^\frac{m}{4}}{4} \right) - 4\alpha^\frac{m}{2} H^1(I_k) \]

\[ \geq L^1(P_{\phi^+}(I_k)) \left( 1 + \frac{c_2 \alpha^\frac{m}{4}}{8} \right) . \]  (116)

The case where \( k \in O_1 \) can be argued with a simple Pythagoras type argument. We do not go into the details.

**Step 5**

Now in the same way as we showed the cardinality of \( P_1 \) and \( P_2 \) are bounded, we will show the cardinality of \( O_1 \) and \( O_2 \) are bounded. The reader who is already convinced is invited to skip to Step 6.
Using (81), (112), (106) and (115) we have

\[
(1 + 8c_3\sigma^{-4}\sqrt{\alpha}) L^1 \left(P_{\phi^+} \left(v^{-1}([\bar{s}, \bar{c}])\right)\right) \geq \left|\bar{s} - \bar{c}\right| \geq \sum_{k \in (\mathcal{K}_1 \cup \mathcal{K}_2 \setminus (P_1 \cup P_2) \cup O_1 \cup O_2)} L^1 (v(I_k)) + \sum_{k \in O_1 \cup O_2} L^1 (v(I_k))
\]

\[
\geq \sum_{k \in (\mathcal{K}_1 \cup \mathcal{K}_2 \setminus (P_1 \cup P_2))} L^1 (P_{\phi^+} (I_k)) + \sum_{k \in O_1 \cup O_2} L^1 (P_{\phi^+} (I_k))
\]

\[
\geq \left(1 - \sigma^{-\frac{4}{2}}c_1\sqrt{\alpha}\right) \sum_{k \in (\mathcal{K}_1 \cup \mathcal{K}_2 \setminus (P_1 \cup P_2))} L^1 \left(P_{\phi^+} \left(v^{-1} ([\bar{s}, \bar{c}])\right)\right)
\]

\[
+ \left(1 + \frac{c_2\alpha^3}{8}\right) \sum_{k \in O_1 \cup O_2} L^1 \left(P_{\phi^+} \left(v^{-1} ([\bar{s}, \bar{c}])\right)\right)
\]

Putting things together we have

\[
\frac{c_2\alpha^3}{8} \sum_{k \in O_1 \cup O_2} L^1 \left(P_{\phi^+} \left(v^{-1} ([\bar{s}, \bar{c}])\right)\right) \leq c_0\alpha^{\frac{3}{2}} L^1 \left(P_{\phi^+} \left(v^{-1} ([\bar{s}, \bar{c}])\right)\right)
\]

so by Lemma 1

\[
\sum_{k \in O_1 \cup O_2} H^1(I_k) \leq \sigma^{-2} \sum_{k \in O_1 \cup O_2} L^1 \left(P_{\phi^+} \left(v^{-1} ([\bar{s}, \bar{c}])\right)\right) \leq 8\sigma^{-2} c_2^{-1} c_0\alpha^{\frac{1}{2}} L^1 \left(P_{\phi^+} \left(v^{-1} ([\bar{s}, \bar{c}])\right)\right).
\]

Step 6

Claim 1. We will show the existence of a set \(Y \subset [\bar{s}, \bar{c}]\) with \(L^1 ([\bar{s}, \bar{c}] \setminus Y) \leq \left(1 - c_7\alpha^{\frac{1}{2}}\right) |\bar{s} - \bar{c}|\) for which if we let \(R^*\) be the clockwise rotation by \(\frac{\pi}{2}\) and let \(w_t := R^* \left(\frac{\bar{x} - \bar{c}}{|\bar{x} - \bar{c}|}\right)\) for any \(z \in Y\) we have

\[
Dv \left(v^{-1} (x)\right) \phi_i \in N_{c_7\sqrt{\alpha}} (w_t).
\]

Proof of Claim:

Let \(D := (\mathcal{K}_1 \setminus (P_1 \cup O_1)) \cup (\mathcal{K}_2 \setminus (P_2 \cup O_2))\). For any \(k \in D \cap \mathcal{K}_1\) (by definition (114)) we have

\[
H^1 \left(\left\{ x \in I_k : \text{ang} (t(z), \phi_i) > \alpha^{\frac{1}{2}} \right\}\right) \leq \alpha^{\frac{1}{2}} H^1 (I_k)
\]

so \(W_k := \left\{ x \in I_k : \text{ang} (t(z), \phi_i) \leq \alpha^{\frac{1}{2}} \right\}\) is such that \(H^1 (W_k) \geq (1 - \alpha^{\frac{1}{2}}) H^1 (I_k)\).

Similarly, for any \(k \in D \cap \mathcal{K}_2\) (by definition (113)), \(W_k := \left\{ x \in I_k : \text{ang} (t(z), u_i) \leq \alpha^{\frac{1}{2}} \right\}\) is such that \(H^1 (W_k) \geq (1 - \alpha^{\frac{1}{2}}) H^1 (I_k)\).

So from (111) and (117) we have

\[
\sum_{k \in P_1 \cup P_2 \cup O_1 \cup O_2} H^1 (I_k) \leq 9\sigma^{-6} c_2^{-1} c_0\alpha^{\frac{1}{2}} L^1 \left(P_{\phi^+} \left(v^{-1} ([\bar{s}, \bar{c}])\right)\right)
\]
so from the definition of $D$ and by (82) and Lemma 1 we have
\[
H^1 \left( v^{-1} ([s, e]) \setminus \bigcup_{k \in D} I_k \right) \leq 11 \sigma^{-6} \epsilon_2^{-1} c_2^{-1} c_0 \alpha^4 H^1 (v^{-1} ([s, e])) .
\] (119)

Note from (73) we have
\[
\int_{v^{-1}(\eta)} d(\text{Dev}(z), SO(2) \cup SO(2) H) dH^1 x \leq \sigma^{-2} \alpha^2 w.
\]

Take $z \in (\bigcup_{k \in D} W_k) \cap \{ z \in v^{-1}(\eta) : d(\text{Dev}(z), SO(2) \cup SO(2) H) < \alpha^2 \}$.
We have that either $z \in \bigcup_{k \in D \cap K_1} W_k$ or $z \in \bigcup_{k \in D \cap K_2} W_k$. Supposing the later, then
\[
\text{ang}(t(z), n_i) \leq \alpha \frac{|n_i|}{|e - s|}.
\] (120)

Now as we have already calculated (Lemma 1, (14)) $t(z) := [S^{-1}(z) S^{-1}(z)] n_i$ where Dev(z) := R(z) S(z) is the polar decomposition of the matrix Dev(z). So S(z) \in N_{\sqrt{\alpha}}(\{H, Id\}).

Its a lengthy calculation to see that
\[
H^{-1} H^{-1} n_i = \hat{\phi}_i
\] (121) for $i = 1, 2$. The proof is relegated to the Appendix 1.

So we know that Dev(z) \in N_{\sqrt{\alpha}}(SO(2)) or Dev(z) \in N_{\sqrt{\alpha}}(SO(2) H) and we can not have the latter case because that would imply $t(z) := [S^{-1}(z) S^{-1}(z)] n_i \in N_{\sqrt{\alpha}}(\hat{\phi}_i)$ which contradicts (120) and so we must have $S(z) \in B_{\sqrt{\alpha}}(Id)$.

Let $R_1 \in SO(2)$ be the rotation such that
\[
R_1 n_i = \frac{\hat{\phi}_1 - \hat{s}}{|\hat{\phi}_1 - \hat{s}|}.
\] (122)

Let $t(z)$ denote the (non-normalised) tangent to the curve $v^{-1}(\eta)$; formally $t(z) := [\text{Dev}(z)]^{-1} \frac{\hat{\phi}_1 - \hat{s}}{|\hat{\phi}_1 - \hat{s}|}$, as already noted, since Dev(z) \in N_{\sqrt{\alpha}}(SO(2)) we know
\[
S(z) \in B_{\sqrt{\alpha}}(Id)
\] (123) as this (by the fact that $t(z) := [S^{-1}(z) S^{-1}(z)] n_i$ implies $|t(z) - n_i| < c_7 \alpha$ and using (122) we have
\[
|\text{Dev}(z) n_i - R_1 n_i| \leq |\text{Dev}(z) t(z) - \text{Dev}(z) n_i| + |\text{Dev}(z) t(z) - R_1 n_i| \leq \sigma^{-2} |t(z) - n_i| \leq \sigma^{-2} c_7 \sqrt{\alpha}.
\]

So letting $R^*$ be the clockwise rotation by $\frac{\pi}{2}$ we have by (123) and (122)
\[
\sigma^{-2} c_7 \sqrt{\alpha} \geq |\text{Dev}(z) n_i - R_1 n_i| = \left| R(z) R^*^{-1} \phi_i - \frac{\hat{\phi}_1 - \hat{s}}{|\hat{\phi}_1 - \hat{s}|} \right| - \sqrt{\alpha} = \left| \text{Dev}(z) \phi_i - R^* \left( \frac{\hat{\phi}_1 - \hat{s}}{|\hat{\phi}_1 - \hat{s}|} \right) \right| - 2 \sqrt{\alpha}.
\] (124)

Now in the case $z \in \bigcup_{k \in D \cap K_1} W_k$, from (121) we can see $S(z) \in B_{\sqrt{\alpha}}(H)$. Let $R_2 \in SO(2)$ be the rotation such that $R_2 H^{-1} n_i = \frac{\hat{\phi}_2 - \hat{s}}{|\hat{\phi}_2 - \hat{s}|}$.

Observe figure 14.

As can be seen from figure 14 letting $R^*$ again denote the clockwise rotation by $\frac{\pi}{2}$, $R^*^{-1} \phi_i = n_i$ and $R^* H^{-1} \phi_i = H^{-1} n_i$. Now
\[
\text{Dev}(z) t(z) = R(z) S(z) \left[ S^{-1}(z) S^{-1}(z) \right] n_i = R(z) S^{-1}(z) n_i,
\]
so
\[
|\text{Dev}(z) t(z) - R(z) H^{-1} n_i| = |S^{-1}(z) - H^{-1}| \leq c_8 \sqrt{\alpha}.
\]
Again as $Dv(z) t(z) = \frac{\epsilon - \bar{\epsilon}}{|\epsilon - \bar{\epsilon}|}$ so (as $R^* H^{-1} n_i = H \phi_i$) by multiplying through on the right by $R^*$ this gives

$$\left| R^* \left( \frac{\epsilon - \bar{\epsilon}}{|\epsilon - \bar{\epsilon}|} \right) - R(z) H \phi_i \right| \leq c_8 \sqrt{\alpha}$$

so as $S(z) \in B_{\sqrt{\alpha}}(H)$

$$\left| R^* \left( \frac{\epsilon - \bar{\epsilon}}{|\epsilon - \bar{\epsilon}|} \right) - Dv(z) \phi_i \right| \leq 2c_8 \sqrt{\alpha}. \quad (125)$$

And as $\frac{\epsilon - \bar{\epsilon}}{|\epsilon - \bar{\epsilon}|} = \frac{\epsilon - \bar{\epsilon}}{2 |\epsilon - \bar{\epsilon}|}$ this gives

$$\left| R^* \left( \frac{\theta - \xi}{|\theta - \xi|} \right) - Dv(z) \phi_i \right| < 2c_8 \sqrt{\alpha}.$$

So let $Y = v(\bigcup_{k \in D} W_k) \cap \{ z \in I_k : d(Dv(z), SO(2) \cup SO(2) H) < \sqrt{\alpha} \}$. Now as $H^1 (\bigcup_{k \in D} v(I_k) \setminus H^1) \leq \alpha^{\frac{3}{2}} \sum_{k \in D} H^1(I_k) \leq \alpha^{\frac{3}{2}} |\bar{\epsilon} - \epsilon|$ so by bilipschitzness $H^1 (\bigcup_{k \in D} v(I_k) \setminus v(W_k)) \leq \epsilon^{-2} \alpha^{\frac{3}{2}} |\bar{\epsilon} - \epsilon|$. So by (119) and (73) we have

$$H^1 ([\bar{s}, \bar{e}] \setminus Y) \leq c_9 \alpha^{\frac{3}{2}} |\bar{s} - \bar{e}| \quad (126)$$

and for any $x \in Y$, by (124), (125), letting $w_t := R^* \left( \frac{\theta - \xi}{|\theta - \xi|} \right)$ we have

$$|Dv(v^{-1}(x)) \phi_i - w_t| < 2c_8 \sqrt{\alpha}. \quad (127)$$

and this establishes claim 1. \hfill \Box

Now recall we chose $\eta$ as a subset of $(l_s + v(s)) \cap v(R)$ when $s$ was an arbitrary point in the set $C$ (see 72). So $\eta$ and hence $Y$ depend implicitly on $s$, now it will be convenient to make the dependence explicit. So let $\eta_s := \eta$ and $Y_s := Y$.

Let $B_t := \bigcup_{s \in C} Y_s$. And recall $A_s := N_{\sqrt{\pi}w} (l_s) \cap v(R)$. Now from (78) and (126) we have for every $s \in C$

$$L^1 (l_s \cap v(R) \setminus Y_s) \leq 2c_9 \alpha^{\frac{3}{2}} |\bar{s} - \bar{e}|$$

and from (72) we have

$$L^2 (A \cap B) \leq \int_{(l_s + v(R) \setminus B_{\sqrt{\pi}w}(t))} L^1 (l_s \cap v(R) \setminus Y_s) dL^1 s$$

$$\leq 2c_9 \alpha^{\frac{3}{2}} |e - s| L^1 ((l_s + t) \cap B_{\sqrt{\pi}w}(t) \setminus C)$$

$$\leq 4c_9 \alpha^{\frac{3}{2}} w^2.$$

And by (127) and point $x \in B_t$ satisfies (71) and the proof is complete. \hfill \Box
7. The Coarea alternative: Part I

In section 4.3 we described the “coarea alternative”, roughly speaking, this was that for a function \( v \) on a region \( S \) (diameter \( \epsilon \) say) with small bulk energy and small “coarea integral” with respect to the level set functions \( \Theta^1 \) and \( \Theta^2 \), function \( v \) on \( S \) must behave very much like an affine map whose linear part is in \( SO(2) \cup SO(2)H \). And for a function \( v \) with small bulk energy and not small “coarea integral”, \( v \) must oscillate by a not small amount in \( S \). If we argue in the simplest way, for a function with small bulk energy (say \( \int_S d(Dv(x),SO(2)\cup SO(2)H)dL^2x \leq \kappa_m \epsilon \), for some large integer \( m_0 \)) then \( \int_S |D^2v(x)|^2 dL^2x \leq \kappa \) implies \( \int_{v(S)} J(x)|D\Theta^i(x)|dL^2x \leq \kappa \epsilon^2 \) for \( i \in \{1,2\} \) and from this we can show that the linear part (denoted by \( L \)) of the affine map obtained from interpolating \( v \) on the corners of a triangle inside \( S \) is such that

\[
d(L,SO(2)\cup SO(2)H) < \kappa. \tag{128}\]

So we take a triangulation \( \{\tau_i\} \) of \( \Omega \) (with triangulation size \( \epsilon \)), by the “alternative”, for all triangles \( \tau_i \) with small bulk energy, either: (1); the linear part \( L_i \) of the interpolation of \( v \) on \( \tau_i \) is such that \( L_i \) is less than \( \kappa \) away from the wells. Or, (2); \( \int_{\tau_i} |D^2v(x)|dL^2x > \kappa \). If we want to apply this to finite element approximations we end up having to argue as follows: We can for simplicity assume all triangles \( \tau_i \) have very low bulk energy. Let \( \kappa = \epsilon^\alpha \) for some \( \alpha > 0 \) we decide on later. Let \( B_1 := \{ \tau_i: d(L_i,SO(2)\cup SO(2)H) > \epsilon^{\frac{\alpha}{2}} \}. \) If \( \int_{\Omega} |D^2v(x)|dL^2x \leq \epsilon^{-\beta} \) then \( \text{Card}(B_1) \leq \epsilon^{\beta-\alpha-1} \). So if \( \tilde{v} \) denotes the function obtained by taking the affine interpolation of \( v \) on the triangulation \( \{\tau_i\} \) then we have,

\[
\int_{\Omega} d(D\tilde{v}(x),SO(2)\cup SO(2)H)dL^2x \leq \sum_{\tau_i \in B_1} \sigma^{-2}\epsilon^2 + \epsilon^\frac{\alpha}{2} \leq \sigma^{-2}\epsilon^{1-\beta-\alpha} + \epsilon^\frac{\alpha}{2}. \tag{129}\]

Now matter how small \( \beta \) is or how we chose \( \alpha \) as we expect \( \int_{\Omega} d(D\tilde{v}(x),SO(2)\cup SO(2)H)dL^2x \approx \epsilon^\frac{\alpha}{2} \) we do not get any kind of contradiction from this!

Figure 15

Hence we need a much more subtle invocation of the coarea alternative. What we failed to do, is to exploit the extremely good control we have on bulk energy. Recall, we bounded the coarea integral \( \int_{v(S)} J(x)|D\Theta^i(x)|dL^2x \) for \( i = 1,2 \) from above by the surface energy. We did this by considering the pullbacks of the integral curves and we obtained a picture like fig 5. The point being somehow that if the bulk energy is sufficiently small we can chose the line \( (z + \langle \phi_1 \rangle) \) for which \( \int_{z+\langle \phi_1 \rangle} d(x)dH^1x \) is small but \( \int_{z+\langle \phi_1 \rangle} J(x)|D\Theta^1(x)|dH^1x \) is not small, to be very close to the line \( (a + \langle \phi_1 \rangle) \). So all the oscillation we pick up from the argument is concentrated in a thin strip around \( (a + \langle \phi_1 \rangle) \). This leads us naturally to the idea of considering the coarea integral in a thin strips parallel to \( \phi \), running through \( S \). As shown in fig 15.
Let \( \{ C_i^1 \} \) denote the set of strips, width \( \kappa^{m_0} \epsilon \) going through \( S \) in direction \( \phi_i \) and let \( \Theta_i^1 \) denote the level set function defined in each strip, then we have \( \sum_k (\kappa \epsilon)^{-1} \int_{v(C_i^1)} J(x) \left| D\Theta_i^1(x) \right| dL^2 x \leq \kappa \epsilon \). So “on average” we can except to have \((\kappa \epsilon)^{-1} \int_{v(C_i^1)} J(x) \left| D\Theta_i^1(x) \right| dL^2 x \leq \kappa^{m_0} \kappa \epsilon \). Thus we can find many integral curves in \( v(C_i^1) \) with.

\[
\int_{\Theta_i^1 = (1 - \epsilon) \cap w(C_i^1)} J(x) \ dH^1 x \leq \kappa^{m_0} \kappa \epsilon. \tag{130}
\]

This gives us very good control over the short length of our little integral curves. Note we get better and better control by taking more and columns and the only thing we need to take more columns is lower bulk energy. This is how we exploit our control on bulk energy. So for any subskewcube \( S_{k,j} \subset C_i^1 \cap C_j^2 \) we have many integral curves with respect to both \( \Theta_i^1 \) and \( \Theta_j^2 \) for which (130) is true.

Now we argue as indicated in the introduction. Lemma 6 says that the pullback of the integral curves with respect to \( \Theta_i^1 \) must look very much like laminates whose interfaces (in the reference configuration) are parallel to \( \phi_i \) for \( i = 1, 2 \). So \( v|_S \) must look very much like a laminate with respect to both \( \phi_1 \) and \( \phi_2 \) and the only way this can happen is if \( v|_S \approx R_1 H \) for some \( R_1 \in SO(2) \) or \( v|_S \approx R_2 \) for some \( R_2 \in SO(2) \). So we have very good control on a large number of subskewcubes inside our subsube \( S \), by using this in combination with smallness of bulk and surface energy, we will in Lemma 9 show that for a triangle \( \tau \) contained in \( S \), the linear part of the affine interpolation of \( v \) on \( \tau \) (denoted by \( L \)) will be such that \( d(L, SO(2) \cup SO(2) H) < \kappa^{m_0} \epsilon \) where \( m_0 \) is some large integer depending on bulk energy. By inserting this “strengthened” “coarea alternative” into the calculation (129) we see that we obtain unrealistic upper bounds on the scaling of the finite element approximation. This is how the coarea alternative works.

**Proposition 1.** Given skewcube \( S := P(a, \phi_1, \phi_2, \kappa \epsilon) \subset \Omega \).

Assume we have:

\[
\int_S d(Dv(x), K) dL^2 x \leq \kappa^{m_0} + \epsilon^2. \tag{131}
\]

- Let \( \{ C_k^{(p)} : k \in \{1, \ldots, [\kappa^{m_0}] + 1 \} \} \) denote the set of columns width \( \kappa^{m_0} \epsilon \) going through \( S \), parallel to \( \phi_p \).
- Let \( a_k^{(p)} \) denote the center point in \( C_k^{(p)} \). Let \( \Theta_k^{(p)} \) denote the level set function defined with respect to the line \( \{ a_k^{(p)} + \langle \phi_k \rangle \} \). Let \( E_k^{(p)} = N_{\epsilon \kappa^{m_0} \epsilon} [C_k^{(p)}] \cap S \) for \( k = 1, 2, \ldots, [\kappa^{m_0}] + 1 \).

From (131), for each \( p \in \{1, 2\} \) we can find a distinct set of numbers \( \{ k_1^p, \ldots, k_{Q_0}^p \} \subset \{1, \ldots, [\kappa^{m_0}] \} \) with \( Q_0 \geq (1 - \kappa^{-m_0}) [\kappa^{m_0}] \) and

\[
\int_{v(E_{j}^{(p)})} J(x) \ dL^2 x \leq \kappa^{3m_0 + 7} \epsilon^2
\]

for each \( j \in \{1, \ldots, Q_0 \} \).

We assume we have the following inequalities

\[
\sum_{j=1}^{Q_0} \int_{v(E_{j}^{(p)})} J(x) \left| D\Theta_j^{(p)} \right| dL^2 x \leq \kappa^{m_0 + 1} \epsilon^2 \tag{132}
\]

for \( p = 1 \) and \( p = 2 \).

\[
\int_S \left| D^2 v(x) \right| dL^2 x < \epsilon \kappa.
\]

then the following statement holds true:

Let

\[
\{ \Xi_{i,j} := P(a_{i,j}, \phi_1, \phi_2, \kappa^{m_0} \epsilon) : i,j \in \{1, 2, \ldots, [\kappa^{m_0}] + 1\} \}
\]
be a set of pairwise disjoint skewcubes such that \( S \subset \cup_{i \in \{1, \ldots, [k^{-m_0}] + 1\}} S_{i,j} \). Let 
\[
S_{i,j} := P(a_{i,j}, \phi_1, \phi_2, c_k e^{m_0} \epsilon)
\]
for some constant \( c_k > 1 \) we will decide on later.

There exists a set \( G_0 \subset \{S_{i,j} : i, j \in \{1, \ldots, [k^{-m_0}] + 1\}\} \) such that

\[
L^2 \left\{ x \in S_{i,j} : d(Dv(x), R_{i,j} T_{i,j}) > \bar{\kappa} \right\} < 20\sigma^{-8} \epsilon \bar{c}_k^2 \bar{\kappa} \epsilon \epsilon (e^{m_0})^2
\]

for some \( R_{i,j} \in SO(2) \), \( T_{i,j} \in \{Id, H\} \).

\[
\text{Card} (G_0) \geq \frac{1 - 16\sigma^2 \epsilon \bar{\kappa}}{\kappa^{2m_0}}
\]

Before proving this we need to prove a number of elementary Lemmas first.

### 7.1. Integral curves in a controlled subskewcube must run parallel.

This lemma is the essential step in showing that a controlled subskewcube (i.e., a subskewcube \( S_{k_1, k_2} \subset C_{k_1} \cap C_{k_2} \)) for columns \( C_{k_1}, C_{k_2} \) such that \( \int_{C_{k_1}} J(x) |D\Theta_{k_1}^i(x)| \, d\mathbb{L}^2 x \) is small for \( i = 1, 2 \) is such that \( v_{S_{k_1, k_2}} \) is very much like a laminate with respect to both rank-1 directions. Essentially what we show is that integral curves given by level sets of the form \( \Theta_{k_1}^{i-1}(t_1) \) and \( \Theta_{k_1}^{i-1}(t_2) \) are roughly parallel. The proof is more or less a calculation. We know that if we consider the pullback of an integral curve then (by Lemma 6) for most points \( x \in v^{-1} (\Theta_{k_1}^i(t_1)) \), \( Dv(x) \phi_1 \) points in the clockwise normal direction to \( \Theta_{k_1}^i(t) \) (recall \( \Theta_{k_1}^i(t) \) is very much close to being a line). Let a denote the center of the skewcube. We chose \( t_1, t_2 \in \{a + \langle \phi_1 \rangle\} \) and \( t_3 \in \{a + \langle \phi_2 \rangle\} \) such that \( \Theta_{k_2}^2(t_3) \) crosses \( \Theta_{k_1}^i(t_1), \Theta_{k_1}^i(t_2) \). It if happens that the intersection points \( v^{-1} (\Theta_{k_2}^2(t_3) \cap \Theta_{k_1}^i(t_1)) \) and \( v^{-1} (\Theta_{k_2}^2(t_3) \cap \Theta_{k_1}^i(t_2)) \) are such that \( Dv(\cdot) \) at these points lie close to different components of the wells (i.e., \( Dv(v^{-1} (\Theta_{k_2}^2(t_3) \cap \Theta_{k_1}^i(t_1))) = SO(2) \) and \( Dv(v^{-1} (\Theta_{k_2}^2(t_3) \cap \Theta_{k_1}^i(t_2))) = SO(2) H \) or vice versa) by the fact that the angle between the normals to the lines \( \Theta_{k_2}^2(t_3) \) and \( \Theta_{k_1}^i(t_1) \) is roughly the same as the angle between \( Dv(\cdot) \phi_1 \) and \( Dv(\cdot) \phi_2 \) at this intersection point, and this is in turn prescribed by which component of the wells \( Dv(\cdot) \) is in, so the intersection points belonging to different components means that the angle of the lines \( \Theta_{k_2}^2(t_3) \) and \( \Theta_{k_1}^i(t_1) \) at their intersection point will be radically different from the angle of the lines \( \Theta_{k_2}^2(t_3) \) and \( \Theta_{k_1}^i(t_2) \) at their intersection point. Hence the lines \( \Theta_{k_1}^i(t_1) \) and \( \Theta_{k_2}^2(t_2) \) will be so radically non-parallel that (assuming we chose \( t_1, t_2 \) close enough to \( a \)) \( \Theta_{k_1}^i(t_1) \cap \Theta_{k_1}^i(t_2) \neq \emptyset \). This is a contradiction and so the intersection points must be near the same component of the wells. Given this fact, almost exactly the same argument implies that the angle between the lines \( \Theta_{k_2}^2(t_3) \), \( \Theta_{k_1}^i(t_1) \) is very close to the angle between the lines \( \Theta_{k_2}^2(t_3) \) and \( \Theta_{k_1}^i(t_2) \) and this means \( \Theta_{k_2}^2(t_2) \) is almost parallel to \( \Theta_{k_1}^i(t_2) \).

**Lemma 7.** Let \( v \in A_\sigma(\Omega) \). Given skew cube \( S := P(a, \phi_1, \phi_2, c_\epsilon w) \) with the following properties:

- \( S \) is contain in a skew rectangles \( R_i := \tilde{\mathbb{F}}(a, c_\epsilon w \phi_1, r_1 \phi_2) \subset \Omega \) and \( R_2 := \tilde{\mathbb{F}}(a, r_2 \phi_0, c_\epsilon w \phi_2) \subset \Omega \) with \( \frac{\bar{\kappa}}{\sigma} < \sigma^2 \) for \( i = 1, 2 \) and \( c_\epsilon \) is some constant bigger than \( c_\epsilon_0 \).

- We have a level set function \( \Theta_{k_1}^i : R_i \to \mathbb{R} \) for \( i = 1, 2 \) such that if we let 

\[
G_i := \left\{ t \in \{a + \langle \phi_i \rangle\} : \int_{\Theta_{k_1}^{i-1}(t) \cap R_i} J(x) \, dH^1 x \leq \alpha \epsilon \right\}
\]

we have

\[
L^1 \left( \{a + \langle \phi_i \rangle\} \cap B_{\frac{\bar{\kappa}}{\sigma}}(a) \setminus G_i \right) \leq \alpha \epsilon \quad \text{w}.
\]

\[
\int_{\tilde{\mathbb{F}}(S)} d(Dv(x), SO(2) \cup SO(2) H) \, dL^2 x \leq \alpha^3 \epsilon^2.
\]

The following holds true:
• Firstly recall by Lemma 5 we have that for each \( t \in G_i \), let \( e_t \) be the first point (going forward in time) to hit \( \partial R \) and \( s_t \) be the first point (going backward in time) to hit \( \partial R \). Let \( U_t \) be the connected subset subset of \( \Theta_i^{-1}(t) \) between \( e_t \) and \( s_t \) then we have for some \( t_i \in G(1,2) \)
\[
U_t \subset N_{c_i \sqrt{\sigma}} (l_t + v(t)).
\]

• Let \( D_t := N_{\frac{\alpha}{\sigma} \sqrt{\pi}} (l_t + v(t)) \cap R \). As before, we define the clockwise normal to \( l_t \) by \( w_t := R^* \frac{e_t - s_t}{|e_t - s_t|} \)

where \( e_t \in (l_t + v(t)) \cap B_{\sqrt{\sigma} w} (e_t) \), \( s_t \in (l_t + v(t)) \cap B_{\sqrt{\sigma} w} (s_t) \) and \( R^* \) is a clockwise rotation by \( \frac{\pi}{2} \).

There exists a set \( C_t \subset D_t \) such that
\[
L^2 (D_t \setminus C_t) \leq \sigma^{-6} \xi_3 \alpha \frac{\lambda}{\sqrt{\pi}} w^2
\]

and for any \( x \in C_t \) we have
\[
|Dv \left( v^{-1}(x) \right) \phi_i - w_t | \leq 128 \xi_4 \sigma^{-5} \alpha \frac{\lambda}{\sqrt{\pi}}.
\]

Secondly for any two points \( t_1, t_2 \in G_1 \cap B \left( a, \frac{w}{\sigma} \right) \) and \( t_3 \in G_2 \cap B \left( a, \frac{w}{\sigma} \right) \) if we let \( \theta_1 \in \Theta_i^{-1} (t_1) \cap \Theta_j^{-1} (t_3) \) and \( \theta_2 \in \Theta_i^{-1} (t_2) \cap \Theta_j^{-1} (t_3) \) then we can find \( \mathcal{S} \in \{ H, I \} \) such that

- \[
L^2 \left( \left\{ x \in B_{\frac{\alpha}{\sigma} \sqrt{\pi}} (\theta_i) : Dv (z) \notin N_{\sqrt{\sigma}} (SO(2) \mathcal{S}) \right\} \right) \leq 4 \sigma^{-6} \xi_4 \alpha \frac{\lambda}{\sqrt{\pi}} w^2,
\]

for \( i = 1, 2 \).

- For any two points \( t_1, t_2 \in G_1 \cap B \left( a, \frac{w}{\sigma} \right) \) we have
\[
|w_{t_1} - w_{t_2} | \leq 2048 \xi_4 \sigma^{-6} \alpha \frac{\lambda}{\sqrt{\pi}}.
\]

Proof. To begin with we assume \( \xi_6 > \sigma^{-7} \) so we have \( B_{\alpha^-} v (a) \subset v(S) \). This gives us some room to work in.

Step 1.
For \( k \in \{ 1, 2 \} \), let
\[
C_k := \left\{ y \in N_{\frac{\alpha}{\sigma} \sqrt{\pi}} (v(t_k) + l_{t_k}) \cap B_{\frac{\alpha}{\sigma} \sqrt{\pi}} (v(a)) : \left| Dv \left( v^{-1}(y) \right) \phi_i - w_{t_k} \right| < 128 \sigma^{-5} \xi_4 \alpha \frac{\lambda}{\sqrt{\pi}} \right\},
\]

we will show that
\[
L^2 \left( N_{\frac{\alpha}{\sigma} \sqrt{\pi}} (v(t_k) + l_{t_k}) \setminus C_k \right) \leq \sigma^{-6} \xi_4 \alpha \frac{\lambda}{\sqrt{\pi}} w^2.
\]

First by (133) we can pick a chain of points
\[
\{ z^k_n : n = 1, 2, \ldots N_0 \} \subset G_1 \cap B_{\frac{\alpha}{\sigma} \sqrt{\pi}} (a)
\]
such that
\[
B_{\frac{\alpha}{\pi}} (a) \cap \{ a + \langle \phi_1 \rangle \} \subset \bigcup_{n=1}^{N_0} B_{\sqrt{\sigma} w} (z^k_n) \cap \{ a + \langle \phi_1 \rangle \},
\]

Note \( N_0 \leq \frac{\alpha \pi \sqrt{\sigma} w}{\sigma \alpha^{\pi} \sqrt{\pi}} = \sigma^{-6} \alpha^{-\pi} \). By Lipschitzness for \( v \), in particular the fact that \( \text{Lip} \left( v \right) \leq \sigma^{-2} \) we have
\[
B_{\frac{\alpha}{\pi}} (v(a)) \cap v \{ a + \langle \phi_1 \rangle \} \subset v \left( B_{\frac{\alpha}{\sigma} \sqrt{\pi}} (a) \cap \{ a + \langle \phi_1 \rangle \} \right)
\]
\[
\subset \bigcup_{n=1}^{N_0} v \left( B_{\sqrt{\sigma} w} (z^k_n) \cap \{ a + \langle \phi_1 \rangle \} \right)
\]
\[
\subset \bigcup_{n=1}^{N_0} B_{\sqrt{\sigma} w} (v(z^k_n)) \cap v \{ a + \langle \phi_1 \rangle \}.
\]

Now as \( B_{\sqrt{\sigma} w} (v(a)) \subset v \left( P \left( a, \phi_1, \phi_2, \frac{\alpha}{\sqrt{\pi}} \right) \right) \subset v(S) \) we consider the integral curves given by
\[ \left\{ \Theta_1^{a-1} (z^k_n) \cap B_{w/\sigma} (v (a)) : n = 1, 2, \ldots N_0 \right\}. \]

We know that this set is disjoint by uniqueness of solutions of ODE and of course by Lemma 5 we have
\[ \Theta_1^{a-1} (z^k_n) \cap B_{w/\sigma} (v (a)) \subset N_{c\sqrt{w}} \left( v (z^k_n) + l_{z^k_n} \right). \quad (135) \]

Now as can be seen from fig 17.

\[ \left\{ v (z^k_{N_0}) + l_{z^k_{N_0}} \right\} \cap B_{w/2\sigma} (v (a)) \cap \left( \left\{ v (z^k_1) + l_{z^k_1} \right\} \cap B_{w/2\sigma} (v (a)) \right) = \emptyset, \quad (136) \]

since otherwise by (135) and the fact that \( |v (z^k_1) - v (z^k_{N_0})| > \sigma^2 \alpha \pi w \) we have
\[ \left( \Theta_1^{k-1} (z^k_1) \cap B_{w/\sigma} (v (a)) \right) \cap \left( \Theta_1^{k-1} (z^k_{N_0}) \cap B_{w/\sigma} (v (a)) \right) = \emptyset \quad (137) \]

and this is a contradiction.
Now since we have (136), as can be seen from fig 17, for any point \( y \in \{ v(z_1^k) + l_z \} \cap B_{w_{z_0}}(v(a)) \) we have
\[
\frac{\alpha \frac{\pi}{4} w}{2} < \frac{|v(z_1^k) - v(z_{N_0}^k)|}{2} < d(y, \{ v(z_{N_0}^k) + l_z \}) \cap B_{w_{z_0}}(v(a)) \leq 2 |v(z_1^k) - v(z_{N_0}^k)| < 4 \alpha \frac{\pi}{4} w. \tag{138}
\]

Now in the same way as (136), since \(|v(z_m^k) - v(z_{m+1}^k)| \leq \sqrt{\pi} \sigma^2 w\), for \( m \in \{ 1, 2, \ldots N_0 - 1 \} \) and for any \( y \in \{ v(z_m^k) + l_z \} \cap B_{w_{z_0}}(v(a)) \) we have
\[
d(y, \{ v(z_m^k) + l_z \}) \cap B_{w_{z_0}}(v(a)) < \sigma^{-2} |v(z_m^k) - v(z_{m+1}^k)| < \sqrt{\frac{\pi}{4} w}, \tag{139}
\]
since otherwise we will have that
\[
(\Theta_1^{-1}(z_m^k) \cap B_{w_{z_0}}(v(a))) \cap (\Theta_1^{-1}(z_{m+1}^k) \cap B_{w_{z_0}}(v(a))) \neq 0.
\]

And again in the same way as (136) for any \( y \in \{ v(z_m^k) + l_z \} \cup \{ v(z_{N_0}^k) + l_z \} \cap B_{w_{z_0}}(v(a)) \) we have
\[
\frac{\alpha \frac{\pi}{4} w}{4} < \frac{1}{2} \min \{|v(z_1^k) - v(a)|, |v(z_{N_0}^k) - v(a)|\} < d(y, \{ v(t) + l_t \} \cap B_{w_{z_0}}(v(a))).
\]

Thus the set \( N \frac{\alpha \frac{\pi}{4} w}{4} (v(t) + l_t) \cap B_{w_{z_0}}(v(a)) \) is contained in the region of \( B_{w_{z_0}}(v(a)) \) between the two lines \( \{ v(z_m^k) + l_z \} \cap B_{w_{z_0}}(v(a)) \) and \( \{ v(z_{N_0}^k) + l_z \} \cap B_{w_{z_0}}(v(a)) \).

Now (139) implies that for any \( m \in \{ 1, 2, \ldots N_0 - 1 \} \) we have
\[
(v(z_m^k) + l_z) \cap B_{w_{z_0}}(v(a)) \subset N \frac{\alpha \frac{\pi}{4} w}{4} (v(z_m^k) + l_z) \cap B_{w_{z_0}}(v(a)). \tag{140}
\]

As any point \( z \in N \frac{\alpha \frac{\pi}{4} w}{4} (v(t) + l_t) \cap B_{w_{z_0}}(v(a)) \) is either on line \( \{ v(z_m^k) + l_z \} \cap B_{w_{z_0}}(v(a)) \) for \( k = 1, \ldots N_0 \) or lies between two such lines. So from (140) we have
\[
N \frac{\alpha \frac{\pi}{4} w}{4} (v(t) + l_t) \cap B_{w_{z_0}}(v(a)) \subset \bigcup_{m=1}^{N_0} N \frac{\alpha \frac{\pi}{4} w}{4} (v(z_m^k) + l_z) \cap B_{w_{z_0}}(v(a)) \cap B(a, w_{z_0}). \tag{141}
\]

For each \( m \in \{ 1, 2, \ldots N_0 \} \) let \( w_m := w(z_m^k) \) be the clockwise normal to \( l_z \). Let \( \mathcal{A}_m := N \frac{\alpha \frac{\pi}{4} w}{4} (v(z_m^k) + l_z) \cap R \). By Lemma 6 we know that there exists a set \( B_m \subset \mathcal{A}_m \) such that \( L^2(\mathcal{A}_m \setminus B_m) \leq c_4 \alpha \frac{\pi}{4} w \) and for any \( x \in B_m \) we have \( |Dv(v^{-1}(x)) \phi_t - w_m| \leq c_4 \sqrt{\alpha} \).

Now we can see from the fig 18.

The difference in angle between \( w_m \) and \( w_{m_2} \) for any \( m_1, m_2 \in \{ 1, 2, \ldots N_0 \} \) is less than \( 2 \tan^{-1}\left(16 \sigma^{-5} \alpha \frac{\pi}{4} w\right) \) so we must have \( |w_{m_1} - w_{m_2}| \leq 64 \sigma^{-5} \alpha \frac{\pi}{4} w \).
So by (141) if we let \( C_k := \left\{ y \in N_{\frac{16}{16w^4}} (v(t_k) + l_k) \cap B_{\frac{w^4}{16}} (v(a)) : |Dv(v^{-1}(y)) \phi_t - w_k| \leq 128 \varepsilon_4 \sigma^{-5} \alpha^{\frac{1}{16}} \right\} \)

we see

\[ N_{\frac{16}{16w^4}} (v(t_k) + l_k) \setminus C_k \subset \bigcup_{m=1}^{N_0} A_m \setminus B_m. \]

Thus

\[
L^2 \left( N_{\frac{16}{16w^4}} (v(t_k) + l_k) \setminus C_k \right) \leq N_0 \varepsilon_4 \alpha^{\frac{1}{16}} w^2 \\
\leq \sigma^{-6} \varepsilon_4 \alpha \pi^2 w^2. \tag{142}
\]

**Step 2.**

Firstly we note that from the fact we established in Lemma 6, namely that path \( v^{-1} (\Theta^{-1}_a (t)) \cap R \) has its tangents mostly in directions \( n_i \) and \( \hat{o}_i \). We can see from the figure 19, for \( t_1, t_2 \in G_1 \cap B_{\frac{w}{\varepsilon_4}} (a) \) and point \( t_3 \in G_2 \cap B_{\frac{w}{\varepsilon_4}} (a) \) the points given by

\[ \theta_1 \in \Theta^{-1}_a (t_1) \cap \Theta^{-1}_a (t_2) \quad \text{and} \quad \theta_2 \in \Theta^{-1}_a (t_2) \cap \Theta^{-1}_a (t_3) \]

are such that \( v^{-1} (\theta_1), v^{-1} (\theta_1) \in B_{\frac{w}{\varepsilon_4}} (a) \).

![Figure 19](image19)

So by Lipschitzness we have

\[ \theta_1, \theta_2 \in B_{\frac{w}{\varepsilon_4}} (v(a)). \tag{143} \]

Observe the figure 20.

![Figure 20](image20)
Now as \( \theta_1 \in N_{\sqrt{\sigma}w} (l_{t_1} + v(t_1)) \cap N_{\sqrt{\sigma}w} (l_{t_3} + v(t_3)) \) and as the angle between lines \( l_{t_1} \) and \( l_{t_3} \) can not be too sharp (by 143) if we let \( \tilde{\theta}_1 := (v(t_1) + l_{t_1}) \cap (v(t_3) + l_{t_3}) \) then we have \( |\tilde{\theta}_1 - \theta_1| < c_1 \sqrt{\sigma} w \).

Similarly if we let \( \tilde{\theta}_2 := (v(t_3) + l_{t_2}) \cap (v(t_2) + l_{t_2}) \) we have \( |\tilde{\theta}_2 - \theta_2| < c_1 \sqrt{\sigma} w \). So

\[
B_{\frac{1}{\sqrt{\sigma}w}} (\tilde{\theta}_1) \subset \left( N_{\frac{1}{\sqrt{\sigma}w}} (l_{t_1} + v(t_1)) \cap B_{\frac{1}{\sqrt{\sigma}w}} (a) \right) \cap \left( N_{\frac{1}{\sqrt{\sigma}w}} (l_{t_3} + v(t_3)) \cap B_{\frac{1}{\sqrt{\sigma}w}} (a) \right)
\]

and

\[
B_{\frac{1}{\sqrt{\sigma}w}} (\tilde{\theta}_2) \subset \left( N_{\frac{1}{\sqrt{\sigma}w}} (l_{t_2} + v(t_2)) \cap B_{\frac{1}{\sqrt{\sigma}w}} (a) \right) \cap \left( N_{\frac{1}{\sqrt{\sigma}w}} (l_{t_2} + v(t_3)) \cap B_{\frac{1}{\sqrt{\sigma}w}} (a) \right).
\]

So by (142) we have

\[
L^2 \left( B_{\frac{1}{\sqrt{\sigma}w}} (\tilde{\theta}_1) \setminus (C_1 \cup C_3) \right) \leq 2\sigma^{-6} \tilde{c}_4 \alpha^\frac{3}{2} \pi w^2
\]

and

\[
L^2 \left( B_{\frac{1}{\sqrt{\sigma}w}} (\tilde{\theta}_2) \setminus (C_2 \cup C_3) \right) \leq 2\sigma^{-6} \tilde{c}_4 \alpha^\frac{3}{2} \pi w^2.
\]

Now by assumption (134) we can find sets; \( F_1 \subset B_{\frac{1}{\sqrt{\sigma}w}} (\tilde{\theta}_1) \cap C_1 \cap C_3 \) such that

\[
L^2 (F_1) \geq \frac{\pi}{2} \left( \frac{a \pi \sigma w}{4} \right)^2 \left( 1 - 64\sigma^{-6} \tilde{c}_4 \alpha^\frac{3}{2} \pi \right)
\]

and for any \( z \in F_1 \) we have \( Dv (v^{-1} (z)) \in N_{\sqrt{\sigma}} (SO(2) \cup SO(2) H) \). In the same way we can find \( F_2 \subset B_{\frac{1}{\sqrt{\sigma}w}} (\tilde{\theta}_2) \cap C_2 \cap C_3 \) such that \( L^2 (F_2) \geq \frac{\pi}{2} \left( \frac{a \pi \sigma w}{4} \right)^2 \left( 1 - 64\sigma^{-6} \tilde{c}_4 \alpha^\frac{3}{2} \pi \right) \) and for any \( z \in F_2 \) we have \( Dv (v^{-1} (z)) \in N_{\sqrt{\sigma}} (SO(2) \cup SO(2) H) \).

We will show if we have a point \( z_1 \in F_1 \) such that \( Dv (v^{-1} (z_1)) \in N_{\sqrt{\sigma}} (SO(2)) \) and \( z_2 \in F_2 \) such that \( Dv (v^{-1} (z_2)) \in N_{\sqrt{\sigma}} (SO(2) H) \) we get a contradiction from the fact that \( \alpha w_t \) and \( \alpha w_2 \) (the orientations of \( l_{t_1} \) and \( l_{t_2} \) respectively) must point in the same direction.

Formally: we will show that for some \( \mathcal{G} \in \{ H, Id \} \) we have

\[
\{ Dv (v^{-1} (z)) : z \in F_1 \cup F_2 \} \subset N_{\sqrt{\sigma}} (SO(2) \mathcal{G}) \text{.} \tag{144}
\]

Before we do so we will have to establish some things about \( \alpha w_1 \) (the clockwise normal of line \( l_{t_1} \)) and \( \alpha w_2 \) (the clockwise normal of line \( l_{t_2} \)).

Step 3 We will show \( \alpha w_1, \alpha w_2 \in \left[ \frac{4}{3}, 1 \right] \).

Firstly we note that since we can run the ODE all the way to the boundary of \( S, \) as \( |t_1 - t_2| < \frac{\pi}{\sigma} \) and

\[
(\Theta_1^{-a} (t_1) \cap v(S)) \cap (\Theta_2^{-a} (t_2) \cap v(S)) = \emptyset
\]

assuming the constant \( c_6 \) has been chosen big enough, the lines \( l_{t_1} \) and \( l_{t_2} \) must be roughly parallel, see figure 21.

\[\text{Figure 21}\]

Now we consider the pullback of lines \( l_{t_1}, l_{t_2} \) in the reference. See figure 22. By bilipschitzness we know
So we can find a point $y_0 \in \{a + \phi_1 \} \cap B_{\frac{-1}{w}}(a)$ such that

$$L^1 \left( \left\{ z \in N_{\alpha + \frac{1}{w}} \left( v^{-1}(t_k) \cap B_{\frac{-1}{w}}(a) \right) : |Dv(y) \phi_1 - w_k| > 128\epsilon_4 \sigma^{-5} \alpha \right\} \right) \leq \sigma^{-\frac{8}{5}} \epsilon_4 \omega^2.$$

And by Step 1 or (142)

$$L^2 \left( \left\{ z \in N_{\alpha + \frac{1}{w}} \left( v^{-1}(t_k) \cap B_{\frac{-1}{w}}(a) : |Dv(y) \phi_1 - w_k| > 128\epsilon_4 \sigma^{-5} \alpha \right\} \right) \leq \sigma^{-\frac{8}{5}} \epsilon_4 \omega^2.$$

So we can find a point $y_0 \in \{a + \phi_1 \} \cap B_{\frac{-1}{w}}(a)$ such that

$$L^1 \left( \left\{ z \in N_{\alpha + \frac{1}{w}} \left( v^{-1}(t_k) \cap B_{\frac{-1}{w}}(a) \right) : |Dv(y) \phi_1 - w_k| > 128\epsilon_4 \sigma^{-5} \alpha \right\} \right) \leq \sigma^{-\frac{8}{5}} \epsilon_4 \omega^2$$

for $k = 1, 2$.

Let

$$\Upsilon_k := N_{\alpha + \frac{1}{w}} \left( v^{-1}(t_k) \cap B_{\frac{-1}{w}}(a) \right) \cap (y_0 + \phi_1)$$

for $k = 1, 2$ and let

$$\tilde{\Upsilon}_k := \left\{ y \in \Upsilon_k : |Dv(y) \phi_1 - w_k| < 128\epsilon_4 \sigma^{-5} \alpha \right\}$$

for $k = 1, 2$. In words; for any $z_1 \in \tilde{\Upsilon}_1$ we know that $w_{t_1}$ is (approximately) equal to $Dv(z_1) \phi_1$ and for any $z_2 \in \tilde{\Upsilon}_2$ we have that $w_{t_2}$ is (approximately) equal to $Dv(z_2) \phi_1$. And $L^1 \left( \Upsilon_k \setminus \tilde{\Upsilon}_k \right) \leq \sigma^{-\frac{8}{5}} \epsilon_4 \omega^2$.

So as $l_{t_1}$ and $l_{t_2}$ are roughly parallel we have (for big enough constant $c_1$) we have $w_{t_1} \cdot w_{t_2} \in \left[ \frac{4}{5}, 1 \right]$ or $w_{t_1} \cdot w_{t_2} \in \left[ -1, -\frac{4}{5} \right]$. Recall we want to show $w_{t_1} \cdot w_{t_2} \in \left[ \frac{4}{5}, 1 \right]$. Suppose not; so $w_{t_1} \cdot w_{t_2} \in \left[ -1, -\frac{4}{5} \right]$.

As $Dv(z) \phi_1$ is the tangent to the line $v \left( \{ y_0 + \phi_1 \} \cap S \right)$ at point $v(z)$ we have that $v \left( \Upsilon_k \right)$ (which is a connected segment of $v \left( \{ y_0 + \phi_1 \} \cap S \right)$) has for most of its points, a tangent pointing roughly in direction $w_{t_2}$.

Formally, we can prove (just by considering the integral $v(z) - v(y_0) = \int_{y_0}^{z} Dv(x) \phi_1 dL^1 x$) that if we let $\xi_k := v^{-1}(l_{t_k}) \cap \{ y_0 + \phi_1 \}$ then

$$H \left( v \left( \Upsilon_k \right), v(\xi_k) - \frac{\sigma^2 \alpha w \cdot w_{t_2}}{4} v(\xi_k) + \frac{\sigma^2 \alpha w \cdot w_{t_2}}{4} \right) \leq c_2 \alpha \omega^2.$$

(145)
More important however is that for \( z_1 \in \tilde{\Upsilon}_1 \) and \( z_2 \in \tilde{\Upsilon}_2 \) we have that \( Dv(z_1) \phi_1 \) and \( Dv(z_2) \phi_1 \) point in roughly opposite directions. The only way this can happen is if \( v((a + \langle \phi_1 \rangle) \cap S) \) “turns around” by \( \pi \) as shown on fig 23.

Now let \( e_1^{(2)} \) and \( e_2^{(2)} \) be the endpoints of \( \Upsilon_2 \) as shown, from (145) we have that \( N_{\sqrt{\sigma_w}}(l_{t_2}) \) passes in between \( v \left( e_1^{(2)} \right) \) and \( v \left( e_2^{(2)} \right) \). Let \( \Sigma := v \left[ [e_1^{(2)}, t_1] \right] \). Its easy to see that

\[
P_{t_{t_2}} \left( [v \left( e_1^{(2)} \right), v \left( e_2^{(2)} \right)] \right) \subset P_{t_{t_2}} (\Sigma)
\]

and so its clear that \( N_{\sqrt{\sigma_w}}(l_{t_2}) \) must pass through both \( v(\Upsilon_k) \) and \( \Sigma \) which implies

\[
\Theta_1^{-1} (t_2) \cap B \left( a, \frac{w}{\sigma^k} \right) \cap v(\Upsilon_k) \neq \emptyset
\]

and

\[
\Theta_0^{-1} (t_2) \cap B \left( a, \frac{w}{\sigma^k} \right) \cap \Sigma \neq \emptyset.
\]

By Lemma 1 \( \Theta^{-1} (t_2) \) can only pass through \( v((y_0 + \langle \phi_1 \rangle) \) once so this is a contradiction. Thus we have finally established that \( w_{t_1}, w_{t_2} \in \left[ \frac{4}{7}, 1 \right] \).

Before continuing on our mission to establish (144) we note the following. If \( \theta_1 \) denotes the angle between \( \phi_1 \) and \( \phi_2 \) then the angle between \( H \phi_1 \) and \( H \phi_2 \) is given by \( \pi - \theta_1 \). This can be seen either by direction calculation or by noting that since \( detH = 1 \) and \( |H \phi_1| = |H \phi_2| = 1 \) a parallelogram with sides parallel to \( \phi_1, \phi_2 \) must be sent to parallelogram with the same volume and same side length and hence the same pair of internal angles.

Now we can proceed with the proof of (144). See fig 24.

We start with point \( z_1 \). Now we know \( Dv^{-1}(z_1) \approx R_0 \) for some \( R_0 \in SO(2) \). Since \( z_1 \in C_1 \) we know \( Dv^{-1}(z) \phi_1 \approx R_0 \phi_1 \) points (roughly) in the direction to \( w_{t_1} \) as shown. Similarly since \( z \in C_3 \), \( Dv^{-1}(z) \phi_2 \approx R_0 \phi_2 \) points (roughly) in the direction \( w_{t_3} \). So the angle between lines \( l_{t_1} \) and \( l_{t_3} \) at the intersection point is approximately the angle between \( \phi_1 \) and \( \phi_2 \).

Now we go to point \( z_2 \). We have \( Dv^{-1}(z_2) \approx R_1 H \) for some \( R_1 \in SO(2) \). As \( z_2 \in C_3 \) we have \( Dv^{-1}(z_2) \phi_2 \approx R_2 H \phi_2 \) points in the direction \( w_{t_3} \) as shown. And as \( z_2 \in C_2 \) we should have that
$Dv(v^{-1}(z))$ should point in the direction $w_2$, however as the action of $H$ on $\phi_1$ and $\phi_2$ is to stretch them apart so that $H\phi_1$ and $H\phi_2$ meet at angle of $\pi - \theta_1$, as we can see from the diagram $H\phi_1$ points in the opposite direction to $w_2$, so this is a contradiction.

In an identical way we get a contradiction from the possibility that $z_1 \in F_1$ with $Dv(v^{-1}(z_1)) \in N_{\sqrt{\alpha}}(SO(2)H)$ and $z_2 \in F_2$ with $Dv(v^{-1}(z_2)) \in N_{\sqrt{\alpha}}(SO(2))$. So there exists $\varnothing \in \{Id, H\}$ such that

$$Dv(v^{-1}(z)) \in SO(2) \varnothing$$

for each $z \in F_1 \cup F_2$.

This completes the proof of the first part of the lemma.

Now we establish the second part of the lemma. See Fig 25.

By the first part of the lemma $Dv(v^{-1}(z_1)) \in B_{\sqrt{\alpha}}(R_0)$ for some $R_0 \in SO(2)$ and $Dv(v^{-1}(z_2)) \in B_{\sqrt{\alpha}}(R_1)$ for some $R_1 \in SO(2)$. 
Similarly to as before. As \( z_1 \in \mathcal{C}_1 \cap \mathcal{C}_3 \) we have
\[
|Dv\left(v^{-1}(z_1)\right) \phi_1 - w_{t_1}| \leq 128\xi_4\sigma^{-5} \alpha^\frac{\pi}{3}
\]
and
\[
|Dv\left(v^{-1}(z_1)\right) \phi_2 - w_{t_3}| \leq 128\xi_4\sigma^{-5} \alpha^\frac{\pi}{3}.
\]
And so the angle between \( w_{t_1} \) and \( w_{t_3} \) is within \( 512\xi_4\sigma^{-5} \alpha^\frac{\pi}{3} \) of the angle between \( \phi_1 \) and \( \phi_2 \).

Formally; let \( \theta_1 \) be the angle between \( w_{t_1} \) and \( w_{t_3} \) and let \( \theta_2 \) be the angle between \( w_{t_2} \) and \( w_{t_3} \). So we have
\[
|w_{t_1} \cdot w_{t_3} - \phi_1 \cdot \phi_2| \leq |w_{t_1} \cdot (w_{t_3} - R_0 \phi_2)| + |R_0 \phi_2 \cdot (w_{t_1} - R_0 \phi_1)|
\]
\[
\leq |w_{t_1} - Dv\left(v^{-1}(z_1)\right) \phi_2| + |Dv\left(v^{-1}(z_1)\right) \phi_2 - R_0 \phi_2| + |w_{t_1} - Dv\left(v^{-1}(z_1)\right) \phi_1|
\]
\[
+ |Dv\left(v^{-1}(z_1)\right) \phi_1 - R_0 \phi_1|
\]
\[
\leq 512\xi_4\sigma^{-6} \alpha^\frac{\pi}{3}. \tag{146}
\]
In exactly the same way we can see
\[
|w_{t_2} \cdot w_{t_3} - \phi_1 \cdot \phi_2| \leq 512\xi_4\sigma^{-6} \alpha^\frac{\pi}{3}
\]
and so putting things together we get
\[
|(w_{t_1} - w_{t_2}) \cdot w_{t_3}| \leq 1024\xi_4\sigma^{-6} \alpha^\frac{\pi}{3}. \tag{147}
\]
Let \( R^* \) be a rotation by \( \frac{\pi}{2} \) in the clockwise direction, we have
\[
|w_{t_2} \cdot R^* w_{t_3} - \phi_1 \cdot R^* \phi_2| \leq |w_{t_2} \cdot (R^* w_{t_3} - R^* R_0 \phi_2)| + |R^* R_0 \phi_2 \cdot (w_{t_3} - R_0 \phi_1)|
\]
\[
\leq |w_{t_3} - Dv\left(v^{-1}(z_1)\right) \phi_2| + |Dv\left(v^{-1}(z_1)\right) \phi_2 - R_0 \phi_2| + |w_{t_1} - Dv\left(v^{-1}(z_1)\right) \phi_1|
\]
\[
+ |Dv\left(v^{-1}(z_1)\right) \phi_1 - R_0 \phi_1|
\]
\[
\leq 512\xi_4\sigma^{-6} \alpha^\frac{\pi}{3}. \tag{148}
\]
And in the same way we can see \( |w_{t_2} \cdot R^* w_{t_3} - \phi_1 \cdot R^* \phi_2| \leq 512\xi_4\sigma^{-6} \alpha^\frac{\pi}{3} \) so \( |(w_{t_1} - w_{t_2}) \cdot R^* w_{t_3}| \leq 1024\xi_4\sigma^{-6} \alpha^\frac{\pi}{3} \). Together with (147) this implies \( |w_{t_1} - w_{t_2}| \leq 2048\xi_4\sigma^{-6} \alpha^\frac{\pi}{3} \).
7.2. Controlled subskewcubes have derivative mostly in one well.

This next lemma essentially follows from Lemma 6, as most of the integral curves given by \( \{ \Theta_i^{-1}(t) : t \in \mathbb{R} \} \) are straight parallel lines for \( i = 1, 2 \). Given that from Lemma 6 we know that \( Dv(\cdot) \phi_i \) is clockwise the normal to these classes of “lines” for \( i = 1, 2 \), we only have to show that significant subskewcube of our skewcube is contained within a neighborhood of these lines to conclude that for most points \( x \) within this skewcube, the directions of \( Dv(x) \phi_1 \) and \( Dv(x) \phi_2 \) are roughly fixed. So (as a weak conclusion) we have that most points in our subskewcube are such that \( Dv(\cdot) \) remain close to one component of the wells.

**Lemma 8.** Given skew cube \( S := P(a, \phi_1, \phi_2, c_6 w) \) with the following properties:

- \( S \) is contained in skew rectangles \( R_1 := \tilde{S} (a, c_7 w \phi_2, r_1 \phi_1), R_2 := \tilde{S} (a, r_2 \phi_2, c_7 w \phi_1) \) with \( \frac{c_6}{r_i} < c^2 \) for \( i = 1, 2 \) where \( c_7 \) is some constant bigger than \( c_6 \).
- We have level set functions \( \Theta_i : R_i \rightarrow \mathbb{R} \) such that if we let
  \[
  G_i := \left\{ t \in (a + \langle \phi_i \rangle) \cap B_{\frac{c_6}{r_i}} (a) : \int_{\Theta_i^{-1}(t) \cap R_i} J(x) dH^1 x \leq \alpha w \right\}
  \]
  we have
  \[
  L^1 \left( (a + \langle \phi_i \rangle) \cap B_{\frac{c_6}{r_i}} (a) \setminus G_i \right) \leq \alpha w
  \]
  for \( i = 1, 2 \).

- \[
  \int_{N_{\alpha w}(S)} d(Dv(x), SO(2) \cup SO(2) H) dL^2 x < c^3 w^2
  \]
  then if we take skewcube \( \tilde{S} := P(a, \phi_1, \phi_2, c_8 w) \) (for some constant \( c_8 \) strictly less than \( c_7 \)) there exists rotation \( R_0 \in SO(2) \) and \( \Theta \in \{ Id, H \} \) such that
  \[
  L^2 \left( \left\{ x \in \tilde{S} : |Dv(x) - R_0 \Theta| > \sqrt{\alpha} \right\} \right) < 20 c^8 c_4 c_8 w^2.
  \]

**Proof.** This lemma follows from Lemma 6 in a relatively straightforward way. Let

- \[
  t_1 := \partial P \left( a, \phi_1, \phi_2, \frac{2w}{\sigma^2} \right) \cap \{ a + \lambda \phi_1 : \lambda > 0 \},
  t_2 := \partial P \left( a, \phi_1, \phi_2, \frac{2w}{\sigma^2} \right) \cap \{ a + \lambda \phi_1 : \lambda \leq 0 \}.
  \]
- \[
  t_3 := \partial P \left( a, \phi_1, \phi_2, \frac{2w}{\sigma^2} \right) \cap \{ a + \lambda \phi_2 : \lambda > 0 \},
  t_4 := \partial P \left( a, \phi_1, \phi_2, \frac{2w}{\sigma^2} \right) \cap \{ a + \lambda \phi_2 : \lambda \leq 0 \}.
  \]

Observe fig 26.

**Figure 26**

Take point \( v_{t_4} \in G_4 \cap [t_1, t_2] \). By Lemma 1 and bilipschitzness we have that line \( \{ v(t_1), v(t_2) \} \) is some distinct angle away from line \( l_1 := l_{\phi_1} \). Specifically there exists a constant \( c_1 := c(\sigma) \in (0, 1) \) such that

\[
L^1 \left( P_{t_4} \left( \{ v(t_1), v(t_2) \} \right) \right) \geq c_1 |v(t_1) - v(t_2)|.
\]
Similarly if we chose point \( \partial t_2 \in G_2 \cap [t_3, t_4] \) let \( t_2 := t_{\partial t_2} \) we have
\[
L^1 \left( P_{t_2^+} \left( [v(t_3), v(t_4)] \right) \right) \geq c_1 |v(t_3) - v(t_4)|.
\]
So for some \( c_2 := c(\sigma) \) we have
\[
B_{c_2w} (v(a)) \subset P_{t_2^+}^{-1} \left( P_{t_2^+} \left( [v(t_1), v(t_2)] \right) \right)
\]
and
\[
B_{c_2w} (v(a)) \subset P_{t_2^+}^{-1} \left( P_{t_2^+} \left( [v(t_3), v(t_4)] \right) \right).
\]
Let \( Q_1 := P_{t_2^+}^{-1} \left( [v(t_1), v(t_2)] \right) \) and \( Q_2 := P_{t_2^+}^{-1} \left( [v(t_3), v(t_4)] \right) \). We cut \( Q_1 \) into intervals of width \( \frac{2 \pi w}{\alpha} \).

Formally, we can find a set \( \left\{ B_{\frac{\pi w}{\alpha}} (\zeta k^1) : k = 1, 2, \ldots M_0 \right\} \) that are pairwise disjoint, with \( \{ \zeta k : k = 1, 2, \ldots M_0 \} \subset Q_2 \).
\[
Q_2 \subset \bigcup_{k=1}^{M_0} B_{\frac{\pi w}{\alpha}} (\zeta k^1)
\]
and \( M_0 := \left\lfloor \frac{4L^1(Q_1)}{\alpha \pi w} \right\rfloor + 1 \leq 5 \left\lfloor \alpha \frac{\pi}{w} \right\rfloor \).

Similarly we cut \( Q_1 \) into intervals of width \( \frac{2 \pi w}{\alpha} \). So we find \( \{ B_{\frac{\pi w}{\alpha}} (\zeta k^2) : k = 1, 2, \ldots M_1 \} \) that are pairwise disjoint, with \( \{ \zeta k : k = 1, 2, \ldots M_1 \} \subset Q_2 \).
\[
Q_2 \subset \bigcup_{k=1}^{M_1} B_{\frac{\pi w}{\alpha}} (\zeta k^1)
\]
and \( M_1 := \left\lfloor \frac{4L^1(Q_2)}{\alpha \pi w} \right\rfloor + 1 \leq 5 \left\lfloor \alpha^{-1} \frac{\pi}{w} \right\rfloor \).

Now as \( v([t_1, t_2]) \) is connected, for each \( k \in \{1, 2, \ldots M_0\} \) we have \( P_{t_2^+}^{-1} (\zeta k^1) \cap v([t_1, t_2]) \neq \emptyset \). So we can pick \( q k^1 \in P_{t_2^+}^{-1} (\zeta k^1) \cap v([t_1, t_2]) \) for \( k \in \{1, 2, \ldots M_0\} \) and \( q k^2 \in P_{t_2^+}^{-1} (\zeta k^2) \cap v([t_3, t_4]) \) for \( k \in \{1, 2, \ldots M_1\} \).

Now observe fig 27 below.

By (149) for each \( k \in \{1, 2, \ldots M_0\} \) we must be able to chose \( \tau k^1 \in N_{aw} (v^1 (q k^1)) \cap G_1 \) and for each \( k \in \{1, 2, \ldots M_1\} \) we can chose \( \tau k^2 \in N_{aw} (v^1 (q k^2)) \cap G_2 \) so we have
\[
Q_1 \subset \bigcup_{k=1}^{M_0} B_{\frac{\pi w}{\alpha}} \left( P_{t_2^+} (v^1 (\tau k^1)) \right)
\]
(151)
and

\[ Q_2 \subset \bigcup_{k=1}^{M_1} B \left( \frac{1}{\alpha \tilde{w}^N} \left( P_i (v (\tau_k^l)) \right) \right) . \]  

(152)

Now by Lemma 6 we know \( w_{\tau_k^l} \) (the clockwise normal to \( l_{\tau_k^l} \)) and \( w_1 \) is the clockwise normal to \( l_1 \) are such that

\[ |w_{\tau_k^l} - w_1| < 2048\sigma^{-6}a_4 w^2 \]  

(153)

Observe fig 28.

As the angle between \( w_{\tau_k^l} \) and \( w_1 \) is less than \( 5000\sigma^{-6}a_4 \), if we let \( \tilde{l}_k^l \) be the line centered on \( v (\tau_k^l) \) parallel to \( l_1 \) as can be seen from fig 28

\[ N \left( \frac{1}{\alpha \tilde{w}^N} (\tilde{l}_k^l) \right) \subset N \left( \frac{1}{\alpha \tilde{w}^N} (\tau_k^l) \right) . \]  

(154)

So by Lemma 7, (153) and (154)

\[
L^2 \left( \left\{ x \in N \left( \frac{1}{\alpha \tilde{w}^N} (\tilde{l}_k^l) \right) \cap R_1 : \left| Dv (v^{-1} (x)) \phi_1 - w_1 \right| > 6000\sigma^{-6}a_4 w^2 \right| \right) 
\leq L^2 \left( \left\{ x \in N \left( \frac{1}{\alpha \tilde{w}^N} (\tau_k^l) \right) \cap R_1 : \left| Dv (v^{-1} (x)) \phi_1 - w_{\tau_k^l} \right| > 3000\sigma^{-6}a_4 w^2 \right| \right) 
\leq \sigma^{-6}\epsilon_4 \alpha \tilde{w}^N w^2 .

However from (150) and (151) we have

\[
B_{c_{2w}} (v (a)) \subset \bigcup_{k=1}^{N_0} N \left( \frac{1}{\alpha \tilde{w}^N} (\tilde{l}_k^l) \right) \cap R_1 .
\]

If we let \( \tilde{l}_k^l \) be the line centered on \( v (\tau_k^l) \) parallel to \( l_2 \) for each \( k \in \{1, 2, \ldots N_1\} \). In exactly the same we have

\[
B_{c_{2w}} (v (a)) \subset \bigcup_{k=1}^{N_1} N \left( \frac{1}{\alpha \tilde{w}^N} (\tilde{l}_k^l) \right) \cap R_2 .
\]

So

\[
L^2 \left( \left\{ x \in B_{c_{2w}} (v (a)) : \left| Dv (v^{-1} (x)) \phi_1 - w_1 \right| > 6000\sigma^{-6}a_4 w^2 \right| \right) 
\leq \sum_{k=1}^{N_0} L^2 \left( \left\{ x \in N \left( \frac{1}{\alpha \tilde{w}^N} (\tilde{l}_k^l) \right) \cap R_i : \left| Dv (v^{-1} (x)) \phi_1 - w_1 \right| > 3000\sigma^{-6}a_4 w^2 \right| \right) 
\leq \sigma^{-6}M_0 \epsilon_4 \alpha \tilde{w}^N w^2 
\leq 5\sigma^{-6}\epsilon_4 \alpha \tilde{w}^N w^2 .
\]

(155)

In exactly the same way we have

\[
L^2 \left( \left\{ x \in B_{c_{2w}} (v (a)) : \left| Dv (v^{-1} (x)) \phi_2 - w_2 \right| > 6000\sigma^{-6}a_4 w^2 \right| \right) \leq 5\sigma^{-6}\epsilon_4 \alpha \tilde{w}^N w^2 .
\]

(156)
Let \( J := \{ x \in S : d(Dv(x), SO(2) \cup SO(2) H) < \sqrt{\alpha} \} \) and 
\[
Z := \left\{ x \in B_{c_2w}(v(a)) : |Dv(v^{-1}(x)) \phi_2 - w_2| < 6000 \sigma^{-6} \alpha^{-16} \text{ and } |Dv(v^{-1}(x)) \phi_1 - w_1| < 6000 \sigma^{-6} \alpha^{-16} \right\}
\]
so by assumption (134) and (155), (156) we have
\[
L^2(B_{c_2w}(v(a)) \setminus (Z \cup v(J))) \leq 20 \sigma^{-8} c_4^4 \alpha^{18} w^2.
\]
(157)
Now for any \( z \in B_{c_2w}(v(a)) \cap (Z \cup v(J)) \) since for \( z \in Z \) we have \(|Dv(v^{-1}(z)) - R\mathcal{S}| < \sqrt{\alpha}\) for some \( R \in SO(2) \) and some \( \mathcal{S} \in \{ Id, H \} \) and as the angle between \( R\mathcal{S}\phi_1 \) and \( R\mathcal{S}\phi_2 \) changes radically depending on whether \( \mathcal{S} = Id \) or \( \mathcal{S} = H \) whilst \( w_1 \) and \( w_2 \) are independent of \( x \), so we either have
\[
\{Dv(v^{-1}(z)) : z \in B_{c_2w}(v(x)) \cap (Z \cup v(J))\} \subset N_{\sqrt{\alpha}}(SO(2))
\]
(158)
\[
\{Dv(v^{-1}(z)) : z \in B_{c_2w}(v(x)) \cap (Z \cup v(J))\} \subset N_{\sqrt{\alpha}}(SO(2) H).
\]
(159)
Now assuming \( c_2 \) is big enough we have that
\[
\tilde{S} := P(a, \phi_1, \phi_2, c_4 w) \subset v^{-1}(B_{c_2w}(v(a)))
\]
and hence from (157)
\[
L^2 \left( \left\{ x \in \tilde{S} : d(Dv(x), SO(2) A) \geq \sqrt{\alpha} \right\} \right) \leq 20 \sigma^{-8} c_4^4 \alpha^{18} w^2
\]
and hence we have established the lemma.
7.3. Proof of Proposition 1 continued.

Lemma 6 and Lemma 8 have essentially done most of the proof of Proposition 1 for us. The only "work" to be done in the coming proof is to set up all the conditions to apply Lemmas 6, 8 and simply to count up the consequences in terms our exponents $\kappa$ and $\varepsilon$.

Proof. So recall, we have

$$
\int_S d(\mathbf{D}v(x), SO(2) \cup SO(2) H) \, dL^2 x \leq \kappa \frac{m}{\varepsilon} + 8\varepsilon^2
$$

(160) and for the set \(\left\{ C_k^{(p)} : k \in \{1, \ldots [\kappa^{-m_0}] \} \right\}\) of pairwise disjoint columns width $\kappa^{m_0}\varepsilon$ going through $S$ parallel to $\phi_k$. We let $E_k^{(p)} := N_{(\kappa^{-1})\kappa^{-m_0}\varepsilon}(C_k^{(p)})$ for $k \in \{1, \ldots [\kappa^{-m_0}] + 1\}$. From (160) we can find a set \(\left\{ k_{Q_0}^p, \ldots k_{Q_0}^p \right\}\) of distinct numbers satisfying the following inequalities

$$
\int_{E_k^{(p)}} J(x) \, dL^2 x \leq \kappa^{3m_0+7\varepsilon^2}
$$

for each $j \in \{1, \ldots Q_0^p\}$ and

$$
Q_0^p \geq \left(1 - \frac{\kappa^{m_0}}{\kappa} \right) [\kappa^{-m_0}] \text{ for } p = 1, 2.
$$

(161)

And by assumption (132) we have

$$
\sum_{j=1}^{Q_0^p} \int_{E_k^{(p)}} J(x) \left| D\Theta_k^{(p)}(x) \right| \, dL^2 x \leq \kappa^{m_0+1}\varepsilon^2
$$

for $p = 1, 2$.

We also have $\int_S |D^2 v(x)| \, dL^2 x < c\kappa$. Let

$$
B_0^p := \left\{ k_j^p : \int_{E_k^{(p)}} J(x) \left| D\Theta_k^{(p)}(x) \right| \, dL^2 x \geq \kappa^{m_0+1}\varepsilon^2, \ j \in \{1, \ldots Q_0^p\} \right\}.
$$

So $\text{Card}(B_0^p) \leq \kappa^{m_0+1}\varepsilon^2$ implies $\text{Card}(B_0^p) \leq \kappa^{-m_0}$. Let

$$
G_0^p := \left\{ k_j^p : j \in \{1, \ldots Q_0^p\} \right\} \backslash B_0^p
$$

thus

$$
\text{Card}(G_0^p) \geq [\kappa^{-m_0} (1 - 2\kappa^{-m_0})].
$$

(162)

Let $a_{i,j}$ be the centerpoint of $E_i^{(1)} \cap E_j^{(2)}$. Note that $S_{i,j} := P(a_{i,j}, \phi_1, \phi_2, \varepsilon_0\kappa^{-m_0}\varepsilon) \subset E_i^{(1)} \cap E_j^{(2)}$. Let $j_k^{(p)} := \left( a_k^{(p)} + \phi_k \right) \cap S$. Let

$$
U_k^{(p)} := \left\{ t \in j_k^{(p)} : \int_{\Theta_k^{(p)}(t) \cap V(E_k^{(p)})} J(x) \, dH^1 x \geq \kappa^{\frac{m_0}{\kappa^m}} \kappa^{-m_0}\varepsilon \right\}.
$$

(163)

Let $k \in G_0^p$, by the coarea formula, for any $k \in G_0^p$

$$
\int_{t \in U_k^{(p)}} \int_{\Theta_k^{(p)}(t) \cap V(E_k^{(p)})} J(x) \, dH^1 x \, dL^1 t \leq \int_{t \in \mathbb{R}} \int_{\Theta_k^{(p)}(t) \cap V(E_k^{(p)})} J(x) \, dH^1 x \, dL^1 t
$$

$$
= \int_{E_k^{(p)}} J(x) \left| D\Theta_k^{(p)} \right| \, dL^2 x
$$

$$
\leq \kappa^{m_0} \kappa^{-m_0+1}\varepsilon^2.
$$
So $L^1 (U^p_k) \leq \kappa^{\kappa^{m_0} \epsilon}$ which implies $L^1 (U^p_k) \leq \kappa^{\kappa^{m_0} \epsilon}$ Now let us temporarily fix $p = 1$. Let $\Lambda_{k, r} := i_k^{(1)} \cap N_{m_0/k} (S_{k, r})$ for $k \in \{1, 2, \ldots [\kappa^{-m_0}] + 1\}$, $r \in \{1, 2, \ldots [\kappa^{-m_0}] + 1\}$. For $k \in G_0$ let

$$D^1_k := \{ r \in \{1, 2, \ldots [\kappa^{-m_0}] \} : L^1 (\Lambda_{k, r} \cap U^1_k) > \kappa^{1+6\epsilon_2} \kappa^{m_0} \epsilon \}.$$  

So since $\{ \Lambda_{k, r} : r \in \{1, 2, \ldots [\kappa^{-m_0}] + 1\} \}$ do not overlap by more than $[\sigma^{-6}] + 1$ we have

$$\frac{\sigma^6}{2} \text{Card} (D^1_k) \kappa^{1+6\epsilon_2} \kappa^{m_0} \epsilon \leq L^1 (U^1_k) \leq \kappa^{\kappa^{m_0} \epsilon}$$

and thus

$$\text{Card} (D^1_k) \leq 2\sigma^{-6} \kappa^{m_0} \kappa^{-m_0}.$$  

For $p = 2$ we can define $\Lambda_{k, r} := i_k^{(2)} \cap N_{m_0/k} (S_{k, r})$ and for $r \in G^2_0$ we let

$$D^2_r := \{ k \in \{1, 2, \ldots [\kappa^{-m_0}] \} : L^1 (\Lambda_{k, r} \cap U^2_k) > \kappa^{1+6\epsilon_2} \kappa^{m_0} \epsilon \}.$$  

We can see in exactly the same way that $\text{Card} (D^2_r) \leq 2\sigma^{-6} \kappa^{m_0} \kappa^{-m_0}$. 

Now we define the “bad” skew cubes $\tilde{B}_0$ of the set $\{ S_{i, j} : i \in G_0, j \in G^2_0 \}$ as follows

$$S_{i, j} \in \tilde{B}_0 \text{ iff } N_{m_0/k} (S_{i, j}) \cap i^{(1)} \in \{ \Lambda_{i, j} : r \in D^1_r \} \text{ or } N_{m_0/k} (S_{i, j}) \cap i^{(2)} \in \{ \Lambda_{i, j} : k \in D^2_k \}.$$  

So

$$\text{Card} (\tilde{B}_0) \leq \sum_{k=1}^{[\kappa^{-m_0}] + 1} D^1_k + \sum_{r=1}^{[\kappa^{-m_0}] + 1} D^2_r \leq 8\sigma^{-6} \kappa^{m_0} \kappa^{-m_0} \kappa^{1+6\epsilon_2} \kappa^{m_0} \epsilon \leq \frac{8\sigma^{-6} \kappa^{m_0}}{\kappa^{2m_0}}.$$  

Let $\tilde{G}_0 := \{ S_{i, j} : i \in G_0, j \in G^2_0 \} \setminus \tilde{B}_0$. So from (162) and (166) we have

$$\text{Card} (\tilde{G}_0) = \left( \text{Card} (\{1, \ldots [\kappa^{-m_0}] + 1\} \setminus G^1_0) \kappa^{-m_0} - \text{Card} (\{1, \ldots [\kappa^{-m_0}] + 1\} \setminus G^2_0) \kappa^{-m_0} \right) - \text{Card} \left( \tilde{B}_0 \right) \geq \frac{1}{\kappa^{2m_0}} \left( 1 - 4\kappa^{m_0} - 8\sigma^{-6} \kappa^{m_0} \right) \geq \frac{(1 - 16\sigma^{-6} \kappa^{m_0})}{\kappa^{2m_0}}.$$  

Obviously we want to apply Lemma 8 to the skew cubes $\{ S_{i, j} \in \tilde{G}_0 \}$. First we have to make a further selection. Let $w := \epsilon \tau \kappa^{m_0} \epsilon$ and let $\alpha := \kappa^{m_0}$. 

Now let

$$G_0 := \left\{ S_{i, j} \in \tilde{G}_0 : \int d\left( D e (x), \mathit{SO} (2) \cup \mathit{SO} (2) \mathit{H} \right) dL^2 x < c^2 \kappa^{m_0 (2+\frac{4}{3})} \epsilon^2 \right\}$$

assuming (160) we have that $\text{Card} (\tilde{G}_0 \setminus G_0) c^2 \kappa^{m_0 (2+\frac{4}{3})} \epsilon^2 \leq \kappa^{3m_0} \epsilon^2$ so

$$\tilde{G}_0 \setminus G_0 = \emptyset.$$  

Given $S_{i, j} \in G_0$ let $R_1 := \mathcal{F} (a_{i, j}, w \phi_2, \epsilon \phi_1)$ and $R_2 := \mathcal{F} (a_{i, j}, \phi \phi_2, w \phi_1)$. 


As $\alpha > \kappa^{\frac{m}{4}}$ and $w > \kappa^{m_0} \epsilon$ we know from definitions (163), (164) and (165) and the fact that $S_{i,j} \in G_0$ that

$$G_p := \left\{ t \in (a_{i,j} + \langle \phi_p \rangle) \cap B_{\frac{1}{\kappa^{m_0}}} (a_{i,j}) : \int_{\Theta^i_x - 1(t) \cap R_p} J(x) dH^1 x \leq \alpha w \right\}$$

is such that

$$L^1 \left( (a_{i,j} + \langle \phi_p \rangle) \cap B_{\frac{1}{\kappa^{m_0}}} (a_{i,j}) \setminus G_p \right) \leq \alpha \kappa^{m_0} \epsilon \leq \alpha w$$

for $p = 1, 2$. So we apply Lemma 8 to $S_{i,j}$ to conclude that for $\tilde{S}_{i,j} := P(a_{i,j}, \phi_1, \phi_2, c_8 w)$ there exists rotation $R_{i,j} \in SO(2)$ and $\tilde{S}_{i,j} \in \{Id, H\}$ such that

$$L^2 \left( \left\{ x \in \tilde{S}_{i,j} : |Dv(x) - R_{i,j} \tilde{S}_{i,j}| > \kappa^{\frac{m}{4}} \right\} \right) < 20 \sigma^{-8} \tilde{c}_4 c_2^2 \kappa^{\frac{m}{4}} \kappa^{m_0} (\kappa^{m_0} \epsilon)^2$$

so by (167) and (168) we have established the proof of Proposition 1.

\[\square\]
8. The Coarea alternative: Part II

In the first part of the “coarea alternative” we established that for a skewcube $S$ of diameter $\epsilon$ with very small bulk energy and surface energy bounded by $\kappa \epsilon$, there must exist very many “controlled” subskeewcubes of size roughly $\kappa^m \epsilon$; by this we mean that $Dv(\cdot)$ is these subskeewcubes remains (mostly) close to one component of the wells. Recall that the goal of the “coarea alternative” was to show that for a function $v$ and skewcube $S$ under our hypotheses and with little surface energy over $S$, given triangle $\tau_i \subset S$, if we let $L$ denote the linear part of the affine interpolation of $v$ on the corners of $L$, then $L$ will be very close to these wells. In the coming Lemma we will establish this for skewcube $S$ under our hypotheses and additionally having the property of having many “controlled” subskeewcubes.

The proof is based on two observations. Firstly we know from a calculation in the proof of Lemma 1 (specifically, equation (14)) that the tangent $v_{x_0}$ at point $x_0$ of the pull back of an integral curve given by a level set of $\Theta_i$ is of the form $v_{x_0} := [S^{-1}(Y(t_0))] S^{-1}(Y(t_0)) \cdot n$, where $Dv(\cdot) = R(\cdot) S(\cdot)$ is the polar decomposition of $Dv(\cdot)$. So the tangent doesn’t depend of the rotational part of the derivative. Secondly, from our constraint on surface energy, $\int_S |D^2v(x)| \, dL^2 x \leq \kappa \epsilon$, if we take any choice of direction $\psi_0 \in S^1$ then considering lines in direction $\psi_0$ going through $S$ spaced out from one another by $\kappa^m \epsilon$, all but $[\frac{\kappa^m \epsilon}{\kappa \epsilon}]$ of these lines must be such that they only pass through controlled subskeewcubes that have derivative close the same component of the wells. So suppose at least half our controlled subskeewcubes are such that $Dv(\cdot)$ is close to $SO(2) \cdot H$, then we must be able to find many lines parallel to $H^{-2}n_1$ and $H^{-2}n_2$ running through $S$ only touching controlled subskeewcubes with derivative close to $SO(2) \cdot H$.

![Figure 29](image)

Recall from the introduction, in trying to control our function $v$ on skewcube $S$ our first step was to show that the integral curves run in straight lines, we did this by using the “pull back idea” (which only required information about the bulk energy) and the “ODE method” in which we needed somehow to find integral curves along which $Dv(\cdot)$ stays close the wells. In our situation now, we have that for many pulled back integral curves through $S$, $Dv(\cdot)$ along the pulled back curve does indeed stay close to the wells (in fact stays close to $SO(2) \cdot H$) and as such by using bulk energy as we have done before, its easy to show that these integral curves form something very much like straight lines.

Observe fig 29. Its not hard to see we can find lines parallel to $H^{-2}n_1$ and $H^{-2}n_2$ which enclose a large subset of $S$ and have the property that they intersect only controlled skewcubes for which $Dv(\cdot)$ is close to $SO(2) \cdot H$. Let $D$ denote the region enclosed. Let $B_1, B_2, B_3, B_4$ denote the sides of $D$, i.e. $\partial D = \bigcup_{i=1}^4 B_i$. By using the “pull back idea” and the “ODE method” carefully its not hard to show that $v_{B_i} \approx (R_i H + \zeta_i)_{B_i}$ for some $R_i \in SO(2)$ and some $\zeta_i \in \mathbb{R}^2$. And then by using Lemma 6 and the fact that $\det(Dv(\cdot)) \approx 1$ for most points, we can (with some care) show that $v_{\partial D} \approx (\tilde{R} H + \tilde{\zeta})_{\partial D}$. From this, by considering the action of $v$ on rank $-1$ lines parallel to $\phi_1$ and $\phi_2$ running through $D$, its easy to see that any triangle $\tau_i \subset D$ is such that if $L$ denotes the linear part of the affine interpolation of $v$ on the corners of $\tau_i$, then $L$ is very close to a matrix in $SO(2) \cdot H$. 

This does the case where at least half the controlled subskewcubes are such that $Dv(\cdot)$ are close to $SO(2)\ H$. In
the case where half the controlled subskewcubes are close to $SO(2)$ we can argue in an entirely analogous way.
In this case we will consider lines going through $S$ in directions $n_1$ and $n_2$, these form pullbacks of integral
curves for which $Dv(\cdot)$ stays close to $SO(2)$. We can then argue the same way to get control of a region
contained by four such lines, specifically we can conclude that any triangle $\tau_i$ contained in this region is such
that the linear part of the affine interpolation of $v$ on $\tau_i$ is close to a matrix in $SO(2)$. This is how the proof
works.

Lemma 9. Let $v \in A_f(\Omega)$ and let $S := P(\alpha, \phi_1, \phi_2, \epsilon \sigma) \subset \Omega$ where $\epsilon$ is some large constant we will decide
on later.

Let

$$\{ \Xi_{i,j} := P(a_{i,j}, \phi_1, \phi_2, \kappa^{m_0} \epsilon) : i, j \in \{1, 2, \ldots, \lfloor \kappa^{-m_0} \rfloor + 1\} \}$$

be a set of pairwise disjoint skewcubes such that $S \subset \bigcup_{i,j \in \{1, \ldots, \lfloor \kappa^{-m_0} \rfloor + 1\}} \Xi_{i,j}$. Let

$$S_{i,j} := P(a_{i,j}, \phi_1, \phi_2, \epsilon \sigma^{m_0}).$$

Suppose we have a set $G_0 \subset \{ S_{i,j} : i, j \in \{1, \ldots, \lfloor \kappa^{-m_0} \rfloor + 1\} \}$ such that for any $S_{i,j} \in G_0$

- $L^2 \left( \{ x \in S_{i,j} : d(Dv(x), R_{i,j} \Xi_{i,j}) > \frac{\kappa^{m_0}}{2} \} \right) < 20 \epsilon \sigma^{-8} \kappa^{-m_0} (\epsilon \kappa^{m_0})^2$
  for some $R_{i,j} \in SO(2)$, $\Xi_{i,j} \in \{Id, H\}$

And we suppose also that

$$\int_S |D^2v(x)| \ dL^2x \leq \kappa \epsilon$$

and

$$\int_S d(Dv, K) \ dL^2x \leq \kappa^{-m_0} \epsilon^2$$

then if $\tau_i$ is the triangle in $\triangle_{\kappa}$ that contains $a$, let $L_i$ be the linear part of the affine map we get from the
interpolation of $v$ on the corners of $\tau_i$, we have the following inequality;

$$d(L_i, SO(2) \cup SO(2) H) < \kappa^{-m_0} \epsilon^2.$$

Proof. Let $B_0 := \{ S_{i,j} : S_{i,j} \cap S \neq \emptyset$ and $S_{i,j} \not\in G_0 \}$. So $\text{Card}(B_0) \leq \frac{16 \epsilon \sigma^{-2} \kappa^{m_0} \epsilon}{\kappa^{m_0}}$. We start by having to consider two cases,

Let

$$G^{(1)}_0 := \{ S_{i,j} \in G_0 : Dv|_{S_{i,j}} \approx R_{i,j}$ for some $R_{i,j} \in SO(2) \}$$

and let

$$G^{(2)}_0 := \{ S_{i,j} \in G_0 : Dv|_{S_{i,j}} \approx R_{i,j}T_{i,j}$ for some $R_{i,j} \in SO(2)$ and $T_{i,j} \in \{Id, H\} \}.$$

Case 1: Card $\left( G^{(2)}_0 \right) \geq \text{Card}(G^{(1)}_0)$.

Case 2: Card $\left( G^{(1)}_0 \right) \geq \text{Card}(G^{(2)}_0)$.

We will have to argue the two cases in analogous, but different ways. As Case 1 is a little more intricate we chose to argue it in detail.

Step 1 Take vector $\hat{\gamma}_1$. Recall definition (54).

We can find a chain of points $\{ \hat{x}_k : k = 1, 2, \ldots, M_0 \} \subset P_{\hat{\gamma}_1}(S)$, $M_0 = \left\lfloor \frac{L^1 \left( P_{\hat{\gamma}_1}(S) \right)}{\kappa^{-m_0} \epsilon} \right\rfloor$ such that $|\hat{x}_{k-1} - \hat{x}_k| = |\hat{x}_k - \hat{x}_{k+1}| = \epsilon \kappa^{m_0}$ for $k = 2, 3, \ldots, M_0 - 1$. Now for $k \in \{2, 3, \ldots, M_0\}$ let

$$\hat{Z}_k := \{ S_{i,j} \in S : \Xi_{i,j} \cap P^{-1}_{\hat{\gamma}_1}(\hat{x}_k) \neq \emptyset \}.$$
Note \( \{S_{i,j} \in S \} \subset \bigcup_{k=1}^{M_0} \overline{Z_k} \). Let
\[
E_0 := \left\{ k \in \{1, 2, \ldots M_0 \} : \begin{array}{l}
\text{There exists } S_{i,j}^{(1)} \in \overline{Z_k} \cap G_0 \text{ with } Dv_{|S_{i,j}^{(1)}} \approx SO(2) \\text{ and } \\
S_{i,j}^{(2)} \in \overline{Z_k} \cap G_0 \text{ with } Dv_{|S_{i,j}^{(2)}} \approx SO(2) H
\end{array} \right\}
\]

By 5r Covering Theorem ([16] Theorem 2.1) can take some subset \( E_1 \subset E_0 \) which has the following properties
- For any \( k_1, k_2 \in E_1 \) that are not equal, \( \overline{Z_{k_1}} \cap \overline{Z_{k_2}} = \emptyset \).
- \[
\bigcup_{k \in E_0} B_{2\kappa m_0 \epsilon} (\tilde{x}_k) \subset \bigcup_{k \in E_1} B_{10\kappa m_0 \epsilon} (\tilde{x}_k).
\]

Now we clearly have that for each \( k \in E_1 \) we have
\[
\int_{P_{\tilde{x}_k}^{-1}(B_{10\kappa m_0 \epsilon}(\tilde{x}_k))} |D^2 v(x)| \, dL^2 x \geq \frac{\kappa m_0 \epsilon}{2}.
\]

So from (170) \( \text{Card}(E_1) \frac{\kappa m_0}{2} \epsilon \leq \frac{\kappa \epsilon}{2} \) which implies that
\[
\text{Card}(E_1) \leq \kappa^{1-m_0}
\]
and from (171) we have
\[
\text{Card}(E_0) 2k^{m_0} \epsilon = L^1 \left( \bigcup_{k \in E_0} B_{2\kappa m_0 \epsilon} (\tilde{x}_k) \right) \\
\leq L^1 \left( \bigcup_{k \in E_1} B_{10\kappa m_0 \epsilon} (\tilde{x}_k) \right) \\
\leq 10k^{m_0} \epsilon \text{Card}(E_1).
\]

So \( \text{Card}(E_1) \geq \frac{\text{Card}(E_0)}{5} \) and thus from (172) we have
\[
\text{Card}(E_0) \leq 5k^{1-m_0}.
\]

Let \( Q_0 := \{1, 2, \ldots M_0 \} \setminus E_0 \). So for any \( k \in Q_0 \), \( \overline{Z_k} \cap G_0 \) consists only of skewcubes \( S_{i,j} \) for which \( Dv_{|S_{i,j}} \approx SO(2) \) or consists only of skewcubes \( S_{i,j} \) for which \( Dv_{|S_{i,j}} \approx SO(2) H \). Let
\[
Q_1 := \{ k \in Q_0 : \text{Card} \left( \overline{Z_k} \cap B_0 \right) \leq \kappa^{m_0} m_0 \}
\]

Now by a similar application of the 5r covering theorem
\[
\text{Card}(Q_0 \setminus Q_1) \kappa^{m_0} m_0 \leq \frac{20k^{m_0}}{K_2^{2m_0}}
\]
so
\[
\text{Card}(Q_0 \setminus Q_1) \leq \frac{20k^{m_0}}{K_2^{2m_0}}.
\]

Thus
\[
\text{Card}(Q_1) = \left( 1 - 5k - 20k^{m_0} \kappa m_0 \right) m_0.
\]

Finally for some constant we let
\[
Q_2 = \{ k \in \{1, 2, \ldots M_0 \} : L^1 \left( P_{\tilde{x}_k}^{-1}(\tilde{x}_k) \cap S \right) \geq 10k \epsilon \}
\]
so its easy to see from the diagram \( Q_1 \setminus Q_2 \approx 10c_1 m_0 + 1 \) for some \( c_1 := c(\sigma) > 0 \). Let \( Q_2 := Q_1 \setminus Q_2 \). So from (174) we have
\[
\text{Card}(\{1, 2, \ldots M_0 \} \setminus Q_2) \leq 20c_1 k^{1-m_0}.
\]

**Step 2.**
Now we will show that either

- For any $S_{i,j} \in \bigcup_{k \in Q_2} \tilde{Z}_k$, $Dv_{\mid S_{i,j}} \approx A_{i,j}$ for $A_{i,j} \in SO(2)$
- For any $S_{i,j} \in \bigcup_{k \in Q_2} \tilde{Z}_k$, $Dv_{\mid S_{i,j}} \approx B_{i,j}$ for $B_{i,j} \in SO(2) H$.

Suppose this was not true, so we can find $k_1, k_2 \in Q_2$ such that:

- For all $S_{i,j} \in \tilde{Z}_{k_1}$, $Dv_{\mid S_{i,j}} \approx A_{i,j}$ with $A_{i,j} \in SO(2)$
- For all $S_{i,j} \in \tilde{Z}_{k_2}$, $Dv_{\mid S_{i,j}} \approx B_{i,j}$ with $B_{i,j} \in SO(2) H$.

Now by considering the change in derivative of $Dv$ in direction $\diamond$ from the set $\bigcup_{S_{i,j} \in \tilde{Z}_1} S_{i,j}$ to the set $\bigcup_{S_{i,j} \in \tilde{Z}_2} S_{i,j}$ we see that

$$\int_S |D^2 v(x)| dL^2 x \geq 10 \kappa \epsilon$$

which contradicts assumption (169). So we have established the claim.

Now if we start the argument again from the beginning and instead of taking a chain of points in $P_{\tilde{Z}_2}(S)$ we take a chain of points in $P_{\tilde{Z}_1}(S)$, we can then run through the whole argument again to establish the following.

Let $\{ \tilde{z}_k : k = 1, 2 \ldots M_1 \} \subset P_{\tilde{Z}_1}(S)$, $(M_1 = \left[ L^1 \left( P_{\tilde{Z}_1}(S) \right) \right] )$ be a chain of points such that

$$|\tilde{z}_k - \tilde{z}_{k+1}| = \epsilon R^{m_0}$$

for $k = 1, 2, \ldots M_1 - 1$. Let $P_1 := \left\{ k \in \{1, \ldots M_1\} : L^1 \left( P_{\tilde{Z}_1}^{-1} (\tilde{z}_k) \cap S \right) > 10 \kappa \epsilon \right\}$. For $k \in \{1, 2, \ldots M_1\}$ we let $Y_k := \{ S_{i,j} : \mathcal{L}_{i,j} \cap P_{\tilde{Z}_1}^{-1} (\tilde{z}_k) \neq \emptyset \}$. We can find a subset $P_2 \subset P_1$ with the following properties.

There exists $\mathfrak{S} \in \{ Id, H \}$ such that

- For any $S_{i,j} \in \bigcup_{k \in P_2} Y_k$ we have $Dv_{\mid S_{i,j}} (\cdot) \approx A_{i,j}$
  
  \begin{equation}
  \text{with } A_{i,j} \in SO(2) \mathfrak{S}.
  \end{equation}

- \begin{equation}
  \text{Card } \{1, 2, \ldots M_1\} \setminus P_2 \leq 20 c_1 \kappa^{1-m_0}
  \end{equation}

Step 3. Now we refine the set up. Now for any $k_1 \in Q_2$ we have situation shown on fig 31.
Since every point in $P^{-1}_{\Omega^1}(x_{k_i}) \cap S$ is covered by skewcubes $\zeta_{i,j}$ which are in turn covered by $S_{i,j}$. We have
\[
N_{\sigma^2c_2\epsilon^{m_0}} \left( P^{-1}_{\Omega^1}(x_{k_i}) \right) \cap S \subset \bigcup_{S_{i,j} \in \mathcal{Z}_k} S_{i,j}.
\]
Now by definition of $Q_2$, for some $\mathcal{G} \in \{Id, H\}$ we have that for any $S_{i,j} \in \bigcup_{k \in Q_2} \mathcal{Z}_k$,
\[
L^2 \left( \left\{ x \in S_{i,j} : d(Dv(x), SO(2, \mathcal{G})) > \frac{\kappa}{\epsilon^{m_0}} \right\} \right) < 20c_6c_1\epsilon^{8}\kappa^{\frac{m_0}{\epsilon^{m_0}}} \left( \epsilon^{m_0} \right)^2.
\]
So
\[
L^2 \left( \left\{ x \in N_{\sigma^2c_2\epsilon^{m_0}} \left( P^{-1}_{\Omega^1}(x_{k_i}) \right) \cap S : d(Dv(x), SO(2, \mathcal{G})) > \frac{\kappa}{\epsilon^{m_0}} \right\} \right) \\
\leq \sum_{S_{i,j} \in \mathcal{Z}_k} L^2 \left( \left\{ x \in S_{i,j} : d(Dv(x), SO(2, \mathcal{G})) > \frac{\kappa}{\epsilon^{m_0}} \right\} \right) \\
\leq 20c_6c_1\epsilon^{8}\kappa^{\frac{m_0}{\epsilon^{m_0}}} \text{Card} \left( \mathcal{Z}_k \right) \kappa^{\frac{m_0}{\epsilon^{m_0}}} \left( \epsilon^{m_0} \right)^2.
\]
Now as $\{S_{i,j} : i,j \in \{1, 2, \ldots, [\epsilon^{-m_0}] + 1\}\}$ do not overlap by more than $c_8$ times, formally
\[
\| \sum_{i,j \in \{1, 2, \ldots, [\epsilon^{-m_0}] + 1\}} X_{S_{i,j}} \|_{\infty} \leq c_8.
\]
We have
\[
\text{Card} \left( \mathcal{Z}_k \right) \leq c_8 \text{Card} \left( \zeta_{i,j} : \zeta_{i,j} \cap P^{-1}_{\Omega^1}(\tilde{x}_k) \neq \emptyset \right) \\
\leq 2c_8\kappa^{-m_0}.
\]
So
\[
L^2 \left( \left\{ x \in N_{\sigma^2c_2\epsilon^{m_0}} \left( P^{-1}_{\Omega^1}(\tilde{x}_k) \right) \cap S : d(Dv(x), SO(2, \mathcal{G})) > \frac{\kappa}{\epsilon^{m_0}} \right\} \right) \leq c_2\epsilon^{2}\kappa^{m_0} \left( 1 + \frac{1}{\epsilon} \right)
\]
and so by Fubini we must be able to find some $x_{k_i} \in B_{\kappa^{m_0} \left( 1 + \frac{1}{\epsilon} \right)}^{(1)} \left( \tilde{x}_k_i \right)$ so
\[
L^1 \left( \left\{ x \in P^{-1}_{\Omega^1}(x_{k_i}) \cap S : d(Dv(x), SO(2, \mathcal{G})) > \frac{\kappa}{\epsilon^{m_0}} \right\} \right) \leq c_2\epsilon^{m_0} \kappa^{\frac{m_0}{\epsilon^{m_0}}}. \tag{178}
\]
So by doing this for every $k \in Q_2$, we can find a set $\{x_k : k \in Q_2\}$ such that
- For every $k \in Q_2$
  \[
  L^1 \left( \left\{ x \in P^{-1}_{\Omega^1}(x_{k}) \cap S : d(Dv(x), SO(2, \mathcal{G})) > \frac{\kappa}{\epsilon^{m_0}} \right\} \right) \leq c_2\epsilon^{m_0} \kappa^{\frac{m_0}{\epsilon^{m_0}}} \tag{179}
  \]
- $|x_k - \tilde{x}_k| \leq \kappa^{m_0} \left( 1 + \frac{1}{\epsilon} \right) \epsilon$ for each $k \in Q_2$. 

Let \( Z_k := \{ S_{i,j} : \mathfrak{L}_{i,j} \cap P_{\frac{1}{\sigma^2}}^{-1}(x) \neq \emptyset \} \).

Now in exactly the same way we can find a set \( \{z_k : k \in P_2\} \) such that for some \( \mathfrak{S} \in \{Id, H\} \)

- For every \( k \in P_2 \)
  \[ L^1 \left( \{ x \in P_{\frac{1}{\sigma^2}}^{-1}(z) \cap S : d(Dv(x), SO(2) \mathfrak{S}) > \kappa^{\frac{\omega}{\sigma}} \} \right) \leq c_0 \epsilon \kappa^{\frac{\omega}{\sigma}} \]

- \( |z_k - z| \leq \kappa^{m_0(1+\frac{20}{\epsilon})} \epsilon \) for each \( k \in P_2 \).

Let \( Y_k := \{ S_{i,j} : \mathfrak{L}_{i,j} \cap P_{\frac{1}{\sigma^2}}^{-1}(z) \neq \emptyset \} \).

Step 4

Observe fig 32.

\[ \text{Figure 32} \]

Let

\[ \Delta_1 := \{ S_{i,j} \in S : \mathfrak{L}_{i,j} \cap P_{\frac{1}{\sigma^2}}^{-1}(x) \neq \emptyset \text{ for } k \in Q_2 \} \]

and let

\[ \Delta_2 := \{ S_{i,j} \in S : \mathfrak{L}_{i,j} \cap P_{\frac{1}{\sigma^2}}^{-1}(z) \neq \emptyset \text{ for } k \in P_2 \} . \]

Now as can be seen from the diagram, assuming we chose \( c_5 \) big enough, then for some \( c_3 > \sigma^{-1} \) we will decide on later, \( I := P(u, \phi_1, \phi_2, \sigma c_\epsilon) \subset S \) is such that

\[ I \subset P_{\frac{1}{\sigma^2}}^{-1}([z_1, z_{M_1}]) \cap P_{\frac{1}{\sigma^2}}^{-1}([x_1, x_{M_0}]) . \]

Now let \( \Pi := \{ S_{i,j} : S_{i,j} \cap I \neq \emptyset \} \). So if we have that \( \Pi \cap \Delta_1 \cap \Delta_2 \neq \emptyset \) then we have that there exists \( \mathfrak{S} \in \{Id, H\} \) such that for any \( S_{i,j} \in \Pi \cap (\Delta_1 \cup \Delta_2) \) we have:

There exists \( R_{i,j} \in SO(2) \) such that \( L^2 \left( \{ x \in S_{i,j} : d(Dv(x), R_{i,j}\mathfrak{S}) > \kappa^{\frac{\omega}{\sigma}} \} \right) < 20c_3 \epsilon \kappa^{-8} \kappa^{\frac{\omega}{\sigma}} (\epsilon \kappa^{m_0})^2 . \) \hspace{1cm} (180)

We will estimate \( \text{Card} (\Pi \setminus (\Delta_1 \cup \Delta_2)) \). Since for any \( k_1 \in \{1, 2, \ldots M_1\} \), \( k_2 \in \{1, 2, \ldots M_2\} \)

\[ \text{Card} (Z_{k_1} \cap Y_{k_2} \leq c_4) \]

for some constant \( c_4 = c(\sigma) \). So for any \( k_1 \in \{1, 2, \ldots M_1\} \) we have

\[ \text{Card} \left( Z_{k_1} \cap \left( \bigcup_{k_2 \in \{1, \ldots M_1\} \setminus P_2} Y_{k_2} \right) \right) = \text{Card} \left( \bigcup_{k_2 \in \{1, \ldots M_1\} \setminus P_2} Z_{k_1} \cap Y_{k_2} \right) \leq \text{Card} (\{1, \ldots M_1\} \setminus P_2) c_4 . \] \hspace{1cm} (181)
So by (177), (175)
\[
\text{Card} \left( \bigcup_{k_1 \in \{1, \ldots, M_0\} \setminus Q_2} Z_{k_1} \right) \cap \left( \bigcup_{k_2 \in \{1, \ldots, M_1\} \setminus P_2} Y_{k_2} \right) \leq \sum_{k_1 \in \{1, \ldots, M_0\} \setminus Q_2} \text{Card} \left( Z_{k_1} \cap \left( \bigcup_{k_2 \in \{1, \ldots, M_1\} \setminus P_2} Y_{k_2} \right) \right) \\
\leq \text{Card} \left( \{1, \ldots, M_0\} \setminus Q_2 \right) \text{Card} \left( \{1, \ldots, M_1\} \setminus P_2 \right) c_4 \\
\leq 100 c_4^2 \frac{\kappa_2^2}{\kappa_2 \omega_0}.
\]

Now
\[
\Pi \setminus (\Delta_1 \cup \Delta_2) = (\Pi \setminus \Delta_1) \cap (\Pi \setminus \Delta_2) \\
\subset \left( \bigcup_{k_1 \in \{1, \ldots, M_0\} \setminus Q_2} Z_{k_1} \right) \cap \left( \bigcup_{k_2 \in \{1, \ldots, M_1\} \setminus P_2} Y_{k_2} \right)
\]
So
\[
\text{Card} \left( \Pi \setminus (\Delta_1 \cup \Delta_2) \right) \leq 400 c_4 \frac{\kappa_2^2}{\kappa_2 \omega_0}
\]
and thus \( \Pi \cap \Delta_2 \cap \Delta_2 \neq \emptyset \) and so (180) is true.
Now the arguments are completely analogous no matter what \( \mathcal{S} \) is, however as the details are slightly more intricate when \( \mathcal{S} = H \) we will deal with this case.

See fig 33.

Let \( \gamma_1, \ldots, \gamma_4 > 1 \) be some numbers we will decide on later. Let \( \theta_1 := a + \gamma_1 \phi_1, \theta_2 := a - \gamma_2 \phi_1, \theta_3 := a + \gamma_3 \phi_2 \) and \( \theta_4 := a - \gamma_4 \phi_2 \).

We assume \( \gamma_1, \ldots, \gamma_4 \) have been chosen so that \( \theta_1 \in P_0^{-1}(x_{k_1}) \) for some \( k_1 \in Q_2 \) and \( \theta_2 \in P_0^{-1}(x_{k_2}) \) for some \( k_2 \in Q_2 \). And \( \theta_3 \in P_0^{-1}(z_{k_3}) \) for some \( k_3 \in P_2 \) and \( \theta_4 \in P_0^{-1}(z_{k_4}) \) for some \( k_4 \in P_2 \). We also assume (using (175),(177) that)
\[
|\gamma_i - \gamma_j| < 20 c_4 \kappa \text{ for any } i, j \in \{1, \ldots, 4\}.
\]

As shown on fig 33. Let \( \mathcal{D} \) denote the region enclosed by the lines \( \{\theta_1 + \langle \phi_1 \rangle\}, \{\theta_2 + \langle \phi_1 \rangle\}, \{\theta_3 + \langle \phi_2 \rangle\} \) and \( \{\theta_4 + \langle \phi_2 \rangle\} \) as shown.

Now we assume \( c_3 \) has been chosen such that \( \{\gamma_i\} \) can be chosen so that \( I_2 := P(a, \phi_1, \phi_2, c_{11} \kappa^{\text{mod}}) \subset \mathcal{D} \) (for some \( c_{11} > 0 \) we will decide on later) and \( \mathcal{D} \subset I \).

We assume \( c_{11} > 0 \) is sufficiently smaller than \( \gamma_1 \) so that we can find \( k_1 \in Q_2 \) such that \( x_{k_1} \in P_{0^{-1}}(\mathcal{D} \setminus I_2) \) with \( P_{0^{-1}}(x_{k_1}) \cap \{a + \alpha \phi_1 : \alpha > 0\} \neq \emptyset \). In the same way we can find \( k_3 \in Q_2 \) such that \( x_{k_3} \in P_{0^{-1}}(\mathcal{D} \setminus I_2) \) and \( P_{0^{-1}}(x_{k_3}) \cap \{a - \alpha \phi_1 : \alpha > 0\} \neq \emptyset \). We also can find \( k_2, k_4 \) with \( z_{k_2}, z_{k_4} \in P_{0^{-1}}(\mathcal{D} \setminus I_2) \) and \( P_{0^{-1}}(z_{k_2}) \cap \{a + \alpha \phi_2 : \alpha > 0\} \neq \emptyset, P_{0^{-1}}(z_{k_4}) \cap \{a + \alpha \phi_1 : \alpha \leq 0\} \neq \emptyset \).
Step 5 We will show for \( j \in \{1,3\} \)
- For any \( y_1, y_2 \in \mathcal{D} \cap P_1^{-1}(x_k) \) where \( k_1 \in Q_2 \) and \( |y_1 - y_2| > \sqrt{\kappa} \) we have
  \[
  |v(y_1) - v(y_2)| \leq \left( 1 - c_5 \kappa^{\frac{m}{m+1}} \right) \left( 1 + c_5 \kappa^{\frac{m}{m+1}} \right).
  \]
  And specifically we have
  \[
  H^1([y_1, y_2]) \leq \left( 1 + c_5 \kappa^{\frac{m}{m+1}} \right) |P_{\phi^i}(y_1 - y_2)|
  \]
- For \( j \in \{2,4\} \) and for any \( y_3, y_4 \in \mathcal{D} \cap P_2^{-1}(z_k) \) where \( k_2 \in P_2 \) and \( |y_3 - y_4| > \sqrt{\kappa} \) we have
  \[
  |v(y_3) - v(y_4)| \leq \left( 1 - c_5 \kappa^{\frac{m}{m+1}} \right) \left( 1 + c_5 \kappa^{\frac{m}{m+1}} \right).
  \]
  And specifically we have
  \[
  H^1([y_3, y_4]) \leq \left( 1 + c_5 \kappa^{\frac{m}{m+1}} \right) |P_{\phi^i}(y_3 - y_4)|
  \]

We will argue only the case where \( y_1, y_2 \in \mathcal{D} \cap P_1^{-1}(x_k) \), \( k_j \in Q_2 \). The case where \( y_3, y_4 \in \mathcal{D} \cap P_2^{-1}(z_k) \) for \( k_j \in P_2 \) follows in exactly the same way.

We start by establishing (184). Let \( L = \{ x \in [y_1, y_2] : d(Dv(x), SO(2)H) \leq \kappa^{\frac{m}{m+1}} \} \). For each \( x \in [y_1, y_2] \) let \( W(x) \in SO(2)H \) be such that

\[
 d(Dv(x), SO(2) \cup SO(2)H) = |Dv(x) - W(x)|.
\]

So by (178) we have \( L^1([y_1, y_2]) \leq c_2 \kappa^{\frac{m}{m+1}} \) and so

\[
 H^1(v([y_1, y_2])) - |y_1 - y_2| H^1 \Omega_1 = \left| \int_{[y_1, y_2]} (|Dv(x)\Omega_1| - |H\Omega_1|) dH^1 x \right|
\]

\[
 \leq \int_L |Dv(x) - W(x)| dL^1 x + \int_{[y_1, y_2]\setminus L} |Dv(x)| + |H\Omega_1| dL^1 x
\]

\[
 \leq \kappa^{\frac{m}{m+1}} |y_1 - y_2| + 2c_2 \sigma^{-2} \kappa^{\frac{m}{m+1}}
\]

\[
 \leq 4 \sigma^{-2} c_2 |y_1 - y_2| \kappa^{\frac{m}{m+1}} - \frac{1}{2}.
\]

Now as we know from (48), \( |y_1 - y_2| |H\Omega_1| = |P_{\phi^i}(y_1 - y_2)| \) and thus

\[
 H^1(v([y_1, y_2])) - |P_{\phi^i}(y_1 - y_2)| \leq 4 \sigma^{-2} c_2 |y_1 - y_2| \kappa^{\frac{m}{m+1}} - \frac{1}{2}.
\]

So this establishes (184).

Now we will show

\[
 |v(y_1) - v(y_2)| \geq |P_{\phi^i}(y_1 - y_2)| \left( 1 - \kappa^{\frac{m}{m+1}} \right).
\]

We appeal to Lemma 4 where it was shown that for any two points \( \epsilon_1, \epsilon_2 \in v(S) \) such that \( \epsilon_1, \epsilon_2 \in v(S) \) and

\[
 \int_{[\epsilon_1, \epsilon_2]} d(Dv(v^{-1}(z)), K) dL^1 x < \kappa^{\frac{m}{m+1}} |\epsilon_1 - \epsilon_2|
\]

we have

\[
 |\epsilon_1 - \epsilon_2| \geq \left( 1 - 2\sigma^{-2} \kappa^{\frac{m}{m+1}} \right) |\Psi_1(\epsilon_1) - \Psi_1(\epsilon_2)|.
\]

By the area formula we have \( \int_{v(S)} J(x) dL^2 x \leq \sigma^{-2} \kappa^{\frac{m}{m+1}} \epsilon^2 \) so by Fubini we must be able to find interval \([\epsilon_1, \epsilon_2]\) parallel to \([v(y_1), v(y_2)]\) with

\[
 \int_{[\epsilon_1, \epsilon_2]} d(Dv(v^{-1}(x)), K) dL^1 x \leq \kappa^{\frac{m}{m+1}} \epsilon \leq \kappa^{\frac{m}{m+1}} |\epsilon_1 - \epsilon_2|.
\]
And \( \iota_1 \in N_{\frac{m_0}{\kappa^{\frac{1}{32}}}}(v(y_1)) \) and \( \iota_2 \in N_{\frac{m_0}{\kappa^{\frac{1}{32}}}}(v(y_2)) \). So by Lemma 4 we have
\[
|\iota_1 - \iota_2| \geq \left(1 - 2\sigma^{-2}\frac{m_0}{\kappa^{\frac{1}{32}}}ight)|\Psi_1(\iota_1) - \Psi_1(\iota_2)|.
\]
Now by Lipschitzness we have
\[
|v(y_1) - v(y_2)| \geq \left(1 - 5\sigma^{-2}\frac{m_0}{\kappa^{\frac{1}{32}}}ight)|\Psi_1(v(y_1)) - \Psi_1(v(y_2))|
= \left(1 - 5\sigma^{-2}\frac{m_0}{\kappa^{\frac{1}{32}}}ight)L_1(P_{\varphi_1^+([y_1, y_2])}).
\]
So this together with (187) establishes Step 5

**Step 6**

Take \( q \in \{2, 4\} \). Consider the line \((\theta_q + \langle \varphi_2 \rangle) \cap D\). We will show that there exists \( R_q \in SO(2) \) such that for any \( z \in (\theta_q + \langle \varphi_2 \rangle) \cap D \) with \( |z - \theta_q| > \sqrt{\kappa} \) we have
\[
v(z) \in B_{\frac{m_0}{c\kappa^{\frac{1}{32}}}}\left(v(\theta_q) + R_q H (z - \theta_q)\right).
\] (188)

And similarly for \( q \in \{1, 3\} \). For the line \((\theta_q + \langle \varphi_1 \rangle) \cap D\) we will show that there exists \( R_q \in SO(2) \) such that for any \( z \in (\theta_q + \langle \varphi_1 \rangle) \cap D \) with \( |z - \theta_q| > \sqrt{\kappa} \) we have
\[
v(z) \in B_{\frac{m_0}{c\kappa^{\frac{1}{32}}}}\left(v(\theta_q) + R_q H (z - \theta_q)\right).
\] (189)

We argue only the case \( q = 1 \). All other cases follow in exactly the same way. Observe fig 34 below.

![Figure 34](image)

Firstly by the Pythagoras type arguments coming from Lemma 5 (see in particular fig 7) (183) implies that
\[
v([o_1, o_2]) \subset N_{\frac{m_0}{\kappa^{\frac{1}{32}}}}(v(\theta_1) + l)
\] (190)
for some \( l \in G(1, 2) \).

Let \( \psi_1 \in S^1 \) be such that \( \langle \psi_1 \rangle = l \) and \( \psi_1 \cdot \left(\frac{v(o_2) - v(o_1)}{|v(o_2) - v(o_1)|}\right) > 0 \). Let \( R_1 \in SO(2) \) be the rotation such that
\[
R_1 \left(\frac{o_2 - o_1}{|o_2 - o_1|}\right) = \psi_1.
\]
Now for any \( z \in (\theta_1 + \langle \varphi_1 \rangle) \cap D \) with \( |z - \theta_1| > \sqrt{\kappa} \) and \( z \cdot (-\varphi_1) \geq \theta_1 \cdot (-\varphi_1) \). Let \( \tilde{R} \) be a rotation such that
\[
\tilde{R} \left(\frac{z - \theta_1}{|z - \theta_1|}\right) = \frac{v(z) - v(\theta_1)}{|v(z) - v(\theta_1)|} \approx \psi_1.
\]
So
\[
v(z) = v(\theta_1) + |v(z) - v(\theta_1)| \tilde{R} \left(\frac{z - \theta_1}{|z - \theta_1|}\right).
\] (191)
Now (190) we know 
\[ |(v(z) - v(\theta_1)) \cdot \psi_1| \leq \frac{\kappa m \epsilon}{\sigma^2} \]
and so
\[ |(v(z) - v(\theta_1)) \cdot \psi_1| \geq |v(z) - v(\theta_1)| - |(v(z) - v(\theta_1)) \cdot \psi_1| \]
\[ \geq |v(z) - v(\theta_1)| - \frac{\kappa m \epsilon}{\sigma^2}. \]  
(192)

So as we know by Bilipschitzness that
\[ |v(z) - v(\theta_1)| \geq \sigma^{-2} |z - \theta_1| \]
\[ \geq \sigma^{-2} \sqrt{\kappa \epsilon}. \]  
(193)

And as \( \frac{z_2 - \theta_1}{|z_2 - \theta_1|} = \frac{z - \theta_1}{|z - \theta_1|} = -\hat{\phi}_1 \) we have
\[
\left| \left( R_1 - \bar{R} \right) \cdot \hat{\phi}_1 \right| = \left| \psi_1 - \frac{v(z) - v(\theta_1)}{|v(z) - v(\theta_1)|} \right| \leq \frac{1 - (v(z) - v(\theta_1)) \cdot \psi_1}{|v(z) - v(\theta_1)|} + \frac{(v(z) - v(\theta_1)) \cdot \psi_1}{|v(z) - v(\theta_1)|} \leq \frac{2\epsilon \sqrt{\kappa \epsilon}}{\sigma^2 \sqrt{\kappa \epsilon}} \leq \frac{c_5 \kappa m 512}{\sqrt{\kappa \epsilon}}.
\]
which implies \( |R_1 - \bar{R}| \leq c_5 \kappa m 512 \).

Now putting this together with (191) we have from (190), (192) and (193)
\[ v(z) \in B_{c_5 \epsilon m 512} \left( v(\theta_1) + |v(z) - v(\theta_1)| R_1 \left( \frac{z - \theta_1}{|z - \theta_1|} \right) \right) \]
which completes the proof of (189) for the case \( z \cdot (-\hat{\phi}_1) \geq \theta_1 \cdot (-\hat{\phi}_1) \).

Now if \( z \cdot (-\hat{\phi}_1) < \theta_1 \cdot (-\hat{\phi}_1) \) we let \( \bar{R} \) be the rotation such that
\[ \bar{R} \left( \frac{z - \theta_1}{|z - \theta_1|} \right) = \frac{v(z) - v(\theta_1)}{|v(z) - v(\theta_1)|} \approx -\psi_1 \]  
(194)
but since \( \frac{z - \theta_1}{|z - \theta_1|} = \hat{\phi}_1 \) we can see as before (since \( R_1 (\hat{\phi}_1) = -\psi_1 \)) that \( |\bar{R} - R_1| \leq c_5 \kappa m 512 \) so again by using this with an unscrambling of (194) we have complete the proof of (189).

Step 7. We will show \( v(\mathcal{D}) \) is (roughly) mapped onto a parallelogram congruent to \( H(\mathcal{D}) \).

First we find the corners of the shape \( \mathcal{D} \). Let \( a_1 := (\theta_1 + (\hat{\phi}_1)) \cap (\theta_4 + (\hat{\phi}_2)) \), \( a_2 := (\theta_1 + (\hat{\phi}_1)) \cap (\theta_3 + (\hat{\phi}_2)) \), \( a_3 := (\theta_2 + (\hat{\phi}_1)) \cap (\theta_3 + (\hat{\phi}_2)) \), \( a_4 := (\theta_2 + (\hat{\phi}_1)) \cap (\theta_4 + (\hat{\phi}_2)) \).

Let \( \mathcal{X} \) denote the shape contained by the lines
\[ \{(v(a_1), v(a_2)), [v(a_1), v(a_4)], [v(a_2), v(a_4)], [v(a_3), v(a_4)]\}. \]

Note \( |(a_1 - a_4) \cdot \phi_1^\perp| = |(a_2 - a_3) \cdot \phi_2^\perp| =: \alpha \) and \( |(a_1 - a_2) \cdot \phi_2^\perp| = |(a_3 - a_4) \cdot \phi_2^\perp| =: \beta \) by Step 5 (see fig 33) we have
\[ |v(a_4) - v(a_1)| \in \left[ \left( 1 - c_5 \kappa \frac{m 512}{\sigma^2} \right) \alpha, \left( 1 + c_5 \kappa \frac{m 512}{\sigma^2} \right) \alpha \right] \]
and
\[ |v(a_2) - v(a_3)| \in \left[ \left( 1 - c_5 \kappa \frac{m 512}{\sigma^2} \right) \alpha, \left( 1 + c_5 \kappa \frac{m 512}{\sigma^2} \right) \alpha \right]. \]
And also by Step 5 we have
\[ |v(a_1) - v(a_2)| \in \left[ \left( 1 - c_5 \kappa \frac{m 512}{\sigma^2} \right) \beta, \left( 1 + c_5 \kappa \frac{m 512}{\sigma^2} \right) \beta \right] \]
and
\[ |v(a_4) - v(a_3)| \in \left[ \left( 1 - c_5 \kappa \frac{m 512}{\sigma^2} \right) \beta, \left( 1 + c_5 \kappa \frac{m 512}{\sigma^2} \right) \beta \right]. \]
So $\mathcal{X}$ must be roughly a parallelogram. Formally, there exists a parallelogram $\tilde{\mathcal{X}}$ such that

$$H(\mathcal{X}, \tilde{\mathcal{X}}) \leq c_7 \kappa \frac{\min}{m_0^2} \epsilon.$$  

Now by Step 6 we have that $H(v(\mathcal{D}), \mathcal{X}) \leq c_6 \kappa \frac{\min}{m_0} 1024 \epsilon$ and so

$$H(\tilde{\mathcal{X}}, v(\mathcal{D})) \leq 4c_7 \kappa \frac{\min}{m_0} 1024 \epsilon.$$ (195)

By the fact that $\int_{\mathcal{D}} J(x) dL^2 x \leq \sigma^{-2} \kappa \frac{\min}{m_0^2} L^2(\mathcal{D})$ we have

$$L^2(v(\mathcal{D})) \in \left( (1 - \kappa \frac{\min}{m_0} \kappa^2), (1 + \kappa \frac{\min}{m_0} \kappa^2), L^2(\mathcal{D}) \right)$$

and so

$$L^2(\tilde{\mathcal{X}}) \in \left( (1 - 4c_7 \kappa \frac{\min}{m_0^2}) L^2(\mathcal{D}), (1 + 4c_7 \kappa \frac{\min}{m_0^2}) L^2(\mathcal{D}) \right).$$

Now given that the size lengths of $\tilde{\mathcal{X}}$ are prescribed and are (upto error $2c_7 \kappa \frac{\min}{m_0^2} \epsilon$) the same side lengths as $H(\mathcal{D})$, there can only be two possible parallelogram with volume equal to $L^2(\mathcal{D})$. So (see fig 35) $v(\mathcal{D})$ is mapped (roughly) onto one of two possible parallelograms, as shown.

![Figure 35](image)

**Figure 35**

We know of course that $H$ maps $\mathcal{D}$ onto a parallelogram and $L^2(H(\mathcal{D})) = L^2(\mathcal{D})$. So $H(\mathcal{D})$ is one of the parallelograms shown in fig 35, in fact its parallelogram show is Case 2.

We will show that $v(\mathcal{D})$ is mapped onto the parallelogram given by $H(\mathcal{D})$. The fig 36 below shows $H(\mathcal{D})$.

![Figure 36](image)

**Figure 36**

Now by Step 5 and (49) we see

$$|v(\theta_4) - v(o_1)| \leq \left( 1 + c_5 \kappa \frac{\min}{m_0} \right) |H(\theta_4 - o_1)|$$

and

$$|v(\theta_1) - v(o_1)| \leq \left( 1 + c_5 \kappa \frac{\min}{m_0} \right) |H(\theta_1 - o_1)|.$$
So if we had Case 2 and $v(o_1)$ was mapped to one of the sharp corners of the parallelograms, then $v(\theta_1)$ would be within $(1+c_{gK}^\frac{m_0}{m_0}) |H(\theta_1-o_1)|$ of the sharp corner and $v(\theta_2)$ would also be within $(1+c_{gK}^\frac{m_0}{m_0}) |H(\theta_2-o_2)|$ of the sharp corner.

In the same way $v(\theta_3)$ and $v(\theta_4)$ would be (respectively) within distance $(1+c_{gK}^\frac{m_0}{m_0}) |H(\theta_3-o_3)|$ of the opposite sharp corner. Now as can be seen from the (36), in this case $|v(\theta_1)-v(\theta_3)|$ would have to be $\geq (1+c_8) |H(\theta_1-\theta_3)|$ for some not so small constant $c_8 = c(\sigma) > 0$. However as $\theta_1, \theta_4 \in (\sigma + \phi_1)$ we have that $|v(\theta_1)-v(\theta_3)| \leq (1+\kappa^2) |\theta_1-\theta_3| = (1+\kappa^2) |H(\theta_1-\theta_3)|$ and this gives as a contradiction.

So we must have Case 1, which is to say $v(\mathcal{D})$ is (roughly) mapped onto a parallelogram congruent $H(\mathcal{D})$. Formally, (195) implies that for some $\zeta \in \mathbb{R}^2$ we have

$$H(v(\mathcal{D}), H(\mathcal{D}) + \zeta) \leq 42c_{gK}^\frac{m_0}{m_0} \epsilon. \quad (196)$$

**Step 8.** We will use this to prove that for some $R \in SO(2)$ such that for any $x \in \partial \mathcal{D} \setminus \bigcup_{i=1}^4 B_{\sqrt{\kappa \epsilon}}(\theta_i)$ we have

$$v(x) \in B_{42c_{gK}^\frac{m_0}{m_0} \epsilon}(v(\theta_1) + RH(x-\theta_1)). \quad (197)$$

We start by noting that since $v(\mathcal{D})$ is an almost parallelogram (see (196)) we know that $R_1$ and $R_3$ from (189) are such that

$$|R_1 - R_3| < 42c_{gK}^\frac{m_0}{m_0} \epsilon \quad (198)$$

and $R_2, R_4$ from (188) are such that

$$|R_2 - R_4| < 2c_{gK}^\frac{m_0}{m_0} \epsilon. \quad (199)$$

So it suffices to show

$$|R_3 - R_4| < 8c_{gK}^\frac{m_0}{m_0} \epsilon. \quad (200)$$

Now by (188) and (189) we have for any $z \in (\theta_4 + \langle \phi_2 \rangle) \cap \mathcal{D} \setminus B_{\sqrt{\kappa \epsilon}}(o_4)$ that

$$v(z) \in B_{c_{gK}^\frac{m_0}{m_0} \epsilon}(v(o_4) + R_4H(z-o_4)) \quad (201)$$

and for any $z \in (\theta_3 + \langle \phi_1 \rangle) \cap \mathcal{D} \setminus B_{\sqrt{\kappa \epsilon}}(o_4)$ we have

$$v(z) \in B_{c_{gK}^\frac{m_0}{m_0} \epsilon}(v(o_4) + R_3H(z-o_4)) \quad (202)$$

Now from (201), (202) we have

$$(v(o_1) - v(o_4)) \cdot (v(o_3) - v(o_4)) \in B_{2c_{gK}^\frac{m_0}{m_0} \epsilon}(R_4H(o_1-o_4) \cdot R_3H(o_3-o_4))$$

However by Step 7 we know $v(\mathcal{D})$ is mapped onto a rectangle congruent to $H(\mathcal{D})$ and so the arrangement of corners is as shown on Case 2, fig 36. And so, as can be seen from these diagrams, (196) implies that

$$(v(o_1) - v(o_4)) \cdot (v(o_3) - v(o_4)) \in B_{4c_{gK}^\frac{m_0}{m_0} \epsilon}(H(o_1-o_4) \cdot H(o_3-o_4))$$

So

$$R_4H(o_1-o_4) \cdot R_3H(o_3-o_4) \in B_{4c_{gK}^\frac{m_0}{m_0} \epsilon}(H(o_1-o_4) \cdot H(o_3-o_4))$$

and thus

$$R_3^{-1}R_4H(o_1-o_4) \cdot H(o_3-o_4) \in B_{8c_{gK}^\frac{m_0}{m_0} \epsilon}(H(o_1-o_4) \cdot H(o_3-o_4)).$$

So there are two possibilities. Either $R_3^{-1}R_4$ is close to the identity or $R_3^{-1}R_4$ flips $H(o_1-o_4)$ onto the other side of $H(o_3-o_4)$ as shown on fig 37. We will gain a contradiction from the possibility that $R_3^{-1}R_4$ is not close to the identity in the following way. Observe figure 38.

Now we can assume we have chosen $\{\theta_1, \theta_2, \theta_3, \theta_4\}$ such that

$$\int_{[o_4,o_1]} d(Dv(x), SO(2) \cup SO(2) H) dL^1 x < \kappa |o_4-o_1|$$

and

$$\int_{[o_4,o_3]} d(Dv(x), SO(2) \cup SO(2) H) dL^1 x < \kappa |o_4-o_3|$$
and so (as shown) we must be able to find $\alpha_1 \in [o_4, o_3]$ and $\alpha_2 \in [o_4, o_1]$ such that $\alpha_2 - \alpha_1$ is parallel to $\phi_1$, 

$$d(Dv(\alpha_1), SO(2) \cup SO(2)H) < \kappa$$

and

$$\int_{[\alpha_1, \alpha_2]} d(Dv(z), SO(2) \cup SO(2)H) dL^1z \leq \kappa |\alpha_1 - \alpha_2|.$$  \hspace{1cm} (203)

Now since $v((\alpha_1, \alpha_2))$ can not pass through $v([o_4, o_3])$ or $v([o_4, o_1])$ by Bilipschitzness. And more importantly since at point $\alpha_1$ (as the $Dv(\alpha_1)$ is orientation preserving) the “triple junction” formed by the lines $[o_4, o_3]$ and $[\alpha_1, \alpha_2]$ must be mapped to a “similar” “triple junction” of $v([o_4, o_3])$ and $v([\alpha_1, \alpha_2])$. See figure 39.
So \( v([\alpha_1, \alpha_2]) \) is forced to take a journey around the outside of \( v([\alpha_3, \alpha_4]) \cup v([\alpha_1, \alpha_4]) \) as shown in fig 38. But this means
\[
H^1(v([\alpha_1, \alpha_2])) > (1 + c_{10}) |\alpha_1 - \alpha_2|
\]
for some not small constant \( c_{10} = c(\sigma) > 0 \).

However (203) since \( \phi_1 \) is a rank-1 direction for \( H \) we have
\[
H^1(v([\alpha_1, \alpha_2])) = \int_{[\alpha_1, \alpha_2]} |Dv(z)\phi_1| dL^1 z \leq (1 + k) |\alpha_1 - \alpha_2|
\]
which contradicts (204). So finally we have a contradiction from the assumption that \( R_3^{-1}R_4 \) flips \( v(\alpha_1 - \alpha_4) \) onto the other side of \( H(\alpha_1 - \alpha_4) \). So we must have the only other possibility which is
\[
R_3^{-1}R_4 \in N_{\theta_1, \theta_2} \text{(Id)} ,
\]
and this establishes (200).

Now we will use this prove (197). We will argue for \( z \in [\alpha_4, \alpha_1] \setminus B_{\sqrt{\kappa}}(\theta_2) \). See fig 33, by (189) and (198),(199), (205) we have
\[
v(z) - v(\alpha_4) \in B_{20\epsilon_k} \text{(R_1H(\alpha_4 - \alpha_1))}
\]
and by (188), (198), (199), (205)
\[
v(\alpha_4) - v(\alpha_1) \in B_{20\epsilon_k} \text{(R_1H(\alpha_1 - \alpha_1))}
\]
and finally by (189)
\[
v(\alpha_1) - v(\theta_1) \in B_{20\epsilon_k} \text{(R_1H(\alpha_1 - \theta_1))}.
\]
Now by adding together (206), (207) and (208) we have
\[
v(z) \in B_{42\epsilon_k} \text{(R_1H(z - \theta_1) + v(\theta_1))}
\]
and this establishes (197).

The cases, \( z \in [\alpha_1, \alpha_4] \setminus B_{\sqrt{\kappa}}(\theta_1) \), \( z \in [\alpha_2, \alpha_4] \setminus B_{\sqrt{\kappa}}(\theta_2) \), \( z \in [\alpha_2, \alpha_3] \setminus B_{\sqrt{\kappa}}(\theta_3) \) and can be argued in the same way.

Step 8

Now we assume \( \gamma_1, \gamma_2, \gamma_3, \gamma_4 \) have been chosen big enough so that if \( \tau_1 \in \Delta \) is the element of the triangulation that contains \( a \), then \( \tau_1 \subset D \). Let \( \{\omega_1, \omega_2, \omega_3\} \) denote the corners of \( \tau_1 \). Now by assumption, none of the edges of \( \tau_1 \) are close to being parallel to the axis \( \phi_1, \phi_2 \). So we have that
\[
\text{Card}(\{\omega_1, \omega_2, \omega_3\} \cap (N_{\sqrt{\kappa}}(a + \Phi_1) \cup N_{\sqrt{\kappa}}(a + \Phi_2))) \leq 1.
\]

If \( \{\omega_1, \omega_2, \omega_3\} \cap (N_{\sqrt{\kappa}}(a + \Phi_1) \cup N_{\sqrt{\kappa}}(a + \Phi_2)) = \emptyset \) then the situation is even simpler, so we will argue the case where the interaction is non-empty.

So without loss of generality assume
\[
\{\omega_1\} = \{\omega_1, \omega_2, \omega_3\} \cap N_{\sqrt{\kappa}}(a + \Phi_1).
\]

Let \( \gamma_1, \gamma_2, \gamma_3, \gamma_4 > 0 \) be numbers we decide on later and let \( \hat{\theta}_1 := a + \gamma_1 \phi_1 \), \( \hat{\theta}_2 := a - \gamma_2 \phi_1 \), \( \hat{\theta}_3 := a + \gamma_3 \phi_2 \) and \( \hat{\theta}_4 := a + \gamma_4 \phi_2 \). By (175) and (177) we can assume \( \gamma_1, \gamma_2, \gamma_3, \gamma_4 \) have been chosen so that
\[
\bullet \: \hat{\theta}_1 \in P_{\gamma_1}(x_{k_5}) \text{ for some } k_5 \in Q_2, \hat{\theta}_2 \in P_{\gamma_2}(x_{k_6}) \text{ for some } k_6 \in Q_2, \hat{\theta}_3 \in P_{\gamma_3}(z_{k_7}) \text{ for some } k_7 \in P_2 \text{ and } \hat{\theta}_4 \in P_{\gamma_4}(z_{k_8}) \text{ for some } k_8 \in P_2.
\]
\[
\bullet \: \omega_1 \in N_{20\epsilon_k}(P_{\gamma_1}(\hat{\theta}_1)), \omega_2 \in N_{20\epsilon_k}(P_{\gamma_2}(\hat{\theta}_2)), \omega_3 \in N_{20\epsilon_k}(P_{\gamma_3}(\hat{\theta}_3)) \text{ and } \omega_3 \in N_{20\epsilon_k}(P_{\gamma_4}(\hat{\theta}_4)).
\]

Note that this last condition together with (210) implies \( \omega_1 \in N_{\sqrt{\kappa}}(\hat{\theta}_1) \). Let \( \tilde{D} \) denote the region enclosed by
\[
\{ (\hat{\theta}_1 \pm \langle \hat{\theta}_1 \rangle), (\hat{\theta}_2 \pm \langle \hat{\theta}_2 \rangle), (\hat{\theta}_3 \pm \langle \hat{\theta}_3 \rangle), (\hat{\theta}_4 \pm \langle \hat{\theta}_4 \rangle) \}.
\]
Either by arguments entirely analogous to those we used to establish (197) or by using (197) directly to show that \( v \left( \tilde{D} \right) \) isn’t mapped onto the “wrong parallelogram” (the one that isn’t \( H \left( \tilde{D} \right) \)) we can establish the following:

There exits \( R \in SO \left( 2 \right) \) such that for any

\[
x \in \partial \tilde{D} \setminus \bigcup_{j=1}^{4} B_{\kappa_{\epsilon}} \left( \tilde{\theta}_{j} \right)
\]

that

\[
v \left( x \right) \in B_{\kappa_{\epsilon}} \left( v \left( \tilde{\theta}_{i} \right) + RH \left( x - \tilde{\theta}_{i} \right) \right) \subset B_{\kappa_{\epsilon}} \left( v \left( \omega_{1} \right) + RH \left( x - \omega_{1} \right) \right).
\]

This of course implies that

\[
v \left( \omega_{2} \right) \in B_{\kappa_{\epsilon}} \left( v \left( \omega_{1} \right) + RH \left( \omega_{2} - \omega_{1} \right) \right) \quad \text{(211)}
\]

\[
v \left( \omega_{3} \right) \in B_{\kappa_{\epsilon}} \left( v \left( \omega_{1} \right) + RH \left( \omega_{3} - \omega_{1} \right) \right) \quad \text{(212)}
\]

Now let \( A \) be the affine map we get by interpolating \( v \) on the corners \( \{ \omega_{1}, \omega_{2}, \omega_{3} \} \). So \( A = L + \zeta \) where \( L \in M^{2 \times 2} \) and \( \zeta \in \mathbb{R}^{2} \). Thus we have

\[
v \left( \omega_{2} \right) - v \left( \omega_{1} \right) = L \left( \omega_{2} - \omega_{1} \right) \quad \text{and} \quad v \left( \omega_{3} \right) - v \left( \omega_{1} \right) = L \left( \omega_{3} - \omega_{1} \right). \text{As}
\]

from (211) and (212) we have

\[
L \left( \omega_{2} - \omega_{1} \right) = v \left( \omega_{2} \right) - v \left( \omega_{1} \right) \in B_{\kappa_{\epsilon}} \left( RH \left( \omega_{2} - \omega_{1} \right) \right)
\]

\[
L \left( \omega_{3} - \omega_{1} \right) = v \left( \omega_{3} \right) - v \left( \omega_{1} \right) \in B_{\kappa_{\epsilon}} \left( RH \left( \omega_{3} - \omega_{1} \right) \right).
\]

This implies

\[
L \left( \frac{\omega_{2} - \omega_{1}}{\omega_{2} - \omega_{1}} \right) \in \left\{ \frac{z}{\omega_{2} - \omega_{1}} : z \in B_{\kappa_{\epsilon}} \left( RH \left( \omega_{2} - \omega_{1} \right) \right) \right\}
\]

\[
\subset B_{\frac{c_{12}R}{\kappa_{\epsilon}}} \left( RH \left( \frac{\omega_{2} - \omega_{1}}{\omega_{2} - \omega_{1}} \right) \right) \quad \text{(213)}
\]

and

\[
L \left( \frac{\omega_{3} - \omega_{1}}{\omega_{3} - \omega_{1}} \right) \in \left\{ \frac{z}{\omega_{3} - \omega_{1}} : z \in B_{\kappa_{\epsilon}} \left( RH \left( \omega_{3} - \omega_{1} \right) \right) \right\}
\]

\[
\subset B_{\frac{c_{12}}{\kappa_{\epsilon}}} \left( RH \left( \frac{\omega_{3} - \omega_{1}}{\omega_{3} - \omega_{1}} \right) \right). \quad \text{(214)}
\]

So \( \left| \left( L - RH \right) \left( \frac{\omega_{2} - \omega_{1}}{\omega_{2} - \omega_{1}} \right) \right| \leq \frac{c_{12}R}{\kappa_{\epsilon}} \) and \( \left( L - RH \right) \left( \frac{\omega_{2} - \omega_{1}}{\omega_{2} - \omega_{1}} \right) \leq \frac{c_{12}}{\kappa_{\epsilon}} \).

From this it follows easily that \( \left| L - RH \right| \leq \frac{c_{13}R}{\kappa_{\epsilon}} \). And so for Case 1, where \( \text{Card} \left( G_{0}^{\left( 2 \right)} \right) \geq \text{Card} \left( G_{0}^{\left( 1 \right)} \right) \) we have established the lemma.

Case 2 where \( \text{Card} \left( G_{0}^{\left( 1 \right)} \right) \geq \text{Card} \left( G_{0}^{\left( 2 \right)} \right) \) follows via entirely analogous arguments, in fact its is even easier.

In this case we take a chain of points \( \{ z_{k_{j}} \} \in P_{n_{1}^{+}} \left( S \right) \) and \( \{ x_{k_{j}} \} \in P_{n_{2}^{+}} \left( S \right) \) so we gain control of \( v \) on the lines \( \{ P_{n_{1}^{+}}^{-1} \left( z_{k_{j}} \right) \cap S \} \) and \( \{ P_{n_{2}^{+}}^{-1} \left( x_{k_{j}} \right) \cap S \} \). Exactly analogous to what we have done in Case 1, we will show a parallelogram with sides parallel to \( n_{1} \) and \( n_{2} \) is mapped (roughly) to a rotated version of some parallelogram.

From this we harvest the approximate control on the corners of \( \tau_{i} \) and we are done.

\[ \square \]
9. Counting the Oscillation

This last lemma is one of the most crucial in the whole proof. The basic idea has been explained in section 4.3 of the introduction. As noted in the introduction, the “coarea alternative” we actually need is more subtle than the one sketched there. The basic idea behind the improved “coarea alternative” is explained in the introduction to section 7; as described we must argue the “coarea alternative” in the thin columns running up through $S$ in directions $\phi_1$ and $\phi_2$.

Given a thin rectangular region $C$ of width $w$ parallel to $\phi_1$, inside $S$ the basic rule of thumb for the relationship between the “coarea integral” of $v$ over $v(C)$ and the surface energy of $v$ over $C$ is (assuming the bulk energy of $v$ over $C$ is small enough).

$$ \frac{\int_{v(C)} J(x) |D\Theta_1(x)| \, dL^2 x}{w} \leq c \int_{C} |D^2 v(x)| \, dL^2 x $$

And the proof of this is basically as described in section 4.3 of the introduction. The rest of the proof is just arithmetic to show that the quantities add up to be what we expect.

Lemma 10. Let $v \in A_F(\Omega)$. Given skew cube $S := (a, \phi_1, \phi_2, \epsilon) \subset \Omega$. Let $m_0 \in \mathbb{N}$ be a big integer whose value we will decide on later.

Suppose for some $p \in \{1, 2\}$ we have;

- Let $\{C^p_k : k \in \{1, 2, \ldots |\kappa^{-m_0}|\}\}$ denote the set of columns of width $\kappa^{m_0}\epsilon$ going through $S$, parallel to $\phi_p$. Let $a^p_k$ denote the center point in $C^p_k$. Let $\Theta^p_k$ denote the level set function defined with respect to line $\{a^p_k + \langle \phi_k \rangle \}$. Let $E^p_k := N_{\epsilon, \kappa^{-m_0}}(C^p_k) \cap S$

Then, for each $j \in \{1, 2, \ldots Q_0\}$ and $Q_0 \geq \left(1 - \kappa^m\right)[\kappa^{-m_0}]$

$$ \sum_{j=1}^{Q_0} \int_{v(E^p_k)} J(x) |D\Theta^p_k(x)| \, dL^2 x \geq \kappa^{m_0+1}\epsilon^2 $$

Proof. Firstly we note that we have

$$ \sum_{j=1}^{Q_0} \epsilon^{-1}\kappa^{-m_0} \int_{v(E^p_k)} J(x) |D\Theta^p_k(x)| \, dL^2 x > \kappa \epsilon. $$

Let

$$ G_0 := \left\{ j \in \{1, 2, \ldots Q_0\} : \epsilon^{-1}\kappa^{-m_0} \int_{v(E^p_k)} J(x) |D\Theta^p_k(x)| \, dL^2 x \geq \kappa^{m_0+2}\epsilon \right\} $$

and let $B_0 := \{1, 2, \ldots Q_0\} \setminus G_0$.

As

$$ \sum_{j \in G_0} \epsilon^{-1}\kappa^{-m_0} \int_{v(E^p_k)} J(x) |D\Theta^p_k(x)| \, dL^2 x + \sum_{j \in B_0} \kappa^{m_0+2}\epsilon \geq \kappa \epsilon $$

we have

$$ \sum_{j \in G_0} \epsilon^{-1}\kappa^{-m_0} \int_{v(E^p_k)} J(x) |D\Theta^p_k(x)| \, dL^2 x \geq (1 - \kappa) \kappa \epsilon. $$
Let
\[ \vartheta_j := \epsilon^{-1} \kappa^{-m_0} \int_{v(E_{kj}^{(p)})} J(x) |D\Theta_k^p(x)| \, dL^2 x \]  
(216)
for \( j \in G_0 \). So
\[ \sum_{j \in G_0} \vartheta_j \geq (1 - \kappa) \kappa \epsilon \]  
(217)
and
\[ \vartheta_j \geq \kappa^{m_0+2} \epsilon \]  
(218)
for each \( j \in G_0 \).

**Claim 2.** We will show we can find \( z_0 \in P_{\phi_k} (E_{kj}^{(p)}) \) such that
\[ \int_{v(E_{kj}^{(p)}) \cap \bar{P}_{\phi_k} (z_0)} J(x) \, dH^1 x \geq \sigma^4 \vartheta_j. \]  
(219)

And
\[ \int_{v(E_{kj}^{(p)}) \cap \bar{P}_{\phi_k} (z_0)} J(x) \, dH^1 x \leq \kappa^{m_0+4} \sigma^{-4} \int_{v(E_{kj}^{(p)}) \cap \bar{P}_{\phi_k} (z_0)} J(x) \, dH^1 x \]

**Proof of Claim**

Let
\[ G_2 := \left\{ z \in P_{\phi_k} (E_{kj}^{(p)}) : \int_{v(E_{kj}^{(p)}) \cap \bar{P}_{\phi_k} (z)} J(x) \, dH^1 x \geq \kappa^{-m_0-4} \int_{v(E_{kj}^{(p)}) \cap \bar{P}_{\phi_k} (z_0)} J(x) \, dH^1 x \right\} \]

and let
\[ G_3 := \left\{ z \in P_{\phi_k} (E_{kj}^{(p)}) : \int_{v(E_{kj}^{(p)}) \cap \bar{P}_{\phi_k} (z)} J(x) \, dH^1 x \geq \sigma^4 \vartheta_j \right\}. \]

Suppose the claim is not true and so \( G_2 \cap G_3 = \emptyset \). Thus \( P_{\phi_k} (E_{kj}^{(p)}) \subset G_2^c \cup G_3^c \). By the Coarea formula
\[ \int_{v(E_{kj}^{(p)})} J(x) \, dH^1 x = \int_{z \in P_{\phi_k} (E_{kj}^{(p)}) \cap G_2} \int_{v(E_{kj}^{(p)}) \cap \bar{P}_{\phi_k} (z)} J(x) \, dH^1 x \, dL^2 z \]
\[ \leq \int_{z \in P_{\phi_k} (E_{kj}^{(p)}) \cap G_2} \int_{v(E_{kj}^{(p)}) \cap \bar{P}_{\phi_k} (z)} J(x) \, dH^1 x \, dL^2 z \]
\[ + \int_{z \in P_{\phi_k} (E_{kj}^{(p)}) \cap G_2} \int_{v(E_{kj}^{(p)}) \cap \bar{P}_{\phi_k} (z)} J(x) \, dH^1 x \, dL^2 z \]
\[ \leq \int_{z \in P_{\phi_k} (E_{kj}^{(p)})} \left( \kappa^{-m_0-4} \int_{v(E_{kj}^{(p)}) \cap \bar{P}_{\phi_k} (z)} J(x) \, dH^1 x + \sigma^4 \vartheta_j \right) \, dL^2 z \]
\[ \leq \kappa^{-m_0-4} \int_{v(E_{kj}^{(p)})} J(x) \, dL^2 x + \sigma^4 \vartheta_j L^1 (P_{\phi_k} (E_{kj}^{(p)})). \]  
(220)

Recall definition of \( \vartheta_j \), (216), rearranging (220) we have by (215) and (218) that
\[ \epsilon \kappa^{m_0} \vartheta_j - \sigma^4 \vartheta_j c_0 \kappa^{m_0} \epsilon \leq \kappa^{-m_0-4} \int_{v(E_{kj}^{(p)})} J(x) \, dL^2 x \]
\[ \leq \kappa^{2m_0+3} \epsilon^2 \]
\[ \leq \kappa^{m_0+4} \vartheta_j \epsilon \]
and as $\sigma^4 < c_0$ we have a contradiction. So we have established the claim. 

So we can find $z_0 \in G_2 \cap G_3$ such that

$$\int_{v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))} J(x) |D\Theta_{k_j}^p(x)| \, dH^1 x \geq \sigma^4 \theta_j$$

and (by the fact that $\sigma^2 \leq |D\psi_p(x)| \leq \sigma^{-2}$)

$$\int_{v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))} J(x) \, dH^1 x \leq \kappa^{m_0 + 4} \sigma^{-4} \int_{v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))} J(x) \, dH^1 x.$$  \hspace{1cm} (221)

**Claim 3.** We can find subset $U_0 \subset v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))$ such that

$$H^1(U_0) \leq \kappa^{m_0 + 3} \epsilon$$  \hspace{1cm} (222)

and

$$\int_{U_0} J(x) \, dH^1 x \geq \frac{\sigma^4}{2} \theta_j$$  \hspace{1cm} (223)

**Proof of Claim.**

Note, most of the points of $v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))$ are much less than average: Formally, let

$$U_0 := \left\{ x \in v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0)) : J(x) > \kappa^{-4} \frac{\int_{v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))} J(x) \, dH^1 x}{H^1(v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0)))} \right\}$$

so using (221) for the first inequality

$$\kappa^{m_0 + 4} \sigma^{-4} \int_{v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))} J(x) \, dH^1 x \geq \int_{U_0} J(x) \, dH^1 x \geq \kappa^{-4} \frac{\int_{v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))} J(x) \, dH^1 x}{H^1(v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0)))} \int_{U_0} \kappa^{m_0 + 3} H^1(v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))) \geq H^1(U_0).$$

So we have

$$\kappa^{m_0 + 3} H^1(v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))) \geq H^1(U_0).$$

Let

$$D_0 := v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0)) \setminus U_0.$$ 

So

$$\int_{D_0} J(x) \, dH^1 x \leq \kappa^{-4} \frac{\int_{v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))} J(x) \, dH^1 x}{H^1(v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0)))} \int_{D_0} \kappa^{m_0 + 3} H^1(v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))) \geq H^1(U_0).$$

As by Lemma 1 $\int_{D_0} \kappa^{m_0 + 4} \sigma^{-4} \int_{U_0} J(x) \, dH^1 x \leq \sigma^{-2} \epsilon$. So

$$\int_{D_0} J(x) \, dH^1 x \leq \kappa^{-6} \frac{\int_{v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))} J(x) \, dH^1 x}{H^1(v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0)))} \int_{U_0} \kappa^{m_0 + 3} H^1(v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))) \geq H^1(U_0).$$

As by Lemma 1 $\int_{D_0} \kappa^{m_0 + 4} \sigma^{-4} \int_{U_0} J(x) \, dH^1 x \leq \sigma^{-2} \epsilon$. So

$$\int_{D_0} J(x) \, dH^1 x \leq \kappa^{-6} \frac{\int_{v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))} J(x) \, dH^1 x}{H^1(v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0)))} \int_{U_0} \kappa^{m_0 + 3} H^1(v(E_{k_j}^p \cap P_{\phi_0}^{-1}(z_0))) \geq H^1(U_0).$$
and so as \( \kappa \ll \sigma^8 \) we have
\[
\int_{U_0} J(x) \left| D\Theta^p_{k_j}(x) \right| dH^1 x \geq \frac{1}{2} \int_{y \in \left( E^{(p)}_{k_j} \cap P_{\partial \Phi}^{-1}(z_0) \right)} J(x) \left| D\Theta^p_{k_j}(x) \right| dH^1 x \geq \frac{\sigma^6 \theta_j}{2}
\]
and this establishes the claim. \( \diamond \)

Note in particular
\[
\int_{U_0} \left| D\Theta^p_{k_j}(x) \right| dH^1 x \geq \frac{\sigma^6 \theta_j}{2} \tag{224}
\]

Now for any point \( x \in v(l_t) \), let \( t(x) \) be the tangent to the curve \( v(l_t) \) at \( x \), as \( \Theta^p_{k_j} \) is increasing up the curve \( v(l_t) \), we have that
\[
t(x) \cdot D\Theta^p_{k_j}(x) > 0.
\]

On the other hand if we let \( v_x \in t(x)^\perp \) we claim
\[
v_x \cdot D\Theta^p_{k_j}(x) = 0 \tag{225}
\]
to prove (225) we argue as follows.

Take function \( X : [0, \infty) \to \mathbb{R}^n \) solving the ODE
\[
X(0) = x \quad \frac{dX}{dt}(t_0) = D\Psi_p(X(t_0))
\]
then by definition of we know \( \Theta^p_a \) is constant on \( \{ X(t) : t > 0 \} \). So
\[
D\Theta^p_{k_j}(x) \cdot \frac{dX}{dt}(0) = 0. \tag{226}
\]

From what we have previously calculated (see (9)), we know
\[
\frac{dX}{dt}(0) = Dv^{-T}(v^{-1}(x)) n_p.
\]
So
\[
\frac{dX}{dt}(0) \cdot t(x) = Dv^{-T}(v^{-1}(x)) n_p \cdot Dv(v^{-1}(x)) \phi_p
\]
\[
= n_p \cdot Dv^{-1}(v^{-1}(x)) Dv(v^{-1}(x)) \phi_p
\]
\[
= n_p \cdot \phi_p
\]
\[
= 0,
\]
so \( \frac{dX}{dt}(0) \in t(x)^\perp \). Now as we are in \( \mathbb{R}^2 \) so \( v_x \in t(x)^\perp \) will be of the form \( v_x = \lambda \frac{dX}{dt}(0) \) for some \( \lambda \in \mathbb{R} \) and so by (226) we have that for any \( v_x \in t(x)^\perp \), (225) is true.

So in fact \( v(l_{t_0}) \) is an integral curve for vector field \( D\Theta^p_{k_j} \). Formally; for any \( x \in v(l_t) \) we have
\[
t(x) \cdot D\Theta^p_{k_j}(x), \quad t(x) \cdot D\Theta^p_{k_j}(x) > 0. \tag{227}
\]

For convenience, at this point we fixed \( p = 1 \). Now \( U_0 \) is an open set in \( v \left( E^{(p)}_{k_j} \cap P_{\partial \Phi}^{-1}(z_0) \right) \) so \( v^{-1}(U_0) \) is an open set in \( l_t \cap S \). So \( v^{-1}(U_0) \) is a countable union of intervals in \( E^{(p)}_{k_j} \cap P_{\partial \Phi}^{-1}(z_0) \), i.e. \( v^{-1}(U_0) = \bigcup_n (a_n, b_n) \) where \( a_n, b_n \in E^{(p)}_{k_j} \cap P_{\partial \Phi}^{-1}(z_0) \). We have from (222)
\[
\sum_{n \in \mathbb{N}} |a_n - b_n| \leq H^1 \left( v^{-1}(U_0) \right) \leq \sigma^{-2} H^1(U_0) \leq \sigma^{-2} \kappa^{m_0 + \epsilon} \kappa.
\]
Take \( n \in \mathbb{N} \), firstly we solve the ODEs
\[
X^{(1)} (0) = v(a_n) \quad \frac{dX^{(1)}}{dt}(t_0) = D\Psi_1 \left( X^{(1)}(t_0) \right)
\]
\[
X^{(2)} (0) = v(b_n) \quad \frac{dX^{(2)}}{dt}(t_0) = D\Psi_1 \left( X^{(2)}(t_0) \right)
\]
By Lemma 1 there exists unique numbers \( t_1, t_2 \in \mathbb{R} \) such that \( X^{(1)} (t_1) \in \{ a^k_p + \langle \phi_1 \rangle \} \) and \( X^{(2)} (t_2) \in \{ a^k_p + \langle \phi_1 \rangle \} \) then by definition of \( \Theta^1_{k_j} \) we have that
\[
\Theta^1_{k_j} (v(a_n)) = X^{(1)} (t_1) \cdot \phi_1
\]
\[
\Theta^1_{k_j} (v(b_n)) = X^{(1)} (t_2) \cdot \phi_1.
\]
Now let \( M := \left\{ n \in \mathbb{N} : \left| \Theta^1_{k_j} (v(a_n)) - \Theta^1_{k_j} (v(b_n)) \right| > 2 |a_n - b_n| \right\} \). So by (227) letting \( t(x) \) denote the tangent to curve \( v(t_{n_0}) \) at point \( x \), we have
\[
\sum_{n \in \mathbb{N} \setminus M} \int_{v((a_n,b_n))} \left| D\Theta^1_{k_j} (x) \right| dH^1 x = \sum_{n \in \mathbb{N} \setminus M} \int_{v((a_n,b_n))} D\Theta^1_{k_j} (x) \cdot t(x) dH^1 x
\]
\[
= \sum_{n \in \mathbb{N} \setminus M} \Theta^1_{k_j} (v(b_n)) - \Theta^1_{k_j} (v(a_n))
\]
\[
\leq \sum_{n \in \mathbb{N} \setminus M} 2 |a_n - b_n|
\]
\[
\leq 2\sigma^{-2} \kappa^{m_0+3} \epsilon. \tag{228}
\]
So from (224), (228) the fact that \( U_0 = \bigcup_{n \in \mathbb{N} \setminus M} v ((a_n,b_n)) \) and the fact that by definition of \( G_0, \theta_j \geq \kappa^{m_0+2} \epsilon \) we have
\[
\sum_{n \in \mathbb{N} \setminus M} \int_{v((a_n,b_n))} \left| D\Theta^1_{k_j} (x) \right| dH^1 x \geq \frac{\sigma^6 \theta_j}{2} - 2\sigma^{-2} \kappa^{m_0+3} \epsilon
\]
\[
\geq \frac{\sigma^6 \theta_j}{4}. \tag{229}
\]
Recall we know from Lemma 1, \( Y^{(1)} (t) := v^{-1} \left( X^{(1)}(t) \right) \) and \( Y^{(2)} (t) := v^{-1} \left( X^{(2)}(t) \right) \) travel in cones. Let \( i \in M, k \in \{ 1, 2 \} \) and let \( X^{(k)}_i \) be the solution of
\[
X^{(1)}_i (0) = v(a_i) \quad \frac{dX^{(1)}_i}{dt}(t_0) = D\Psi_1 \left( X^{(1)}_i(t_0) \right)
\]
\[
X^{(2)}_i (0) = v(b_i) \quad \frac{dX^{(2)}_i}{dt}(t_0) = D\Psi_1 \left( X^{(2)}_i(t_0) \right)
\]
Let \( Y^{(k)}_i (t) = v^{-1} \left( X^{(k)}_i(t) \right) \) and let \( t^k_i \in \mathbb{R} \) be the unique number such that \( Y^{(k)}_i(t^k_i) \in \{ a + \langle \phi_1 \rangle \} \).

Denoted by \( Q^{(k)}_i \) := \{ \langle y^{(k)}_j(t) : t \in [0,t^k_i] \rangle \} \) and define function \( \vartheta^k_i : P_{\langle \phi^k_1 \rangle} \left( Q^{(k)}_i \right) \to \mathbb{R} \) by
\[
\vartheta^k_i (x) := \left( P_{\langle \phi^k_1 \rangle}^{-1}(x) \cap Q^{(k)}_i \right) \cdot \phi_1.
\]
So by Lemma 1, \( \vartheta^1_i \) and \( \vartheta^2_i \) are well defined Lipschitz functions. See figure 40.

At this point the indices have been changed and fixed so often we chose to take a moment to recall where we are. We are in column \( E^1_{k_j} \), \( U_0 \) is a subset of a line running parallel to \( \phi_1 \) up through \( E^1_{k_j} \). \( U_0 \) is the countable union of intervals \( \{ (a_n,b_n) : n \in \mathbb{N} \} \), \( \vartheta^1_i \) is the function from \( \phi_i^+ \) to \( \mathbb{R}^2 \) whose graph is the pullback of part of an integral curve that runs from \( v(a_i) \) up to \( v(a + \langle \phi_1 \rangle) \) and \( \vartheta^2_i \) is the function from \( \phi_i^+ \) to \( \mathbb{R}^2 \) whose graph is the pullback of part of an integral curve that runs from \( v(b_i) \) up to \( v(a + \langle \phi_1 \rangle) \).
From this point on to simplify notation we will take $i$ to be fixed. So let $p_k := \vartheta_i^k$. Now let functions $q_1 : \mathcal{P}_i \left( Q_i^{(1)} \right) \to \mathbb{R}$ and $q_2 : \mathcal{P}_i \left( Q_i^{(2)} \right) \to \mathbb{R}$ be defined as follows. Let $c_0, d_0$ be the end points of interval $\mathcal{P}_i \left( Q_i^{(1)} \right)$ (which also, as can be seen from fig 40, are the endpoints of $\mathcal{P}_i \left( Q_i^{(2)} \right)$). For $x \in [c_0, d_0]$ let

$$q_k (x) := \int_{c_0}^{x} p_k' (z) \, dL^1 z \quad \text{for} \quad k = 1, 2.$$  \hspace{1cm} (230)

So

$$|q_1 (d_0) - q_2 (d_0)| = \left| \int_{c_0}^{d_0} p_1' (z) - p_2' (z) \, dL^1 z \right| \leq \int_{c_0}^{d_0} |p_1' (z) - p_2' (z)| \, dL^1 z. \quad \text{(231)}$$

So from (230) and since by definition of $\Theta_{k_1}^i, \Theta_{k_2}^i \left( v (a_i) \right) = \vartheta_i^1 (d_0) = p_1 (d_0)$ and $\Theta_{k_2}^i \left( v (b_i) \right) = \vartheta_i^2 (d_0) = p_2 (d_0)$ and as $p_1 (c_0) = a_i, p_2 (c_0) = b_i$ we have

$$|q_1 (d_0) - q_2 (d_0)| = \left| (p_1 (d_0) - p_2 (d_0)) - (p_1 (c_0) - p_2 (c_0)) \right| \geq \left| \Theta_{k_1}^i \left( v (a_i) \right) - \Theta_{k_2}^i \left( v (b_i) \right) \right| - |a_i - b_i| \geq \frac{\Theta_{k_1}^i \left( v (a_i) \right) - \Theta_{k_2}^i \left( v (b_i) \right)}{2}. \quad \text{(232)}$$

So by (231)

$$\frac{\Theta_{k_1}^i \left( v (a_i) \right) - \Theta_{k_2}^i \left( v (b_i) \right)}{2} \leq \int_{c_0}^{d_0} |p_1' (z) - p_2' (z)| \, dL^1 z. \quad \text{(232)}$$

Let $t_1 \in (0, t_0)$. Now if we let $v_{t_1}^{(k)}$ denote the tangent to the path $\left\{ Y_i^{(k)} (t) : t \in [c_0, d_0] \right\}$ at point $Y_i^{(k)} (t_1)$ then as we have already calculated

$$v_{t_1}^{(k)} := \left[ S^{-1} \left( Y_i^{(k)} (t_1) \right) \right] n_1. \quad \text{(233)}$$
As vector \( p_k' (t_1) \phi_1 + n_1 \) is parallel to and pointing in the same direction as \( v_t^{(k)} \), we have
\[
\frac{p_k' (t_1) \phi_1 + n_1}{(p_k' (t_1)^2 + 1)^{\frac{1}{2}}} = v_t^{(k)} \quad \text{for} \quad k = 1, 2.
\]

**Claim 4.** We will show
\[
|v_t^{(1)} - v_t^{(2)}| \geq \frac{2c_15 \left| p_2' (t_1) - p_2' (t_2) \right|}{\sqrt{\sigma - 2} + 1}
\]
for some small constant \( c_1 > 0 \).

Unfortunately we will have to consider three cases.

**Case 0.** If \( p_1' (t_1) \) and \( p_2' (t_1) \) has the opposite sign, then
\[
\frac{p_1' (t_1)}{\sqrt{(p_1' (t_1))^2 + 1}} - \frac{p_2' (t_1)}{\sqrt{(p_2' (t_1))^2 + 1}} = \frac{|p_1' (t_1)|}{\sqrt{(p_1' (t_1))^2 + 1}} + \frac{|p_2' (t_1)|}{\sqrt{(p_2' (t_1))^2 + 1}}
\]
\[
\geq \frac{|p_1' (t_1) - p_2' (t_1)|}{2\sqrt{(\sigma - 2) + 1}}
\]
and we are done.

**Case 1** If \( \max \left\{ |p_1 (t_1)|, |p_2 (t_1)| \right\} \leq c_1 \) where \( c_1 > 0 \) is a small constant we will decide on later.

Now
\[
|v_t^{(1)} - v_t^{(2)}| \geq \left| (v_t^{(1)} - v_t^{(2)}) \cdot \phi_1 \right|
\]
\[
= \frac{p_1' (t_1)}{\sqrt{(p_1' (t_1))^2 + 1}} - \frac{p_2' (t_1)}{\sqrt{(p_2' (t_1))^2 + 1}}
\]
\[
\geq \frac{p_1' (t_1) - p_2' (t_1)}{\sqrt{(p_1' (t_1))^2 + 1}} \cdot \frac{1}{\sqrt{(p_1' (t_1))^2 + 1}} - \frac{1}{\sqrt{(p_2' (t_1))^2 + 1}}
\]
\[
|v_t^{(1)} - v_t^{(2)}| \geq \frac{1}{\sqrt{(p_1' (t_1))^2 + 1}} - \frac{1}{\sqrt{(p_2' (t_1))^2 + 1}}
\]
So as
\[
\frac{1}{\sqrt{(p_1' (t_1))^2 + 1}} - \frac{1}{\sqrt{(p_2' (t_2))^2 + 1}} = \frac{\sqrt{(p_1' (t_2))^2 + 1} - \sqrt{(p_1' (t_1))^2 + 1}}{\sqrt{(p_1' (t_1))^2 + 1}\sqrt{(p_2' (t_2))^2 + 1}}
\]
\[
\leq 2(\sigma - 4 + 1)^{-1}\left| \sqrt{(p_1' (t_2))^2 + 1} - \sqrt{(p_1' (t_1))^2 + 1} \right|
\]
Now observe fig 41.
Now as can be seen from fig 41, assuming constant \( c_1 \) has been chosen small enough we have that
\[
\left| \sqrt{1 + (p_1'(t_1))^2} - \sqrt{1 + (p_1'(t_2))^2} \right| \leq 2 \| p_1'(t_1) \| - \| p_1'(t_2) \| \sin \theta_1.
\]
And for some enough \( c_1 \) we also know \( \theta_1 \leq 2 \| p_1'(t_1) \|. \) This gives
\[
\left| \sqrt{1 + (p_1'(t_1))^2} - \sqrt{1 + (p_1'(t_2))^2} \right| \leq 4 \| p_1'(t_1) \| - \| p_1'(t_2) \| \| p_1'(t_2) \|.
\]
Putting this together with (237) and recalling the assumption the assumption that \( \max \{ \| p_1(t_1) \|, \| p_2(t_1) \| \} \leq c_1 \) for some small constant \( c_1 \) we have
\[
\left| \left( 1 + (p_1'(t_1))^2 \right)^{-\frac{1}{2}} - \left( 1 + (p_1'(t_2))^2 \right)^{-\frac{1}{2}} \right| \leq 8c_1 \left( \sigma^{-4} + 1 \right) \| p_1'(t_1) \| - \| p_1'(t_2) \|,
\]
Applying this to (236) gives
\[
\left| \nu_{t_1}^{(1)} - \nu_{t_1}^{(2)} \right| \geq \frac{|p_1'(t_1) - p_2'(t_1)|}{(\sigma^2 + 1)^2} - 8c_1^2 \left( \sigma^{-4} + 1 \right)^{-1} \| p_1'(t_1) \| - \| p_1'(t_2) \| \geq \frac{|p_1'(t_1) - p_2'(t_1)|}{2(\sigma^2 + 1)^2}.
\]
which is what we want.

Case 2 \( \max \{ \| p_1'(t_1) \|, \| p_2'(t_1) \| \} \geq c_1. \)
\[
\left| \nu_{t_1}^{(1)} - \nu_{t_1}^{(2)} \right| \geq \left| \left( p_2'(t_1)^2 + 1 \right)^{\frac{1}{2}} - \left( (p_1'(t_1)^2 + 1 \right)^{\frac{1}{2}} \right| \geq \left| \left( p_2'(t_1)^2 + 1 \right)^{\frac{1}{2}} - \left( (p_1'(t_1)^2 + 1 \right)^{\frac{1}{2}} \right| \geq \left( (\sigma^2 + 1) \right).\]

Now we need to use the following identity
\[
\sqrt{a^2 + 1} - \sqrt{b^2 + 1} = \frac{(a - b)(a + b)}{\sqrt{a^2 + 1} + \sqrt{b^2 + 1}}
\]
So we have
\[
\left| \sqrt{p_2'(t_1)^2 + 1} - \sqrt{p_1'(t_1)^2 + 1} \right| \geq \left| p_2'(t_1) - p_1'(t_1) \right| \left| p_2'(t_1)^2 + p_1'(t_1)^2 \right| \geq \frac{2c_1 |p_1'(t_1) - p_2'(t_1)|}{2\sqrt{(\sigma^2 + 1)}}.
\]
Thus we have established the claim. \( \Diamond \)

More notation, for a point \( z \in Q_i^{(k)} \) let \( t_k(z) \in S^1 \) denote the tangent to graph \( Q_i^{(k)} \) for \( k \in \{1, 2\} \), then inequality (234) in our notation becomes; for any \( z_0 \in P(\phi^+_z) \left( Q_i^{(k)} \right) \)
\[
|t_1(p_1(z_0)) - t_2(p_2(z_0)) | \geq \frac{2c_1}{(\sigma^2 + 1)^{\frac{1}{2}}} |p_2'(z_0) - p_1'(z_0)|.
\]
So inequality (232) becomes
\[
\left| \frac{\Theta_{k_1}^i (v (a_i)) - \Theta_{k_1}^j (v (b_i))}{2} \right| \leq \frac{(\sigma^{-2} + 1)^{\frac{1}{2}}}{2c_1} \int_{c_0}^{d_0} |t_1 (p_1 (z)) - t_2 (p_2 (z))| dL^1 z. \tag{238}
\]

Now as we have already calculated \( t_i (p_1 (z)) = [S^{-1} (p_1 (z)) S^{-1} (p_1 (z))] a_i \), (recall the notation, \( Dv (\cdot) =: R (\cdot) S (\cdot) \) where \( R (\cdot) \in SO (2) \) and \( S (\cdot) \) is a positive symmetric matrix). Since the map \( Dv (\cdot) \to S (\cdot) \) is a projection and \( |S (\cdot)| > \sigma \) we have
\[
|Dv (p_1 (z)) - Dv (p_2 (z))| > |S (p_1 (z)) - S (p_2 (z))|
\geq \frac{1}{2} || S (p_1 (z)) - S (p_2 (z)) ||
\geq \frac{\sigma^2}{2} || (S (p_1 (z)) - S (p_2 (z))) (S (p_1 (z)) S (p_2 (z)))^{-1} ||
= \frac{\sigma^2}{2} || S (p_1 (z))^{-1} - S (p_2 (z))^{-1} ||
\]

Now
\[
\frac{|Dv (p_1 (z)) - Dv (p_2 (z))|}{\sigma} \geq \frac{\sigma^2}{2} || S (p_2 (z))^{-1} || || S (p_1 (z))^{-1} - S (p_2 (z))^{-1} ||
\geq \frac{\sigma^2}{2} || (S (p_2 (z))^{-2} - S (p_1 (z))^{-1} S (p_2 (z))^{-1} ||
\]
and similarly
\[
\frac{|Dv (p_1 (z)) - Dv (p_2 (z))|}{\sigma} \geq \frac{\sigma^2}{2} || S (p_1 (z))^{-2} - S (p_1 (z))^{-1} S (p_2 (z))^{-1} ||.
\]

Putting these things together we have
\[
\frac{|Dv (p_2 (z)) - Dv (p_1 (z))|}{\sigma} \geq \frac{\sigma^2}{2} || S (p_2 (z))^{-2} - S (p_1 (z))^{-2} ||
\geq \frac{\sigma^2}{2} \left( || S (p_2 (z))^{-2} - S (p_1 (z))^{-2} || n_1 \right)
\geq \frac{\sigma^2}{2} |t_2 (p_2 (z)) - t_1 (p_1 (z))|.
\]

Inserting this into equation (238) gives us
\[
\left| \frac{\Theta_{k_1}^i (v (a_i)) - \Theta_{k_1}^j (v (b_i))}{2} \right| \leq 4 \frac{(\sigma^{-2} + 1)^{\frac{1}{2}}}{c_1 \sigma^3} \int_{c_0}^{d_0} |Dv (p_1 (z)) - Dv (p_2 (z))| dL^1 z
\leq 4 \frac{(\sigma^{-2} + 1)^{\frac{1}{2}}}{c_1 \sigma^3} \int_{c_0}^{d_0} \left| \int_{p_2 (z)}^{p_1 (z)} \frac{1}{\partial \phi_1} Dv (x) dL^1 x \right| dL^1 z
\leq 4 \frac{(\sigma^{-2} + 1)^{\frac{1}{2}}}{c_1 \sigma^3} \int_{c_0}^{d_0} \left| \int_{p_2 (z)}^{p_1 (z)} |D^2 v (x)| dL^1 x dL^1 z. \tag{239}
\]

Now let \( V_i \) denote the region enclosed by the two graphs \( Q_i^{(1)} \), \( Q_i^{(2)} \) and the lines \( l_i \), \( l_{P (\cdot)} (a) \). Formally \( V_i := \bigcup_{z \in [c_0, d_0]} [p_1 (z), p_2 (z)] \). The set \( \{ E_i : i \in M \} \) is pairwise disjoint and the equation (239) in this notation is by Fubini
\[
\left| \frac{\Theta_{k_1}^i (v (a_i)) - \Theta_{k_1}^j (v (b_i))}{2} \right| \leq 4 \frac{(\sigma^{-2} + 1)^{\frac{1}{2}}}{c_1 \sigma^3} \int_{V_i} |D^2 v (x)| dL^2 x.
\]
So from (229) and from the fact that \( v(l_t) \) is an integral curve for \( \Theta^{1}_{l_j} \) we have by summing over \( M \)

\[
\frac{\sigma^6\epsilon}{4} \leq \sum_{i \in M} \int_{v((a_i, b_i))} D\Theta^{1}_{l_j}(x) t_x dH^1 x
\]

\[
= \sum_{i \in M} \left| \Theta^{1}_{l_j}(v(a_i)) - \Theta^{1}_{l_j}(v(b_i)) \right|
\]

\[
\leq \frac{4 (\sigma^{-2} + 1)^2}{c_1 \sigma^3} \left( \sum_{i \in M} \int_{V_i} |D^2 v(x)| dL^2 x \right).
\]

Now \( \bigcup_{i \in M} V_i \subset E^{(p)}_{k_j} \) so finally we have

\[
\int_{E^{(p)}_{k_j}} |D^2 v(x)| dL^2 x > c_1 \sigma^9 \theta_j.
\]

So for each \( j \in G_0 \) we have that

\[
\int_{E^{(p)}_{k_j}} |D^2 v(x)| dL^2 x \geq \frac{c_1 \sigma^9}{16} \theta_j.
\]

Thus recall (217)

\[
\sum_{j \in G_0} \int_{E^{(p)}_{k_j}} |D^2 v(x)| dL^2 x \geq \frac{c_1 \sigma^9}{16} \left( \sum_{j \in G_0} \theta_j \right) \geq \frac{c_1 \sigma^9}{16} (1 - \kappa) \nu C.
\]

However \( \{ E^{(p)}_{k_j} : j \in G_0 \} \) are overlapping, recall \( E^{(p)}_{k_j} := N_{\epsilon \kappa^{\alpha \nu} \epsilon} \left( C^{(p)}_{k_j} \right) \cap S \), where \( \{ C^{(p)}_{k_j} : j \in G_0 \} \) are disjoint columns of width \( \kappa^{\alpha \nu} \epsilon \) going through \( S \). So \( \{ E^{(p)}_{k_j} : j \in G_0 \} \) can not overlap by more than \( 2 [c_5] \) times.

Thus must be able to find a subset \( G_1 \subset G_0 \) such that

- \( \sum_{j \in G_1} \int_{E^{(p)}_{k_j}} |D^2 v(x)| dL^2 x \geq \frac{c_2 \sigma^{9} \kappa \epsilon}{64} \).

\[
\int_{S} |D^2 v(x)| dL^2 x \geq \frac{c_2 \sigma^{9} \kappa \epsilon}{64}.
\]

\[\Box\]
10. Proof of Theorem 2

The proof of Theorem 2 is just a matter of collecting everything together.

Proof. Recall, we have triangulation $\triangle_x$ of $\Omega$, with triangulation size $\epsilon$. Let $v \in A_F(\Omega)$ and we have skewcube $S := P(a, \phi_1, \phi_2, \epsilon \sigma)$ such that $N_{\phi_1}(S) \subset \Omega$. In addition we have following inequalities

$$\int_S d(Dv(x), K) dL^2 x \leq \kappa \frac{10 m_0 + 8 \epsilon^2}{2}$$

(240) and

$$\int_S |D^2 v(x)| dL^2 x \leq \epsilon_0 \kappa \epsilon.$$  

(241)

Let $\{ C_k^{(p)} : k \in \{1, \ldots, [\kappa^{-m_0} + 1]\} \}$ denote the set of columns width $\kappa^{m_0} \epsilon$ going through $S$, parallel to $\phi_p$ for $p = 1, 2$. Let $E_k^{(p)} := N_{\epsilon \kappa^{m_0} \epsilon}(C_k^{(p)}) \cap S$ for $k = 1, 2, \ldots, [\kappa^{-m_0} + 1]$. Let

$$L_p := \left\{ k \in \{1, \ldots, [\kappa^{-m_0} + 1]\} : \int_{v(E_k^{(p)})} J(x) dL^2 x \geq \kappa^{3m_0 + 7} \epsilon^2 \right\}.$$

So as the set $\{ E_k^{(p)} : k \in \{1, \ldots, [\kappa^{-m_0} + 1]\} \}$ does not overlap more than $2\epsilon_5 \kappa^{-m_0}$ times

$$\frac{1}{2\epsilon_5} \kappa^{m_0} \kappa^{3m_0 + 7} \epsilon^2 \text{Card}(L_p) \leq \left(2\epsilon_5 \kappa^{-m_0}\right)^{-1} \left( \sum_{k \in L_p} \int_{v(E_k^{(p)})} J(x) dL^2 x \right) \leq \int_{v(S)} J(x) dL^2 x \geq \sigma^{-2} \kappa^{-m_0 + 8} \epsilon^2$$

Which implies

$$\text{Card}(L_p) \leq 2\epsilon_5 \kappa^{-m_0} \kappa^{\frac{m_0}{2} + 1}.$$

So we must be able to find distinct numbers $\{k_1, k_2, \ldots, k_{Q_0^p}\} \subset \{1, 2, \ldots, [\kappa^{-m_0} + 1]\}$ such that $Q_0^p \geq \left(1 - \kappa^{\frac{m_0}{2}}\right) \kappa^{-m_0}$ and

$$\int_{v(E_k^{(p)})} J(x) dL^2 x \leq \kappa^{3m_0 + 7} \epsilon^2$$

for $j \in \{1, 2, \ldots, Q_0^p\}$. Now if we have that for $p \in \{1, 2\}$

$$\sum_{j=1}^{Q_0^p} \int_{v(E_k^{(p)})} J(x)\left|D\Theta_k^{(p)}(x)\right| dL^2 x \geq \kappa^{m_0 + 1} \epsilon^2$$

we can apply Lemma 10 to conclude

$$\int_S |D^2 v(x)| dL^2 x \geq \epsilon_0 \kappa \epsilon$$

and this contradicts (241).

So we must have

$$\sum_{j=1}^{Q_0^p} \int_{v(E_k^{(p)})} J(x)\left|D\Theta_k^{(p)}(x)\right| dL^2 x \leq \kappa^{m_0 + 1} \epsilon^2.$$  

(242)

So now, by (240), (241) and (242) can invoke Proposition 1 which gives the following conclusion;

Let

$$\{ \mathcal{E}_{i,j} := P(a_{i,j}, \phi_1, \phi_2, \kappa^{m_0} \epsilon) : i, j \in \{1, 2, \ldots, [\kappa^{-m_0} + 1]\} \}$$
be a set of pairwise disjoint skewcubes such that $S \subset \cup_{i,j \in \{1, \ldots, [\kappa^{-m_0}] + 1\}} S_{i,j}$. Let

$$S_{i,j} := P(a_{i,j}, \phi_1, \phi_2, c_2 \kappa^{m_0} \epsilon)$$

for some constant $c_2 > 1$ we will decide on later.

There exists a set $G_0 \subset \{S_{i,j} : i,j \in \{1, \ldots, [\kappa^{-m_0}] + 1\}\}$ such that

- $$L^2 \left( \left\{ x \in S_{i,j} : d(Dv(x), R_{i,j}T_{i,j}) > \kappa^\frac{m_0}{2} \right\} \right) < 20c^2_2 \xi_3 \sigma^{-8} \kappa^\frac{m_0}{2} (c_2 \kappa^{m_0})^2$$

for some $R_{i,j} \in SO(2)$, $T_{i,j} \in \{Id, H\}$

- $$\text{Card}(G_0) \geq 1 - 16\sigma^{-2}\kappa^\frac{m_0}{2} \kappa^{2m_0}$$

Now this, together with (240) and (241) gives us all we need to invoke Lemma 9. So if $\tau_i$ is a triangle in $\Delta_\epsilon$ that contains $a$ and $L$ is the linear part of the affine map we get from interpolating $v$ on the corners of $\tau_i$, we have the following inequality

$$d(L, SO(2) \cup SO(2) H) < \kappa^\frac{m_0}{2}$$

and this complete the proof of Theorem 2. $\square$
11. The Proof of Theorem 1

First note that we have the following trivial lower bound for for the finite element approximation of \( I \). Now consider a triangulation of \( \Omega \) with triangles size of \( \alpha \). Let

\[
A_\alpha := \left\{ v : \Omega \to \mathbb{R}^2 : v \text{ satisfies the affine boundary condition and piecewise affine on } \{ \tau_i : i = 1, \ldots, M_1 \} \right\}
\]

Note that its trivial that for any \( u \in A_\alpha \) we must have as least \( \frac{\alpha}{100} \) triangles \( \tau_{i,j} \) with

\[
d(D \tau_{i,j}, SO(2) \cup SO(2) H) > \sigma^4.
\]

So by Theorem 1 we have

\[
\inf_{u \in A_\alpha} I(u) \geq \frac{\sigma^4}{100} \alpha.
\]

We can use Theorem 2 in the following way:

Suppose

\[
\int_{\Omega} d(Dv(x), SO(2) \cup SO(2) H) dL^2 x \leq \epsilon^5
\]

and

\[
\int_{\Omega} |D^2v(x)| dL^2 x \leq \epsilon^{-\beta}.
\]

Let \( \{ \tau_i : 1 = 1, \ldots, [\epsilon^{-2}] + 2 \} \) be a triangulation of with triangle size \( \epsilon \). Let \( \kappa := \epsilon^{1-\beta} \). Let \( \tilde{\kappa} := \frac{\kappa}{1024} \).

Let \( B_1 := \{ \tau_i : \int_{\tau_i} T(x) dL^2 x \geq \epsilon^{2+\gamma} \} \). So Card(\( B_1 \)) \( \epsilon^{2+\gamma} \leq \epsilon^\kappa \) which implies Card(\( B_1 \)) \( \leq \epsilon^{\kappa-\gamma-2} \).

Let \( B_2 := \{ \tau_i : \text{The linear part of the affine interpolation of } S \text{ on } \tau_i \text{ is distance } > \kappa \text{ from } \} \)

So by Theorem 1 we have

\[
\text{Card}(B_2) \tilde{\kappa} \epsilon = \text{Card}(B_2) \epsilon^{1 + \frac{1024(1-\beta)}{m_0}} \leq \epsilon^{-\beta}
\]

which implies

\[
\text{Card}(B_2) \leq \epsilon^{-1 - \frac{1024}{m_0}} \beta.
\]

Now let \( \tilde{v}_\epsilon \) be the triangulation of \( v \) on \( \{ \tau_i : i = 1, \ldots, \epsilon^{-2} \} \). We have the following estimate

\[
I(\tilde{v}_\epsilon) = \int_{\Omega} d(D\tilde{v}_\epsilon(x), K) dL^2 x
\]

\[
= \sum_{\tau_i \in B_1} \int_{\tau_i} d(D\tilde{v}_\epsilon(x), K) dL^2 x + \sum_{\tau_i \in B_2} \int_{\tau_i} d(D\tilde{v}_\epsilon(x), K) dL^2 x + \sum_{\tau_i \notin (B_1 \cup B_2)} \int_{\tau_i} d(D\tilde{v}_\epsilon(x), K) dL^2 x
\]

\[
\leq \sigma^{-2} \epsilon^2 (\text{Card}(B_1) + \text{Card}(B_2)) + \sum_{\tau_i \notin (B_1 \cup B_2)} \int_{\tau_i} d(D\tilde{v}_\epsilon(x), K) dL^2 x
\]

\[
\leq \sigma^{-2} \epsilon^2 \left( \epsilon^{\kappa-\gamma-2} + \epsilon^{-1 - \frac{1024}{m_0}} \beta \right) + \epsilon^{1-\beta} L^2(\Omega)
\]

So by letting \( \zeta := \frac{7m_0}{2} + 8, \gamma := \frac{m_0}{2}, \beta := \frac{1024}{m_0} \) we have

\[
I(\tilde{v}_\epsilon) \leq c \epsilon^{1 - \frac{7m_0}{2m_0}}.
\]

Now letting \( m_1 = 4m_0 \) completes the proof of Theorem 1.
12. Proof of Corollary 1

So if we have a function $v$ such that $\frac{I_v}{\epsilon} \leq \epsilon^{\frac{m_1^2 - 2048}{m_1}}$. Recall $h := \epsilon^{\frac{m_1^2 - 2048}{m_1}}$

$$\int_{\Omega} d(Dv(x), SO(2) \cup SO(2) H) dL^2 x \leq \epsilon^{\frac{m_1^2 - 2048}{m_1}}$$

$$= h^{m_1}.$$ 

And

$$\int_{\Omega} |D^2v(x)| dL^2 x \leq \frac{I_v}{\epsilon}$$

$$\leq h \left( \frac{m_1^2}{m_1^2 - 2048} \right)^{\frac{2048}{m_1}}$$

$$= h \frac{m_1^2}{m_1^2 - 2048}.$$ 

As we know $m_1 \geq 2048$ so we have $m_1^2 - 2048 = m_1 \left( m_1 - \frac{2048}{m_1} \right) \geq \frac{m_1^2}{2}$ so $\frac{2048m_1}{m_1^2 - 2048} \leq \frac{4096}{m_1}$ and so

$$\int_{\Omega} |D^2v(x)| dL^2 x \leq h \frac{\frac{4096}{m_1}}{m_1^2 - 2048}$$

$$\leq h \frac{4096}{m_1^{m_1}}.$$ 

(243)

So by Theorem 1 if $\tilde{v}_h$ denotes the F.E. approximation on the triangulation $\Delta_h$ we have

$$I(\tilde{v}_h) \leq ch^{1 - \frac{2048}{m_1}}.$$
13. Appendix

13.1. $H^{-1}n_i = \diamond_i$ for $i = 1, 2$. We begin by calculating $\diamond_1$ and $\diamond_2$. Firstly we know $\diamond_i \in \Xi_i$ for $i = 1, 2$. Recall from section 4.1 in the introduction (in particular see fig 2), that $\diamond_1$ is the optimal direction for the path $W$ that joins two lines $l_1, l_2$ (that are parallel to $\phi_1$), but that minimizes the integral $\int_W |Ht(x)| dH^1x$ (where $t(x)$ is the tangent to the path $W$ at point $x$). Now let $\psi_0 \in S^1$ be the vector “in between” $-\phi_1$ and $-\phi_2$ (formally $\psi_0 := \frac{\phi_1 - \phi_2}{|\phi_1 + \phi_2|}$), $\psi_0$ is the vector that is most shrunk under the action of $H$ (see for example fig 14). However as we will see, $\psi_0$ is not the optimal angle for $W$ because it is at too flat an angle to $-\phi_1$ (see fig 2) so any path joining $l_1$ and $l_2$ that is parallel to $\psi_0$ will have to be so long it cancels the shrinking effects of $\psi_0$. For the same reason it is clear that the optimal vector $\diamond_1$ must be in the “half” of the shrink directions that lie between $-\phi_2$ and $\psi_0$, i.e. paths that are parallel to vectors in the other “half” will be too long.

Hence $\diamond_1$ (as is shown on fig 42) points above the $x$-axis. By absolutely identical considerations we see that $\diamond_2$ also points above the $x$-axis.

Using this initial (crude) information about $\diamond_1, \diamond_2$ we will now calculate the coordinate of $\diamond_2$.

Firstly recall from (54) that for the unique $\tilde{\alpha} \in [0, \pi)$ such that $\tan 2\tilde{\alpha} = \frac{2\sigma^3}{(1 - \sigma^6)}$ we have $\diamond_2 := \left( \frac{\cos \tilde{\alpha}}{\sin \tilde{\alpha}} \right)$. Note that

\[
\sqrt{\left(\left(2\tilde{\sigma}^3\right)^2 + (1 - \tilde{\sigma}^6)^2\right)} = \sqrt{\left(4\tilde{\sigma}^6 + 1 - 2\tilde{\sigma}^6 + \tilde{\sigma}^{12}\right)} = \sqrt{(1 + 2\tilde{\sigma}^6 + \tilde{\sigma}^{12})} = \left(1 + \tilde{\sigma}^6\right) \]

So

\[
\sin 2\tilde{\alpha} = \frac{2\tilde{\sigma}^3}{1 + \tilde{\sigma}^6} \quad \text{and} \quad \cos 2\tilde{\alpha} = \frac{(1 - \tilde{\sigma}^6)}{(1 + \tilde{\sigma}^6)}
\]
Hence

\[
\begin{align*}
(sin \tilde{a})^2 &= \frac{1}{2} - \frac{(1 - \tilde{\sigma}^6)}{2(1 + \tilde{\sigma}^6)} \\
&= \frac{1}{2} \left( \frac{1 + \tilde{\sigma}^6}{1 + \tilde{\sigma}^6} - \frac{(1 - \tilde{\sigma}^6)}{1 + \tilde{\sigma}^6} \right) \\
&= \frac{1}{2} \left( \frac{2\tilde{\sigma}^6}{1 + \tilde{\sigma}^6} \right) \\
&= \frac{\tilde{\sigma}^6}{(1 + \tilde{\sigma}^6)}
\end{align*}
\]

And thus

\[
\begin{align*}
\sin \tilde{a} &= \pm \frac{\tilde{\sigma}^3}{\sqrt{(1 + \tilde{\sigma}^6)}} \quad (244) \\
(cos \tilde{a})^2 &= \frac{1}{2} + \frac{(1 - \tilde{\sigma}^6)}{2(1 + \tilde{\sigma}^6)} \\
&= \frac{1}{(1 + \tilde{\sigma}^6)}
\end{align*}
\]

Hence

\[
\cos \tilde{a} = \pm \frac{1}{\sqrt{(1 + \tilde{\sigma}^6)}} \quad (245)
\]

Now from (244) and (245) and what we have established about \( \tilde{\sigma}_2 \) pointing above the x-axis and the fact that it belongs to \( \Xi_2 \), we must have that

\[
\sin \tilde{a} = \tilde{\sigma}^3 \sqrt{(1 + \tilde{\sigma}^6)}, \quad \cos \tilde{a} = \frac{1}{\sqrt{(1 + \tilde{\sigma}^6)}}.
\]

Now we need to calculate \( \tilde{\sigma}_1 \). We have to start from scratch. So for \( \psi := \left( \frac{\cos \tilde{a}}{\sin \tilde{a}} \right) \), let

\[
g(A) := |H\psi|^2 - (\psi \cdot n_1)^2
\]

\[
= \tilde{\sigma}^2 \cos^2 a + \frac{\sin^2 \tilde{a}}{\tilde{\sigma}^2} - \left( -\frac{\tilde{\sigma} \cos a}{\sqrt{(1 + \tilde{\sigma}^4)}} + \frac{\sin a}{\sqrt{(1 + \tilde{\sigma}^4)}} \right)^2
\]

\[
= \tilde{\sigma}^2 \cos^2 a + \frac{\sin^2 \tilde{a}}{\tilde{\sigma}^2} - \frac{\tilde{\sigma}^2 \cos^2 a}{(1 + \tilde{\sigma}^2)} - \frac{\sin^2 a}{(1 + \tilde{\sigma}^2)} + \frac{2\tilde{\sigma} \sin \tilde{a} \cos \tilde{a}}{(1 + \tilde{\sigma}^2)}
\]

So

\[
\tilde{\sigma}^2 (\tilde{\sigma}^2 + 1) g(a) = \tilde{\sigma}^6 \cos^2 a + \sin^2 a + 2\tilde{\sigma} \cos a \sin a.
\]

And as in the calculation of \( \tilde{\sigma}_1 \), by standard trigonometric identities this reduces to

\[
\tilde{\sigma}^2 (\tilde{\sigma}^2 + 1) g(a) = \tilde{\sigma}^6 \left( \frac{1 + \cos 2a}{2} \right) + \frac{1 - \cos 2a}{2} + \tilde{\sigma}^2 \sin 2a.
\]

So

\[
2\tilde{\sigma}^2 (\tilde{\sigma}^2 + 1) g(a) = (\tilde{\sigma}^6 - 1) \cos 2a + 2\tilde{\sigma}^3 \sin 2a + \tilde{\sigma}^6 + 1.
\]

Thus

\[
2\tilde{\sigma}^2 (\tilde{\sigma}^2 + 1) g'(a) = -2 (\tilde{\sigma}^6 - 1) \sin 2a + 4\tilde{\sigma}^3 \cos 2a.
\]

So

\[
g'(\tilde{b}) = 0 \iff 2 (\tilde{\sigma}^6 - 1) \sin 2\tilde{b} = 4\tilde{\sigma}^3 \cos 2\tilde{b}
\]

\[
\iff \tan 2\tilde{b} = \frac{-2\tilde{\sigma}^3}{(1 - \tilde{\sigma}^6)}
\]
Hence
\[ \tan 2\tilde{b} = -\tan 2\tilde{a}. \] (246)

Now as we know \( \tilde{b} = (\cos \tilde{a}) \) points upwards and to the right (as shown in fig 42) so \( \tilde{a} \in \left(0, \frac{\pi}{2}\right) \).
So (246) implies either \( \tilde{b} = -\tilde{a} \) or \( \tilde{b} = \pi - \tilde{a} \). Now as the former possibility implies that \( \tilde{\phi}_1 = (\cos \tilde{b}) \) is not in \( \Xi_1 \) so we must have that \( \tilde{b} = \pi - \tilde{a} \).

Thus
\[ \tilde{\phi}_1 = (\cos \pi - \tilde{a}) = (\cos \tilde{a} - \tilde{a}) = \sqrt{2}. \] (247)

We claim
\[ H^{-1}H^{-1}_{n_2} = \tilde{\phi}_2. \] (248)

From fig 42 it should seem reasonable that \( H^{-1}H^{-1}_{n_2} \) is sent into the shrink directions, specifically into \( \Xi_1 \). And from what we have calculated \( \tilde{\phi}_2 := \sqrt{\frac{1 - \tilde{\sigma}^2}{\lambda^2 - \tilde{\sigma}^2}}. \) Now from (35) we have \( n_2 := \sqrt{\frac{1 - \tilde{\sigma}^2}{\lambda^2 - \tilde{\sigma}^2}} \) for \( \lambda = \tilde{\sigma}^{-1} \). So by writing this out more carefully we have \( n_2 := \sqrt{\frac{1 - \tilde{\sigma}^2}{\lambda^2 - \tilde{\sigma}^2}} \). Now
\[ H^{-1}H^{-1}_{n_2} = \begin{pmatrix} \tilde{\sigma}^{-2} & 0 \\ 0 & \tilde{\sigma}^2 \end{pmatrix} \begin{pmatrix} \sqrt{1 + \tilde{\sigma}^2} \\ 1 \end{pmatrix} = \begin{pmatrix} \tilde{\sigma} \sqrt{1 + \tilde{\sigma}^2} \\ \sqrt{\tilde{\sigma}^2 + 1} \end{pmatrix} = \begin{pmatrix} \tilde{\sigma} \sqrt{1 + \tilde{\sigma}^2} \\ \sqrt{\tilde{\sigma}^2 + 1} \end{pmatrix}. \] (249)

Now we normalize the vector; so
\[ \sqrt{\frac{1}{\tilde{\sigma}^2 (1 + \tilde{\sigma}^2)}} + \sqrt{\frac{\tilde{\sigma}^4}{(1 + \tilde{\sigma}^2)}} = \sqrt{\frac{\tilde{\sigma}^6 + 1}{\tilde{\sigma}^2 (1 + \tilde{\sigma}^2)}} = \sqrt{\frac{\tilde{\sigma}^6 + 1}{\tilde{\sigma}^2}}. \]

And hence
\[ \frac{H^{-1}H^{-1}_{n_2}}{\left|H^{-1}H^{-1}_{n_2}\right|} = \frac{\tilde{\sigma} \sqrt{1 + \tilde{\sigma}^2}}{\sqrt{\tilde{\sigma}^6 + 1}} \frac{1}{H^{-1}H^{-1}_{n_2}} = \begin{pmatrix} \tilde{\sigma} \sqrt{1 + \tilde{\sigma}^2} \\ \sqrt{\tilde{\sigma}^6 + 1} \end{pmatrix} = \tilde{\phi}_2 \]

which establishes the claim.

From the fact that \( \tilde{\phi}_2 = \tilde{\phi}_1 \) and \( \tilde{\phi}_1 = n_2 \), using (248) we get
\[ H^{-1}H^{-1}_{n_1} = H^{-1}H^{-1}_{n_2} = H^{-1}H^{-1}_{n_2} = \tilde{\phi}_2 = \tilde{\phi}_1 \]

and this completes the calculation.
REFERENCES